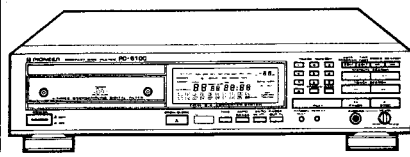


Service Manual



ORDER NO.
ARP1570

COMPACT DISC PLAYER

PD-6100

PD-6100-S

MODEL PD-6100 AND PD-6100-S HAVE THREE VERSIONS :

| TYPE | Applicable model | | Power requirement | Export destination |
|------|------------------|-----------|--|--|
| | PD-6100 | PD-6100-S | | |
| HEM | ○ | ○ | AC220V, 240V (switchable) * | European continent |
| HB | ○ | — | AC220V, 240V (switchable) * | United Kingdom |
| SD | ○ | — | AC110V, 120V-127V, 220V, 240V (switchable) | Kingdom of Saudi Arabia and General market |

* Change the primary wiring of the power transformer.

- This manual is applicable to the HEM, HB and SD types.
- For the HB, SD and PD-6100-S/HEM types, refer to page 84.
- The PD-6100-S is the same as the PD-6100 except for the color.
- Ce manuel pour le service comprend les explications en français de réglage.
- Este manual de servicio trata del método ajuste escrito en español.

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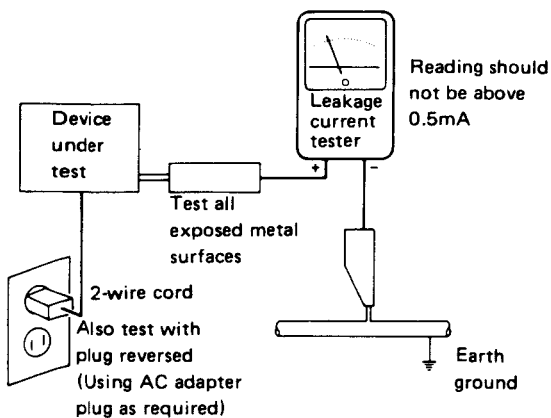
1. SAFETY INFORMATION

1. SAFETY PRECAUTIONS

The following check should be performed for the continued protection of the customer and service technician.

LEAKAGE CURRENT CHECK

Measure leakage current to a known earth ground (water pipe, conduit, etc.) by connecting a leakage current tester such as Simpson Model 229-2 or equivalent between the earth ground and all exposed metal parts of the appliance (input/output terminals, screwheads, metal overlays, control shaft, etc.). Plug the AC line cord of the appliance directly into a 120V AC 60Hz outlet and turn the AC power switch on. Any current measured must not exceed 0.5mA.



AC Leakage Test

ANY MEASUREMENTS NOT WITHIN THE LIMITS OUTLINED ABOVE ARE INDICATIVE OF A POTENTIAL SHOCK HAZARD AND MUST BE CORRECTED BEFORE RETURNING THE APPLIANCE TO THE CUSTOMER.

2. PRODUCT SAFETY NOTICE

Many electrical and mechanical parts in the appliance have special safety related characteristics. These are often not evident from visual inspection nor the protection afforded by them necessarily can be obtained by using replacement components rated for voltage, wattage, etc. Replacement parts which have these special safety characteristics are identified in this Service Manual.

Electrical components having such features are identified by marking with a ⚠ on the schematics and on the parts list in this Service Manual.

The use of a substitute replacement component which does not have the same safety characteristics as the PIONEER recommended replacement one, shown in the parts list in this Service Manual, may create shock, fire, or other hazards.

Product Safety is continuously under review and new instructions are issued from time to time. For the latest information, always consult the current PIONEER Service Manual. A subscription to, or additional copies of, PIONEER Service Manual may be obtained at a nominal charge from PIONEER.

(FOR EUROPEAN MODEL ONLY)

VAROITUS!

LAITE SISÄLTÄÄ LASERDIODIN, JOKA LÄHETTÄÄ NÄKYMÄTÖNTÄ, SILMILLE VAARALLISTA INFRAPUNASATEILYÄ LAITTEEN SISÄLLÄ ON LASERDIODIN LAHEISYYDESSÄ KUVA 1. MUKAINEN VAROITUSMERKKI.



LASER
Kuva 1
Lasersäteilyn
varoituserkki

WARNING!

DEVICE INCLUDES LASER DIODE WHICH EMITS INVISIBLE INFRARED RADIATION WHICH IS DANGEROUS TO EYES. THERE IS A WARNING SIGN ACCORDING TO PICTURE 1 INSIDE THE DEVICE CLOSE TO THE LASER DIODE.



LASER
Picture 1
Warning sign for
laser radiation

ADVERSEL:

USYNLIG LASERSTRÅLING VED ÅBNING NÅR SIKKERHEDSAFBRYDERE ER UDE AF FUNKTION UNDGA UDSÆTTELSE FOR STRÅLING.

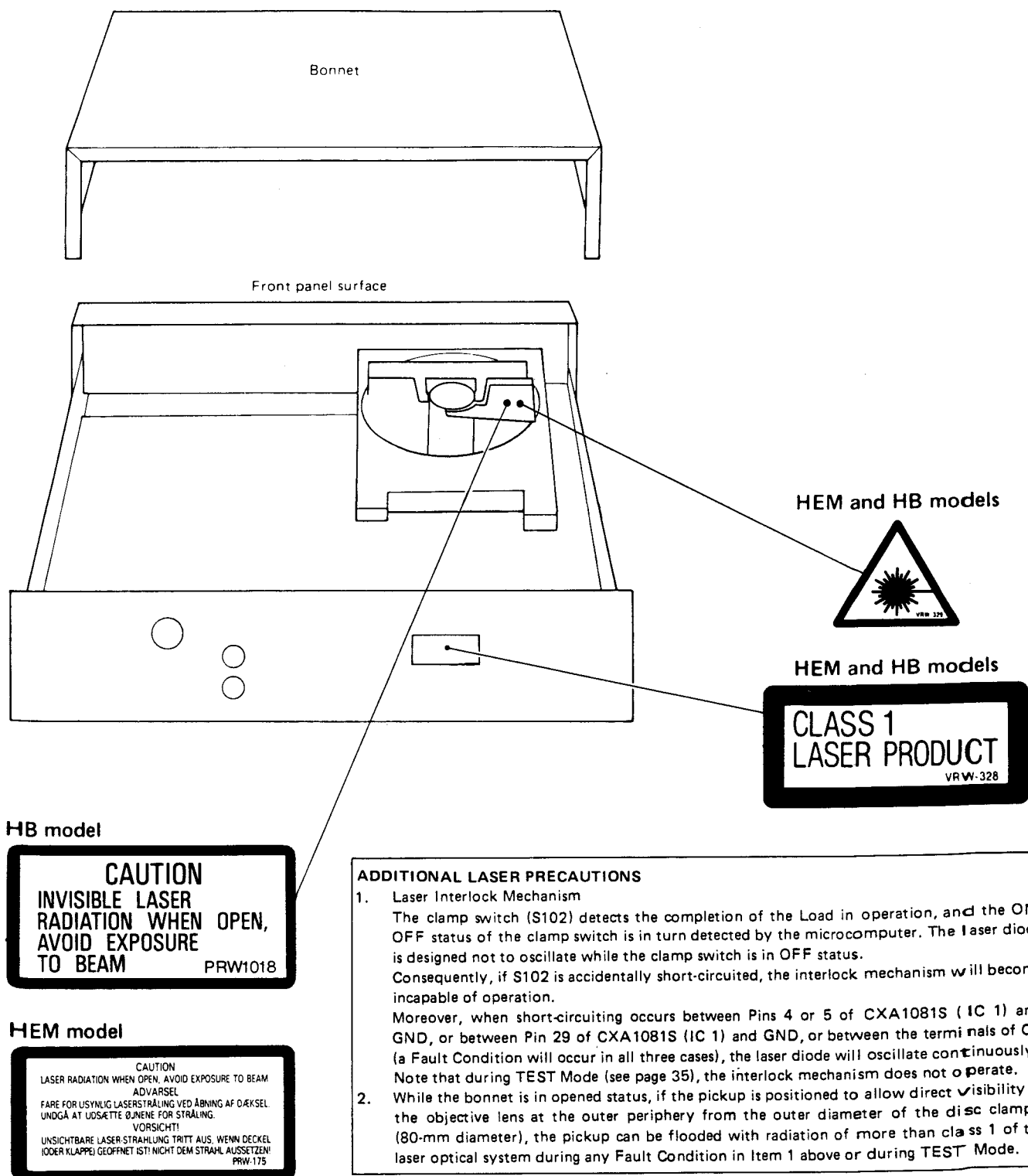
VIKTIGT

APARATEN INNEHÅLLER LASER AV HÖGRE KLASS ÄN 1. INGREPP I APPARATEN BÖR GÖRAS AV SPECIELLT UTBILDAD PERSONAL.

IMPORTANT

PIONEER COMPACT DISC PLAYER APPARATUS CONTAINS LASER OF HIGHER CLASS THAN 1. SERVICING OPERATION OF THE APPARATUS SHOULD BE DONE BY A SPECIALLY INSTRUCTED PERSON.

LABEL CHECK



1. General

Power requirements

Weight 4.0kg (8lb, 13oz)
External dimensions 420(W) x 315(D) x 98(H)mm
16-1/2(W) x 12-3/8(D) x 3-7/8(H) in.

Number of channels 2 channels (stereo)
Digital output Coaxial output: 0.5Vp-p (75Ω)

Audio line output terminal
Coaxial digital output terminal
Headphone jack (with volume control)

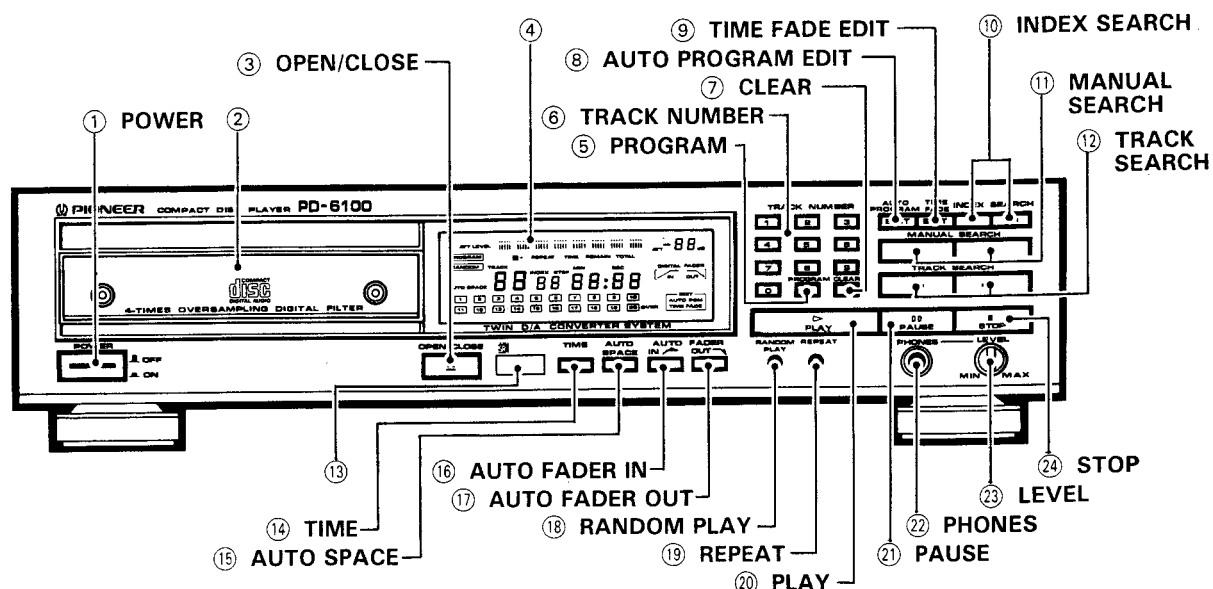
- Play
- Pause
- Manual search
- Track search
- Index search
- Direct track search
- One track repeat
- All track repeat
- Programmed repeat
- Programmed playback
- Pause program
- Add-on program
- Auto program editing
- Time fade editing
- Random play
- Random play repeat
- Auto space
- Digital level control (remote control)
- Timer start
- One touch fade-in and fade-out

- Remote control unit 1
- Size AAA/R03 dry cell batteries 2
- Output cable 1
- Operating instructions 1

The specifications and design of this product are subject to change without notice, due to improvements.

3. PANEL FACILITIES

FRONT PANEL



① POWER switch

Press to turn power to the unit ON and OFF.
If there is a disc in the unit when power is turned ON, playback will begin automatically. (Timer start function)

② Disc Tray

This is where the disc is set. When power is switched ON and the OPEN/CLOSE key is pressed, the tray is ejected forward. To insert the tray, press the OPEN/CLOSE key, or lightly push the tray in with your finger. With the disc tray open, pressing the PLAY key will close the disc tray and start playback.

③ OPEN/CLOSE key (▲)

Press when you wish to eject or load a disc. Each time the key is pressed, the tray is alternately pushed out or pulled in.

④ Indicators

- ATT LEVEL : The volume level of fade-in, fade-out, and output level is displayed.
- PROGRAM : Lights after programming (after program has been memorized).
- REPEAT : Lights during repeat playback of one track.
- REPEAT : Lights during repeat playback.
- RANDOM : Lights during random playback.
- AUTO SPACE : Lights during auto space playback.

TRACK

[1] - [20], OVER

(Music calendar) : Displays the current track number (during normal playback and programmed playback) or the track being programmed during programming operation. The lower figures light up in accordance with the number of tracks recorded on the disc, and the numbers of the tracks which have been played are deleted in order. (During programmed playback only the programmed tracks light.) For 21 or over, OVER will light.

- INDEX : Displays the index * number of the music section of a track or the track division.
- STEP : Displays the program steps.
- MIN (minute) : Displays the minutes of the elapsed time, total playback time, and remaining time.
- SEC (second) : Displays the seconds of the elapsed time, total playback time, and remaining time.
- TIME/REMAIN/TOTAL

- TIME : Changes each time the TIME key is pressed.
- TIME : Displays the track number of the track being played (TRACK) and the elapsed time (minutes and seconds).
- REMAIN : Displays the remaining time on the track being played.
- When the TIME key is pressed again, the remaining time on the disc will be displayed.
- TOTAL : Displays the total number of tracks on the disc (TRACK) and the overall playback time (minutes and seconds).
- During playback, the display goes on for about 5 seconds before changing to the TIME display.

Programmed playback operation displays the remaining time of the programmed tracks (REMAIN), and the total playback time (TOTAL).

IN

OUT

ATT

: Lights during fade-in.

: Lights during fade-out.

: The volume level of fade-in, fade-out, and output level is displayed by decreasing level (-dB).

AUTO PGM EDIT : Displays when Auto Program Editing is set or used.

TIME FADE EDIT : Displays when Time Fade Editing is set or used.

* The INDEX is a signal which is recorded within a track to indicate division of the track into separate turns and items of music.

⑤ PROGRAM key (program memory)

Use to program a sequence of tracks.

- Press this key after selecting a desired track with the track number keys. Tracks will be added to the program in the order in which they are selected.

⑥ TRACK NUMBER keys (1 to 0)

- Use to specify track numbers (track 1—track 99) for selection of tracks or program entry.
- Use to specify time (in minutes), during auto program editing and time fade editing.

⑦ CLEAR key

Press this key to clear the program.

⑧ AUTO PROGRAM EDIT key

Press to program a tune which may be played back within a specified time.

⑨ TIME FADE EDIT key

Press this key to end playback at a desired time with fade-out.

⑩ INDEX SEARCH keys

Searches, during playback or pause, for the music section of a track or the track index. When pressed, the unit will return to the previous index or advance to the next index.

[▶▶] : Advances to the next index number.

[◀◀] : Returns to the index number of the currently-playing music section or track.

⑪ MANUAL SEARCH keys

When the player is in playback or pause modes, these keys are pressed to perform fast forward or reverse operations to allow manual searching. These operations are only carried out during the time either key is pressed.

[▶▶] : For fast forward operation. If the end of the disc is reached during fast forward operation, "End" will be displayed and the player will enter the pause mode. [During programmed playback, the player will enter the pause mode right before it reaches the next track (program step).]

[◀◀] : For fast reverse operation. If the beginning of the disc is reached during fast reverse operation, the player will enter the playback mode. [During programmed playback, the player will enter the playback mode right before it reaches the previous track (program step).]

⑫ TRACK SEARCH keys

During normal playback, programmed playback or pause modes, these keys are pressed to search for the desired track. Pressing either key causes the player to advance to the next track or to return to the previous track. Even in stop mode, these keys can be used to select the desired track. Press the PLAY key to playback the desired track.

[▶▶] : When pressed once, playback advances to the beginning of the next track on the disc; when pressed continuously, playback advances to the beginning of succeeding tracks on the disc. (During programmed playback, it advances to the beginning of the next programmed track.)

[◀◀] : When pressed once, playback returns to the beginning of the currently playing track; when pressed continuously, playback shifts to the beginning of previous tracks on the disc. (During programmed playback it returns to the beginning of the previous programmed track.)

⑬ Remote sensor**⑭ TIME key**

This key selects the display mode of the indicator panel. Each time the key is pressed, the indication changes from TIME, REMAIN, to TOTAL in that order. (For details concerning the display contents, refer to the explanation about the indicators.)

If pressed after pressing the track number key, the playback time of the selected track only is displayed.

⑮ AUTO SPACE key

During playback, there will be a pause of about three seconds before the next track is played.

⑯ AUTO FADER IN key

Press this key to start playback with fade-in sound. (Possible only in pause mode during playback.)

⑰ AUTO FADER OUT key

Press this key for fade-out sound. (After fade-out is completed, the unit will enter pause mode.)

⑱ RANDOM PLAY key

Press to begin random playback.

⑲ REPEAT key

Press this key for repeat playback. Pressing the key once, twice, or three times will change the repeat mode from single track repeat, all tracks repeat, and repeat playback cancellation. Single track repeat:

The currently-playing track will repeat. The key can be used during normal playback, program playback, random playback.

All tracks repeat:

All tracks on the disc will be repeated.

- If pressed during normal playback mode, all tracks on the disc will be repeatedly played back.
- If pressed during programmed playback, the programmed tracks will be repeatedly played back in the programmed order.
- In the case of random play mode, after all the tracks have been played, random play will start again.

⑳ PLAY key/indicator (▶)

Press to begin playback, and to cancel the pause mode.

㉑ PAUSE key/indicator (⏸)

Press to temporarily interrupt playback. When pressed again, the pause mode is cancelled and playback resumes.

㉒ PHONES (headphones) jack

When you wish to use headphones, insert the plug for the headphones into the headphone jack.

②③ PHONES LEVEL control knob

Use to adjust the level of sound when using headphones. Turning the knob to the right increases the sound level.

②④ STOP key (■)

Press to stop playback. When pressed, the player goes into stop mode and all operations stop.

NOTE:

The output level of the digital out output (digital data) cannot be controlled. (It will not fade in or fade out.)

Reference:

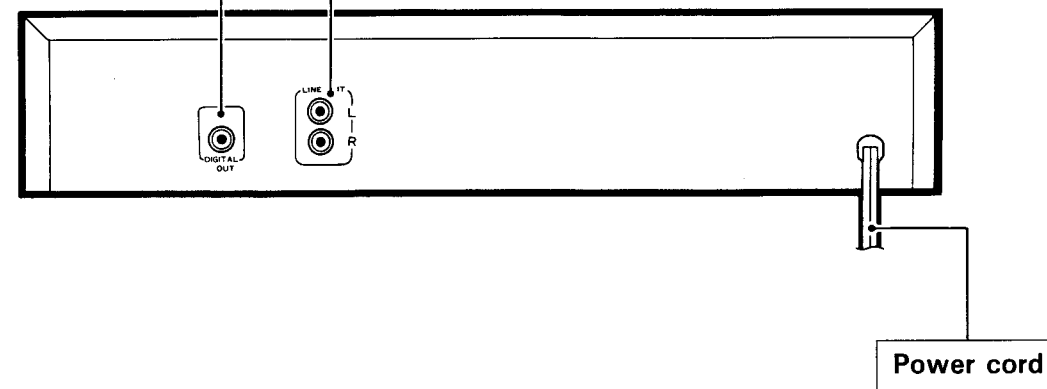
Fade-in : With no sound, the sound fades in gradually getting louder.
 Fade-out : The sound gradually gets softer until there is no sound.

REAR PANEL

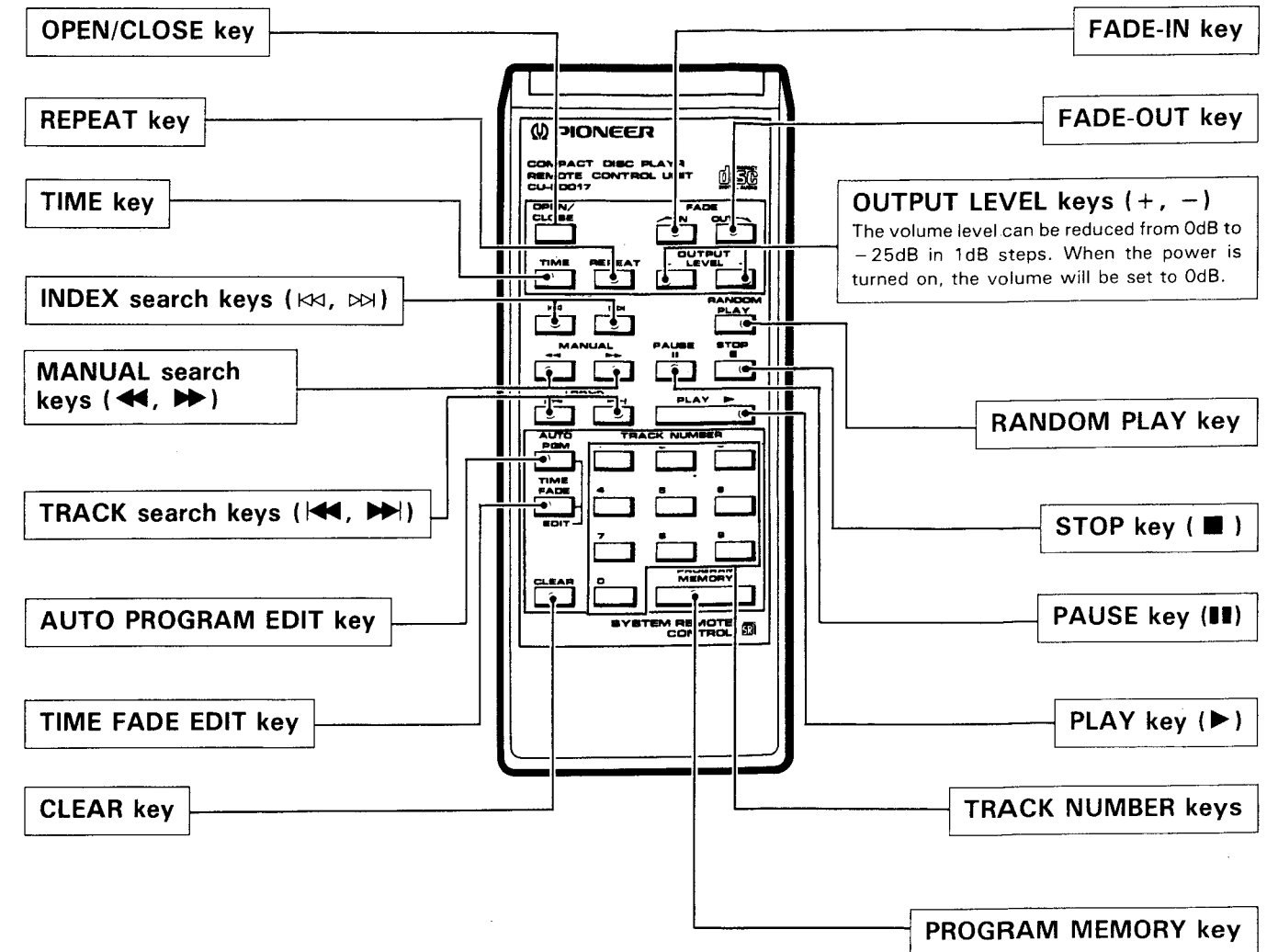
Coaxial digital output terminal (DIGITAL OUT)

This terminal allows output of disc audio data and subcode (signals which can be recorded together with the audio signal) as digital signals.

LINE OUT terminal



REMOTE CONTROL UNIT



Digital level controller

By using the OUTPUT LEVEL keys [+ , -], the volume level can be controlled in 1dB steps from 0dB to -25dB of the digital circuit processing.

- To increase the volume level: Press the [+] LEVEL key.
 (If the volume level is already set at 0dB, there will be no change.)
- To decrease the volume level: Press the [-] LEVEL key.
 (When the key is held down, the volume level will stop at -25dB).

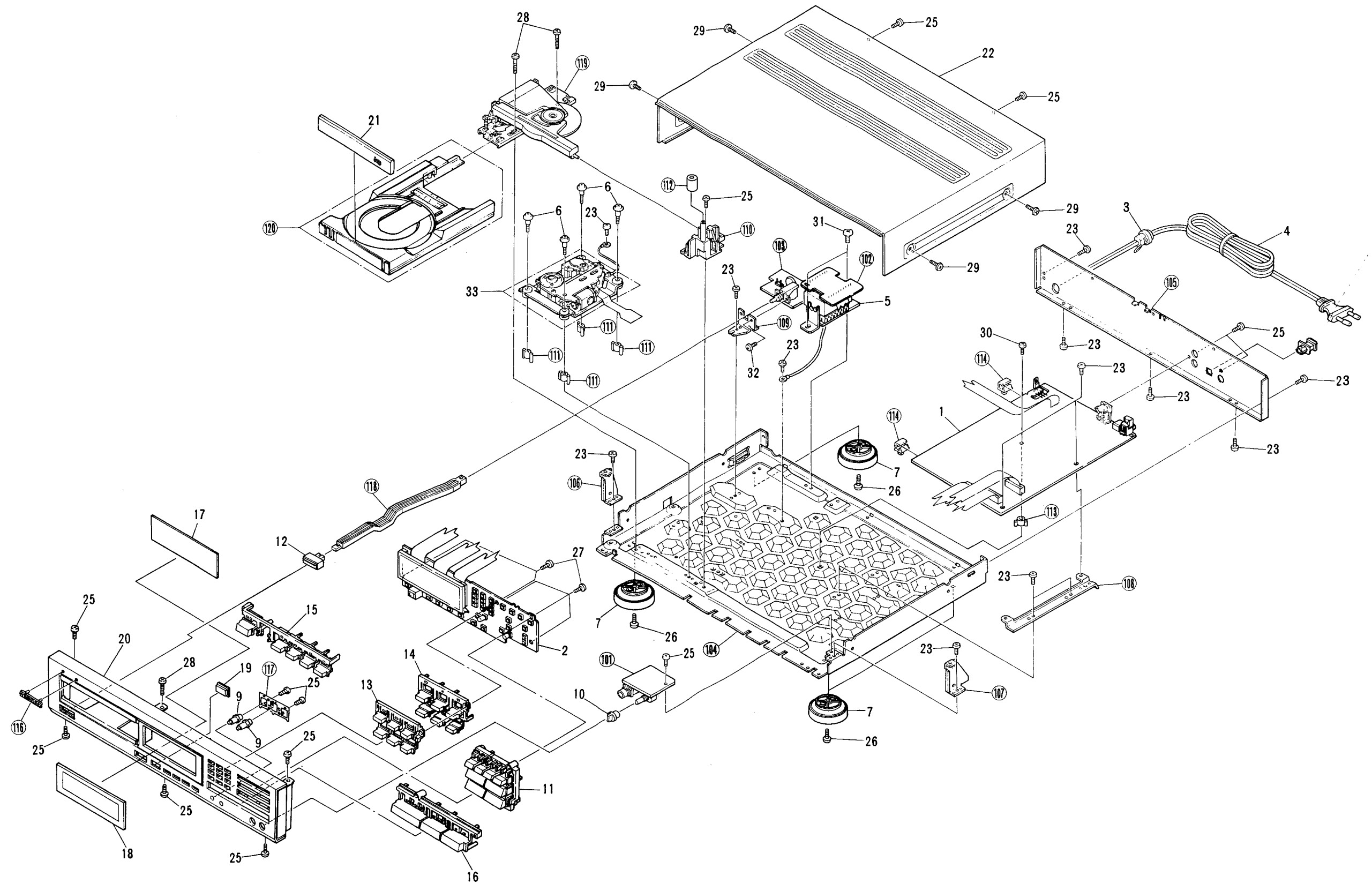
When the volume level is adjusted, it will be displayed on the ATT LEVEL indicator and the ATT indicator.

NOTE:

The headphones can also be adjusted simultaneously. However, the volume level of the digital output from the DIGITAL OUT terminal cannot be adjusted.

4. EXPLODED VIEWS AND PARTS LIST

4.1 EXTERIOR



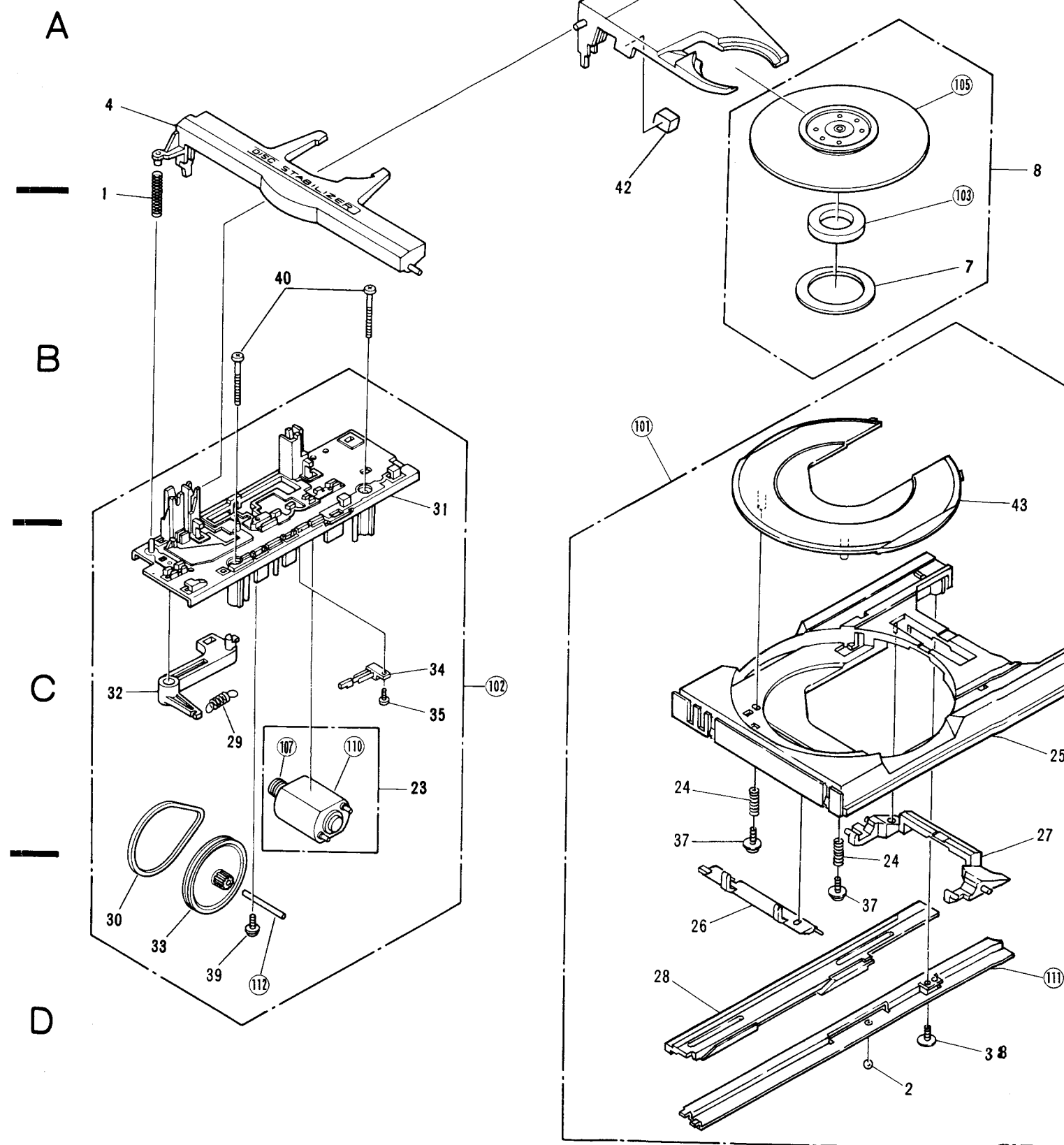
4.2 MECHANISM SECTION

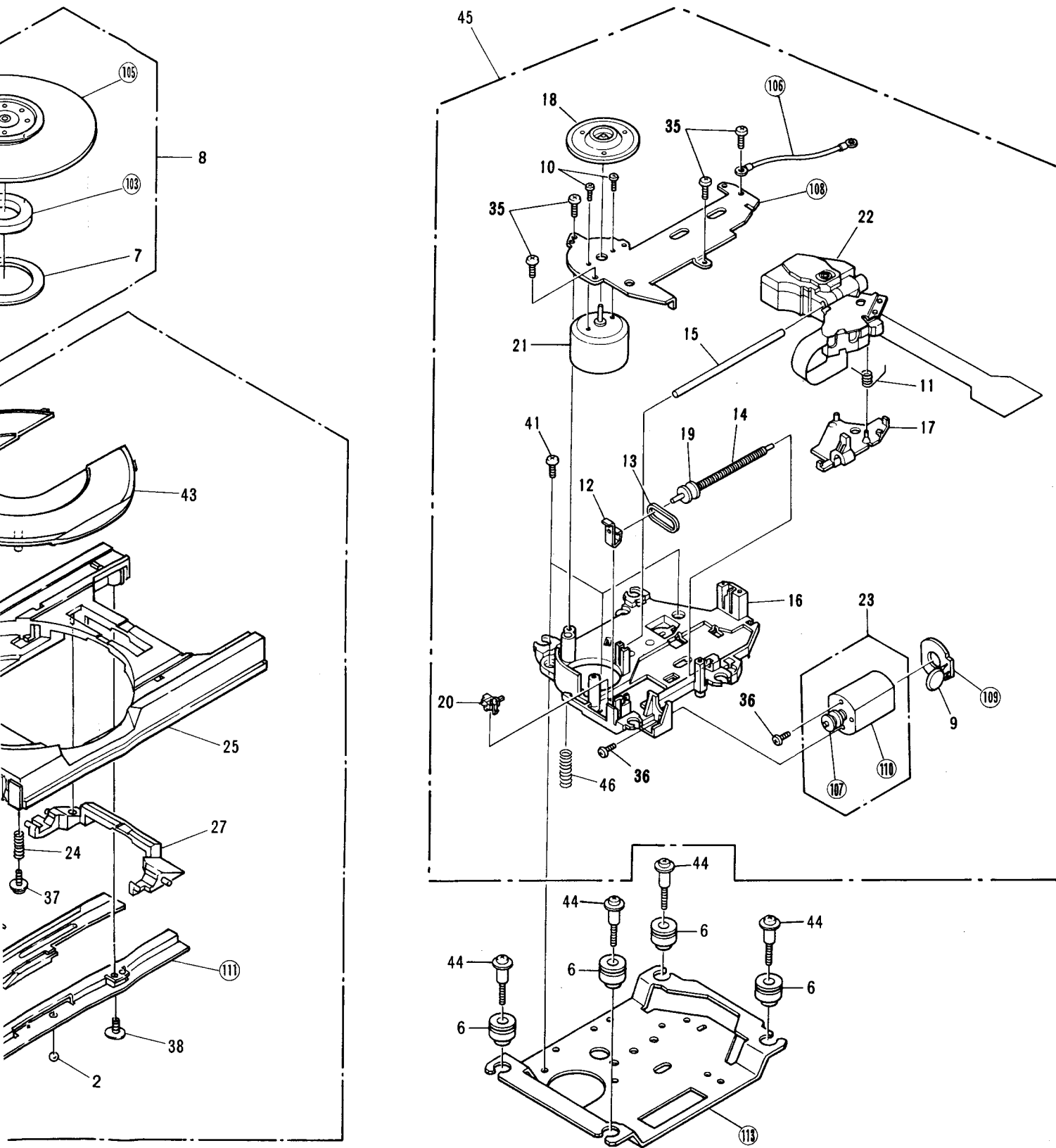
Parts List of Exterior

NOTES :

- Parts without part number cannot be supplied.
- The Δ mark found on some component parts indicates the importance of the safety factor of the part. Therefore, when replacing, be sure to use parts of identical designation.
- For your parts Stock Control, the fast moving items are indicated with the marks $\star\star$ and \star .
 $\star\star$ GENERALLY MOVES FASTER THAN \star .
 This classification shall be adjusted by each distributor because it depends on model number, temperature, humidity, etc.
- Parts marked by "⊙" are not always kept in stock. Their delivery time may be longer than usual or they may be unavailable.

| Mark | No. | Part No. | Description | Mark | No. | Part No. | Description |
|------------------|-----|--------------|----------------------------|------|-----|----------|-----------------------|
| Δ ⊙ | 1 | PWZ1426 | Main board assembly | | 111 | | Mechanism support |
| Δ ⊙ | 2 | PWX1037 | Control board assembly | | 112 | | Guide spacer |
| Δ | 3 | CM-22B | Strain relief | | 113 | | P.C. Board spacer |
| Δ | 4 | PDG1003 | AC power cord | | 114 | | P.C. Board holder |
| Δ \star | 5 | PTT1063 | Power transformer | | 115 | | |
| | 6 | PBA1001 | Screw | | 116 | | Friction name plate |
| | 7 | PNW1376 | Insulator | | 117 | | Spring |
| | 8 | | | | 118 | | SW joint |
| | 9 | PAA1004 | Button | | 119 | | Loading base assembly |
| | 10 | PAC1208 | Knob (PHONES LEVEL) | | 120 | | Tray assembly |
| | 11 | PAC1251 | Button (TRACK) | | | | |
| | 12 | PAC1252 | Button B (POWER) | | | | |
| | 13 | PAC1253 | Button C (SELECT) | | | | |
| | 14 | PAC1254 | Button D (SELECT) | | | | |
| | 15 | PAC1256 | Button C (OPEN/CLOSE) | | | | |
| | 16 | PAD1035 | Play button B assembly | | | | |
| | 17 | PAM1232 | FL filter B | | | | |
| | 18 | PAM1177 | Display window C | | | | |
| | 19 | PNW1075 | Receiving window | | | | |
| | 20 | PNW1357 | Control panel C | | | | |
| | 21 | PNW1358 | Name plate B | | | | |
| | 22 | PYY1062 | Bonnet | | | | |
| | 23 | BBZ30P060FMC | Screw | | | | |
| | 24 | | | | | | |
| | 25 | BBZ30P080FZK | Screw | | | | |
| | 26 | BBZ30P120FMC | Screw | | | | |
| | 27 | BBZ30P160FMC | Screw | | | | |
| | 28 | BBZ30P230FMC | Screw | | | | |
| | 29 | FBT40P080FZK | Screw | | | | |
| | 30 | IBZ30P150FCU | Screw | | | | |
| | 31 | IBZ40P080FCC | Screw | | | | |
| | 32 | PMZ30P060FCU | Screw | | | | |
| | 33 | PYY1063 | Servo mechanism assembly | | | | |
| | 101 | | Headphone board assembly | | | | |
| | 102 | | Transformer board assembly | | | | |
| | 103 | | SW board assembly | | | | |
| | 104 | | Under base | | | | |
| | 105 | | Rear base | | | | |
| | 106 | | Angle | | | | |
| | 107 | | Panel angle | | | | |
| | 108 | | P.C. Board angle | | | | |
| | 109 | | SW angle | | | | |
| | 110 | | Slide guide | | | | |





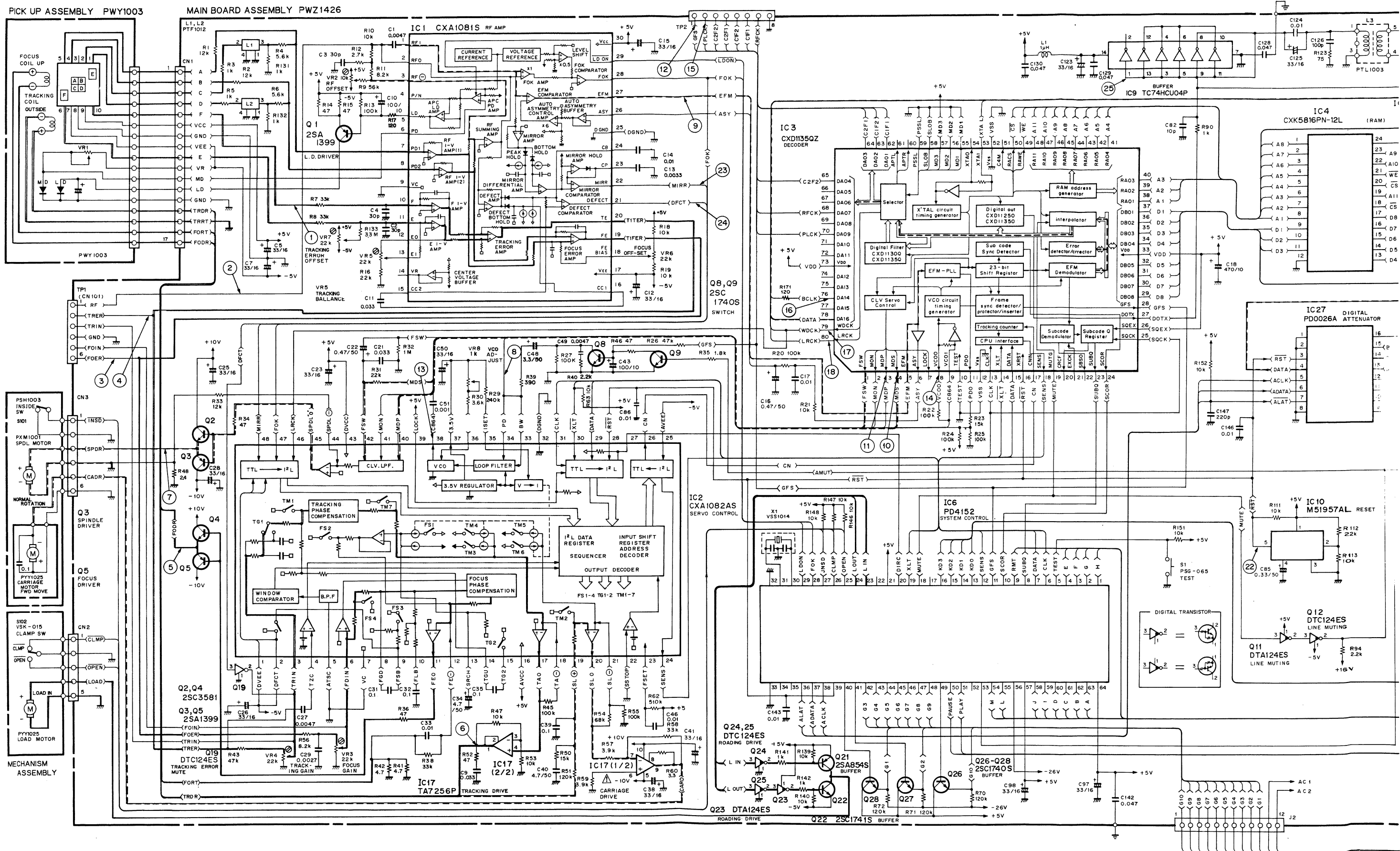
Parts List of Mechanism Section

| Mark | No. | Part No. | Description | Mark | No. | Part No. | Description |
|------|-----|-------------|------------------------------------|------|-----|--------------|-------------------------------|
| | 1 | PBH1013 | Spring | | 31 | PNW1069 | Loading base |
| | 2 | PBP-001 | Steel ball $\phi 4$ | | 32 | PNW1083 | Clamp lever |
| | 3 | PNW1084 | Clamp holder | | 33 | PNW1171 | Gear pulley |
| | 4 | PNW1085 | Clamp retainer | ★★ | 34 | VSK-015 | Leaf switch (S102.OPEN/CLAMP) |
| | 5 | PBH1009 | Spring | | 35 | BPZ20P080FZK | Screw |
| | 6 | PBE1031 | Floating rubber | | 36 | PMZ20P030FMC | Screw |
| | 7 | PNM1010 | Disc cushion | | 37 | PBA1025 | Screw |
| | 8 | PYY1028 | Clamper assembly | | 38 | PPZ30P080FMC | Screw |
| | 9 | CGDYX104M25 | Semiconductive ceramic capacitor | | 39 | IPZ30P060FMC | Screw |
| | 10 | PBA-209 | Screw M2 x 3 | | 40 | BBZ30P230FMC | Screw |
| | 11 | PBH1008 | Drive spring | | 41 | BBZ30P080FCC | Screw |
| | 12 | PBK1010 | Plate spring | | 42 | PEB1095 | Stopper rubber |
| ★★ | 13 | PEB1072 | Belt (CARRIAGE) | | 43 | PNW1329 | Disc plate |
| | 14 | PLA1003 | Drive worm | | 44 | PBA1001 | Screw |
| | 15 | PLA1004 | Guide bar | | 45 | PYY1063 | Servo mechanism assembly |
| | 16 | PNW1062 | Mechanism chassis | | 46 | PBH1009 | Earth spring |
| | 17 | PNW1063 | Carriage plate | | 101 | | Tray assembly |
| | 18 | PNW1064 | Disc table | | 102 | | Loading base assembly |
| | 19 | PNW1066 | Pulley | | 103 | | Magnet |
| ★★ | 20 | PSH1003 | Slide switch (S101. INSIDE) | | 104 | | Ballast base |
| ★★ | 21 | PXM1001 | Spindle motor | | 105 | | Clamper |
| ★★ | 22 | PWY1003 | Pick up assembly | | 106 | | Earth lead wire unit |
| ★★ | 23 | PYY1025 | Motor assembly (CARRIAGE, LOADING) | | 107 | | Motor pulley |
| | 24 | PBH1045 | Plate Spring | | 108 | | Base plate |
| | 25 | PNW1390 | Tray | | 109 | | Carriage M board |
| | 26 | PNW1330 | Plate lever (F) | | 110 | | Motor (LOADING, CARRIAGE) |
| | 27 | PNW1331 | Plate lever (R) | | 111 | | Slide base |
| | 28 | PNW1332 | Rack | | 112 | | Gear shaft |
| | 29 | PBH1012 | Clamp spring | | 113 | | Ballast base |
| ★★ | 30 | PEB1013 | Belt (LOADING) | | | | |

5. SCHEMATIC DIAGRAM

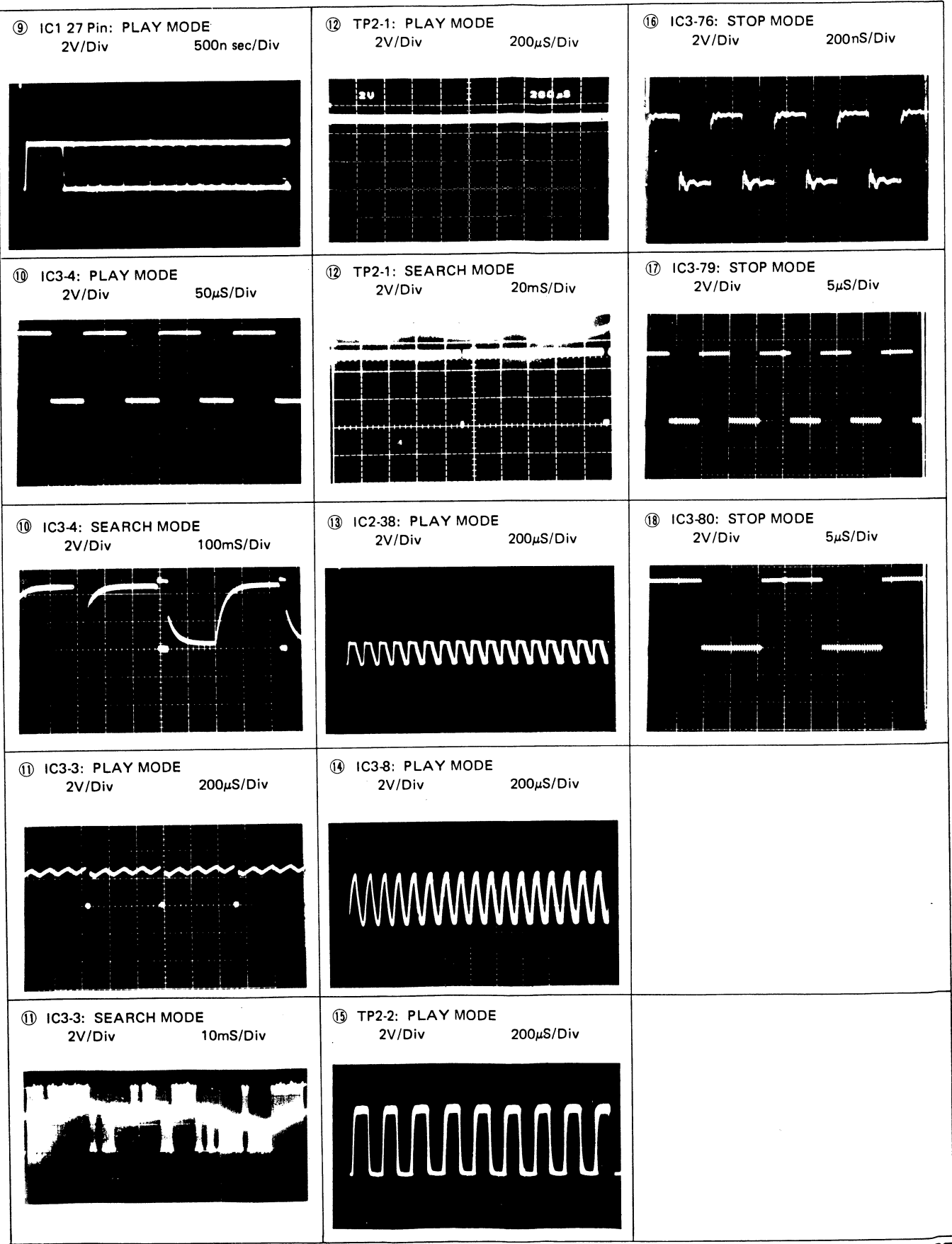
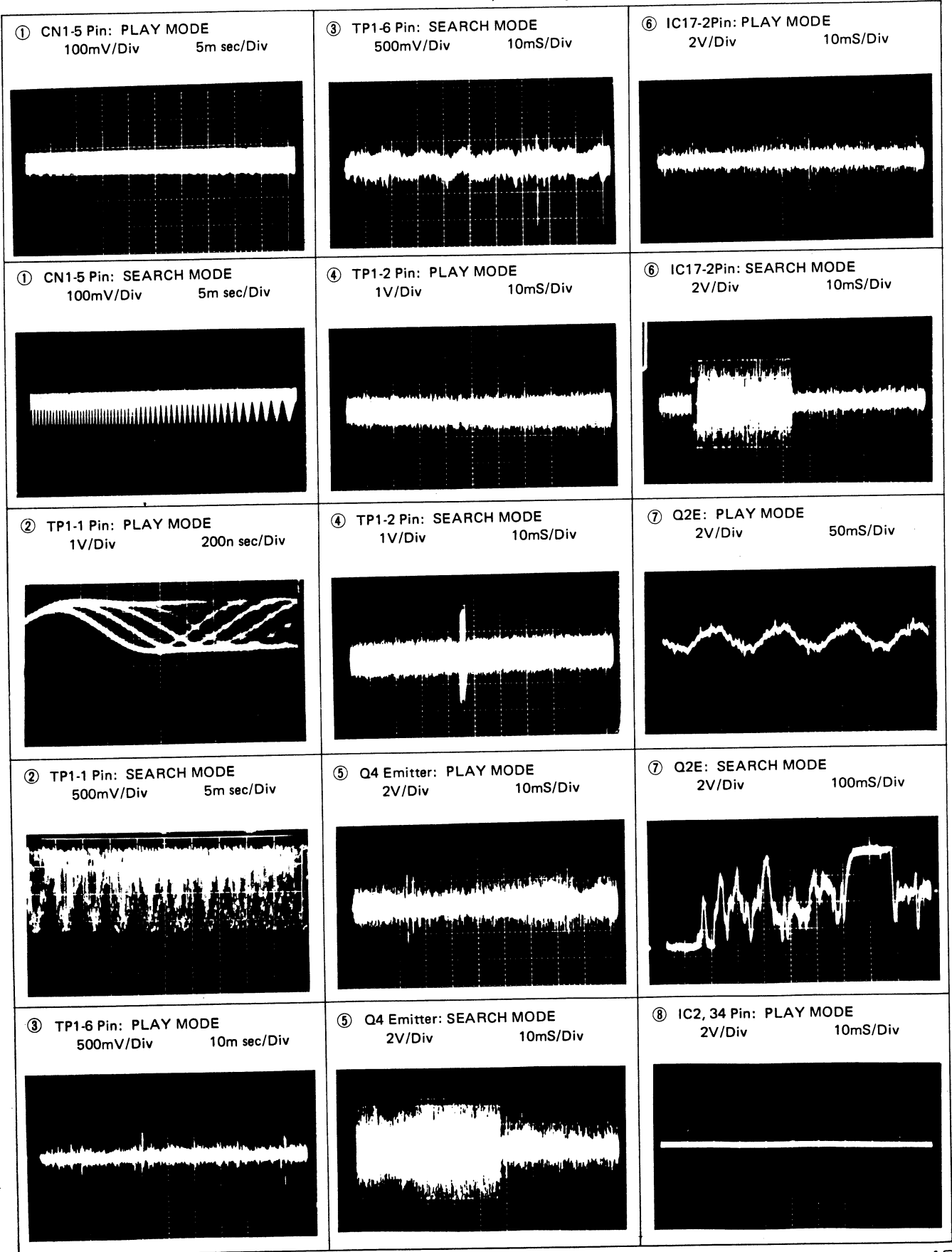
PICK UP ASSEMBLY PWY1003

MAIN BOARD ASSEMBLY PWZ1426

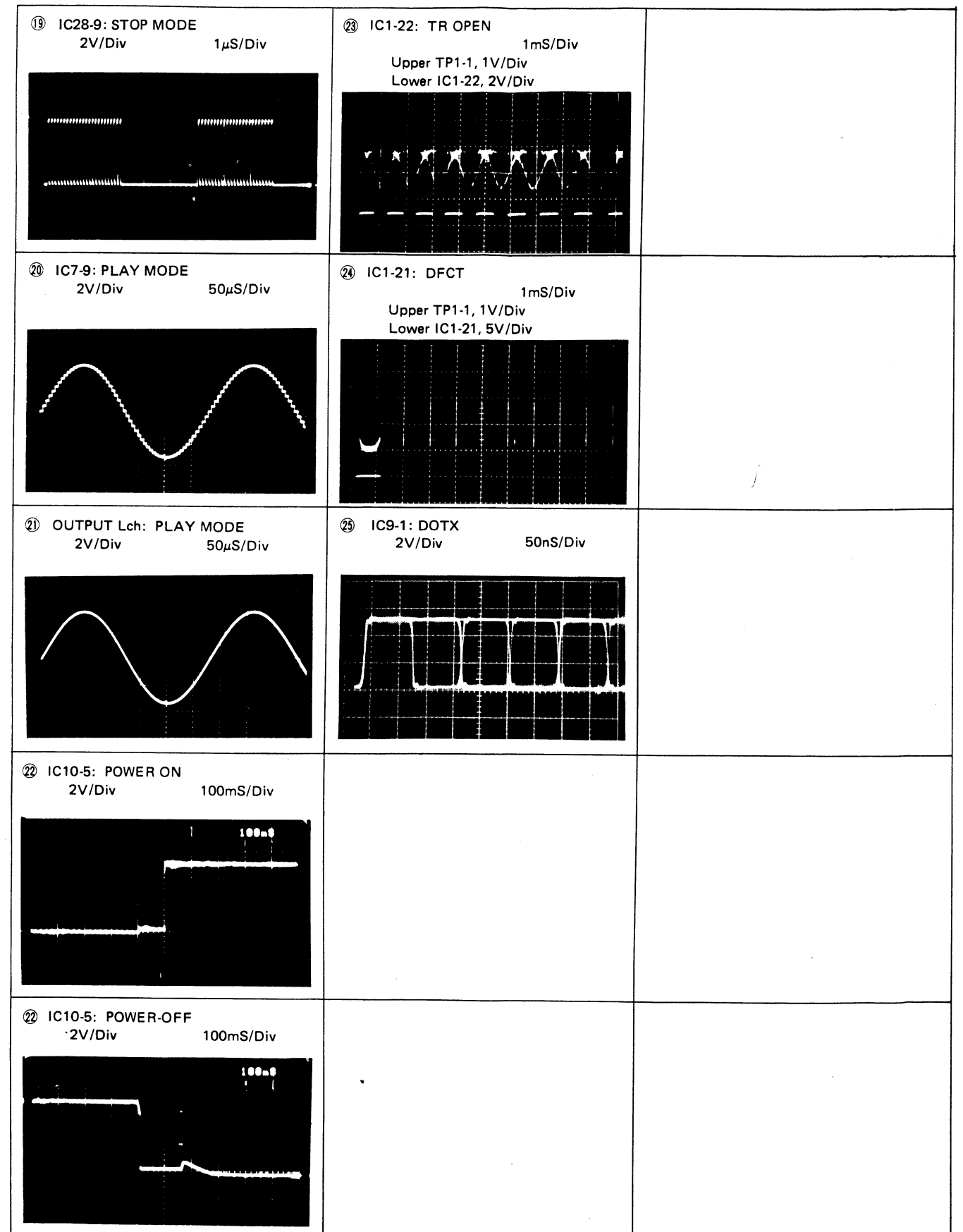
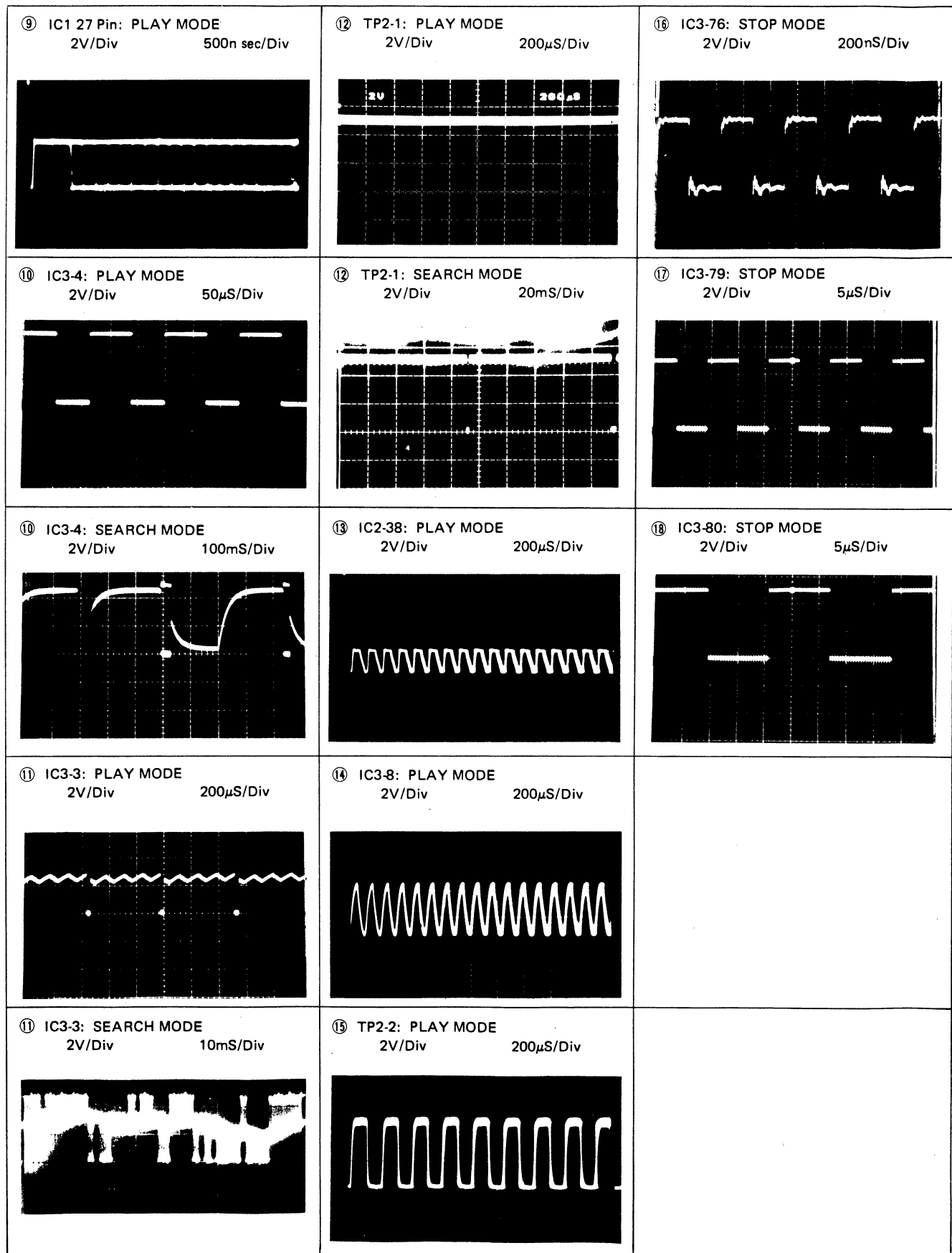
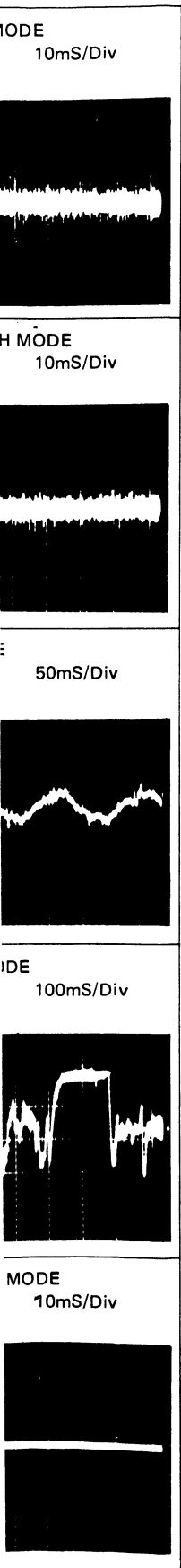


WAVE FORMS

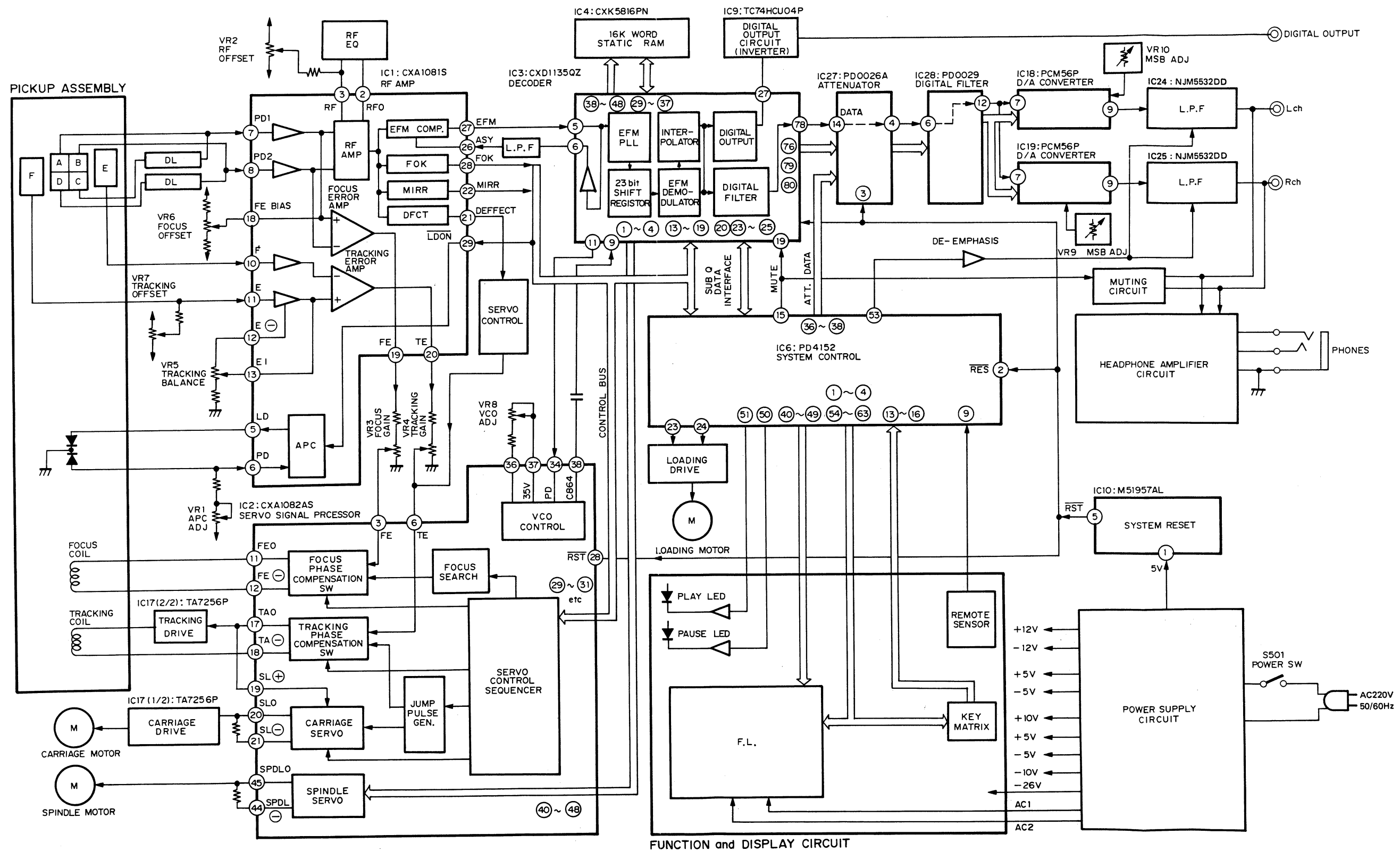
NOTE: The encircled numbers denote measuring points in the circuit and pattern diagrams.



nts in the circuit and



6. BLOCK DIAGRAM



FUNCTION and DISPLAY CIRCUIT

External

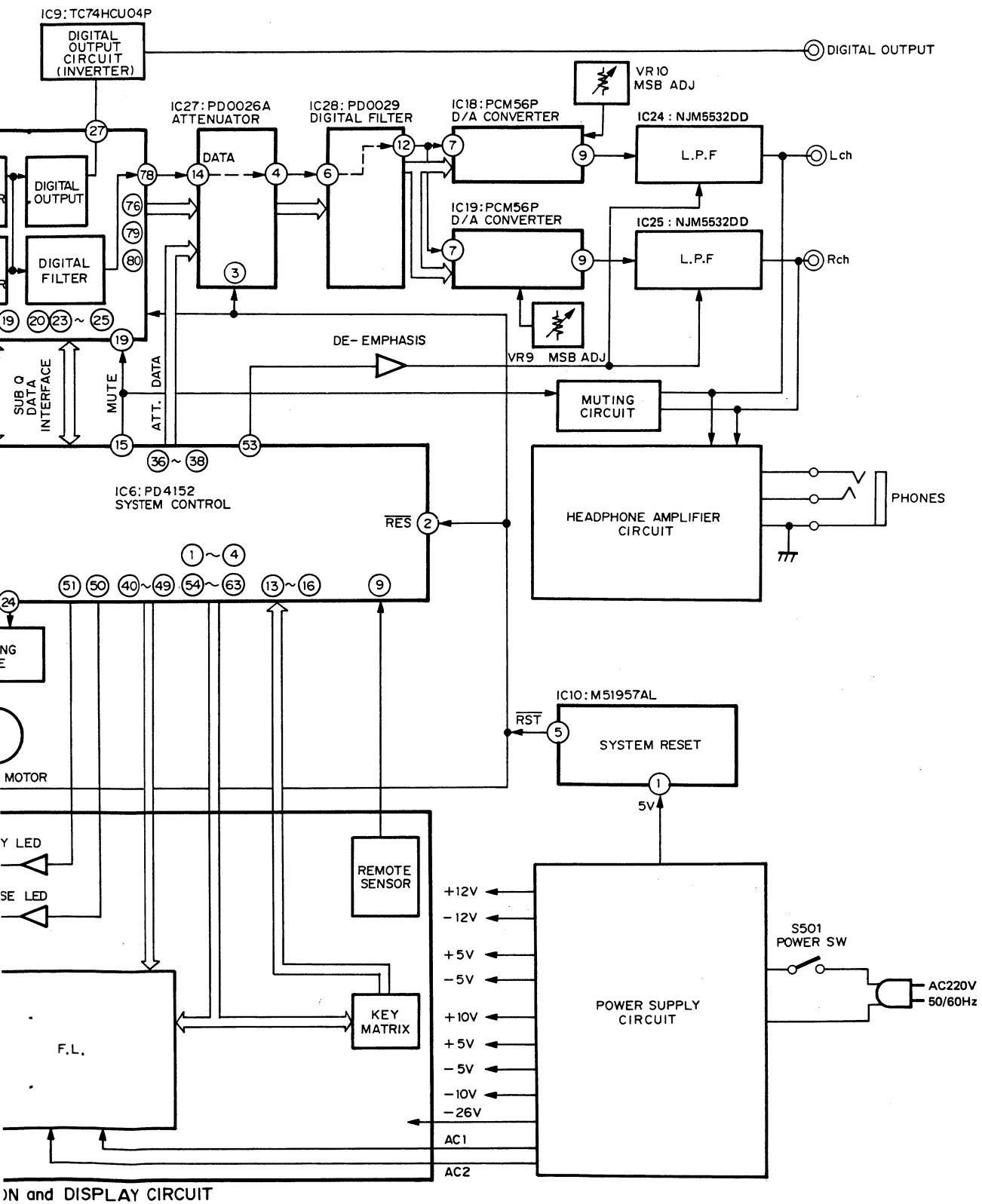
CXA1081S

CXD1135QZ

CXK5816PN

ICP-N10

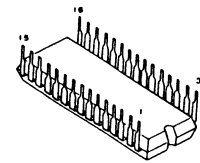
TA7256P



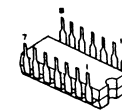
ON and DISPLAY CIRCUIT

External Appearance of Transistors and ICs

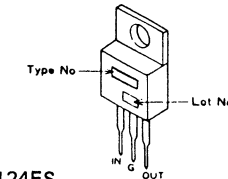
CXA1081S



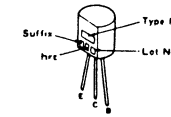
TC74HCU04P



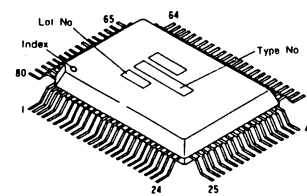
NJM7805FA



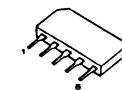
2SD1302



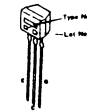
CXD1135QZ



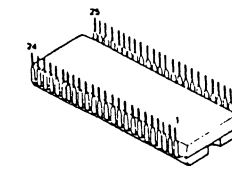
M51957AL



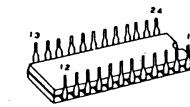
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DTC124ES



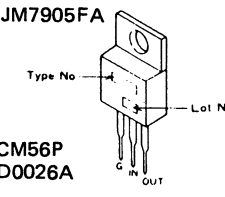
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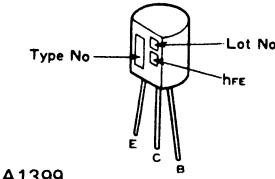
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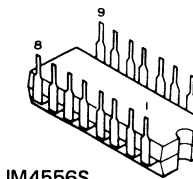
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NJM79M05FA
NJM7905FA



2SA1015



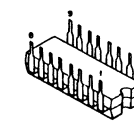
PD0029



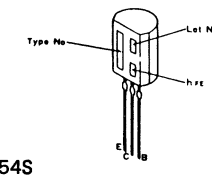
ICP-N10



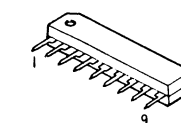
PCM56P
PD0026A



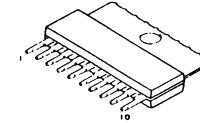
2SA1399
2SC3581



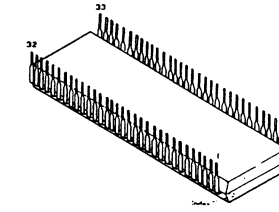
NJM4556S



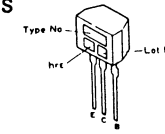
TA7256P



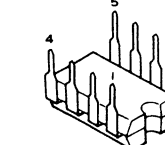
PD4152



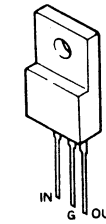
2SA854S
2SA933S
2SC1740S
2SC1741S



NJM5532DD



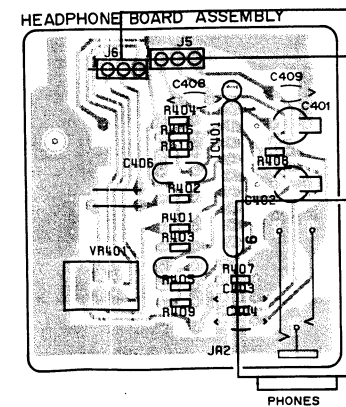
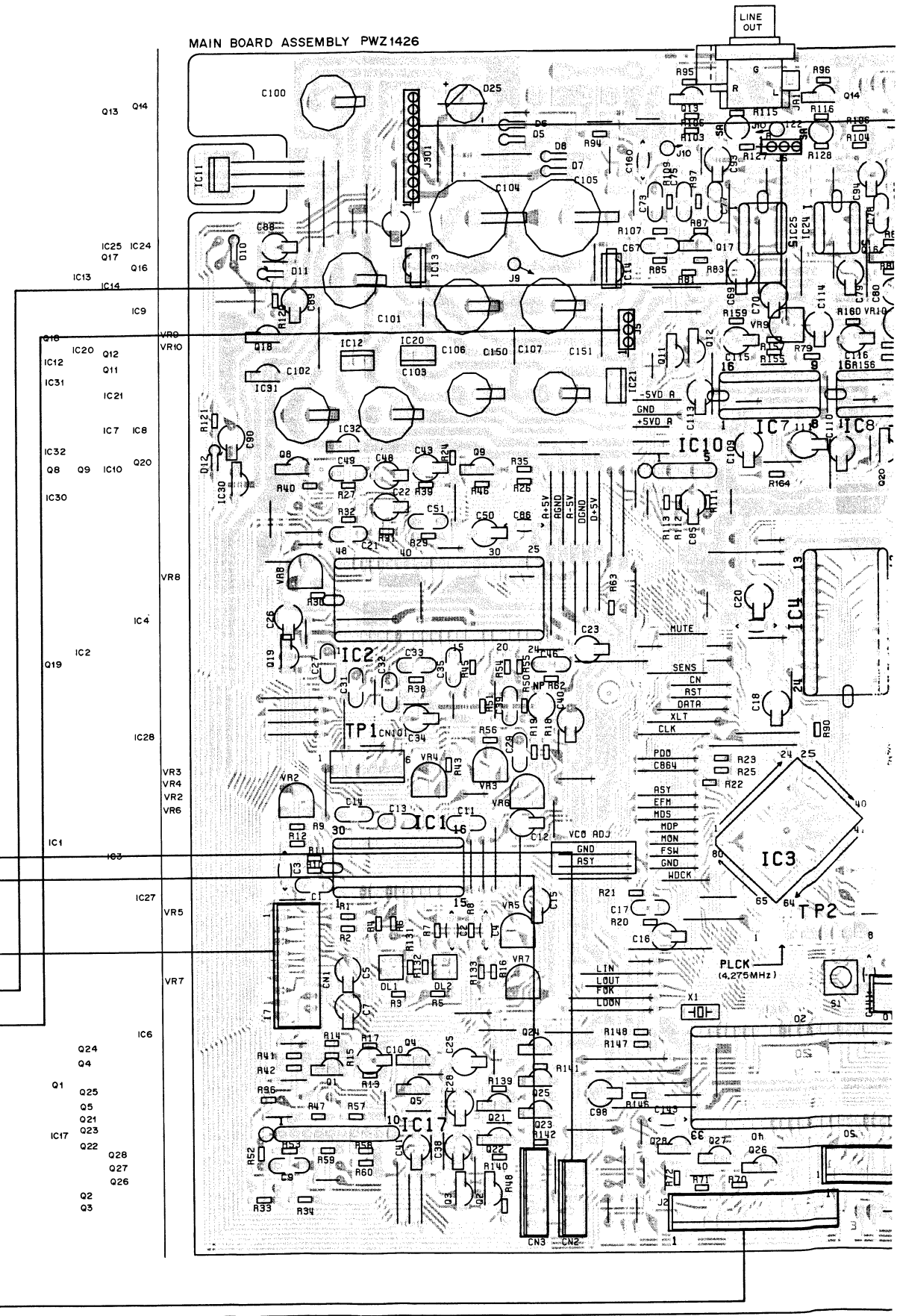
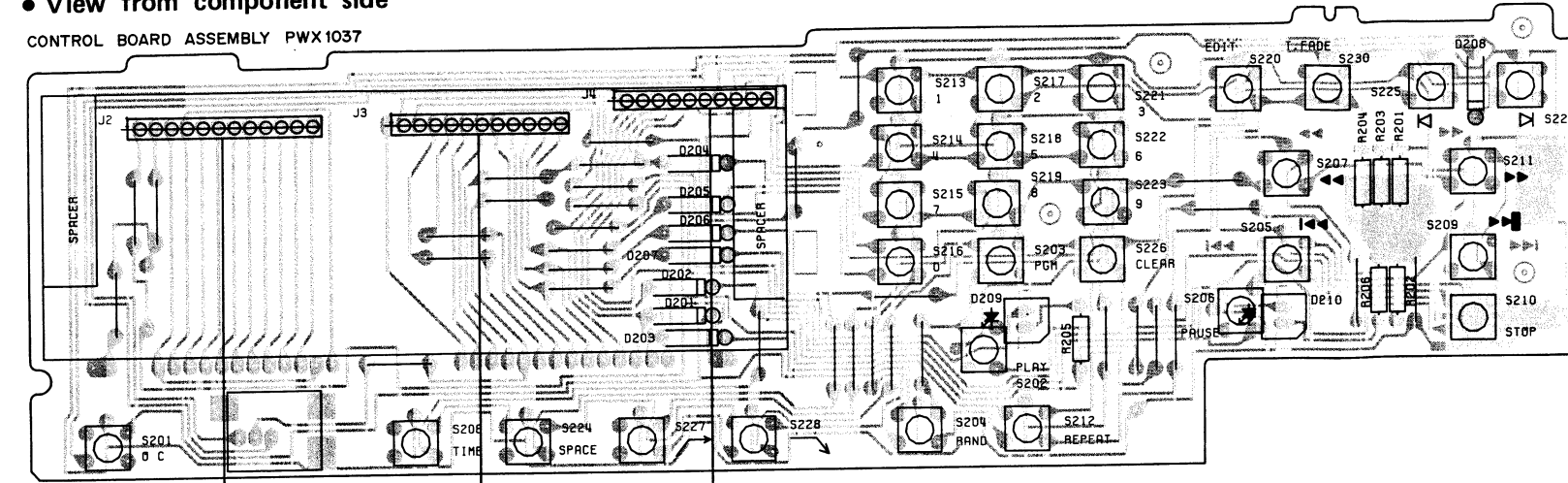
NJM78M12FA



7. P.C.BOARDS CONNECTION DIAGRAM

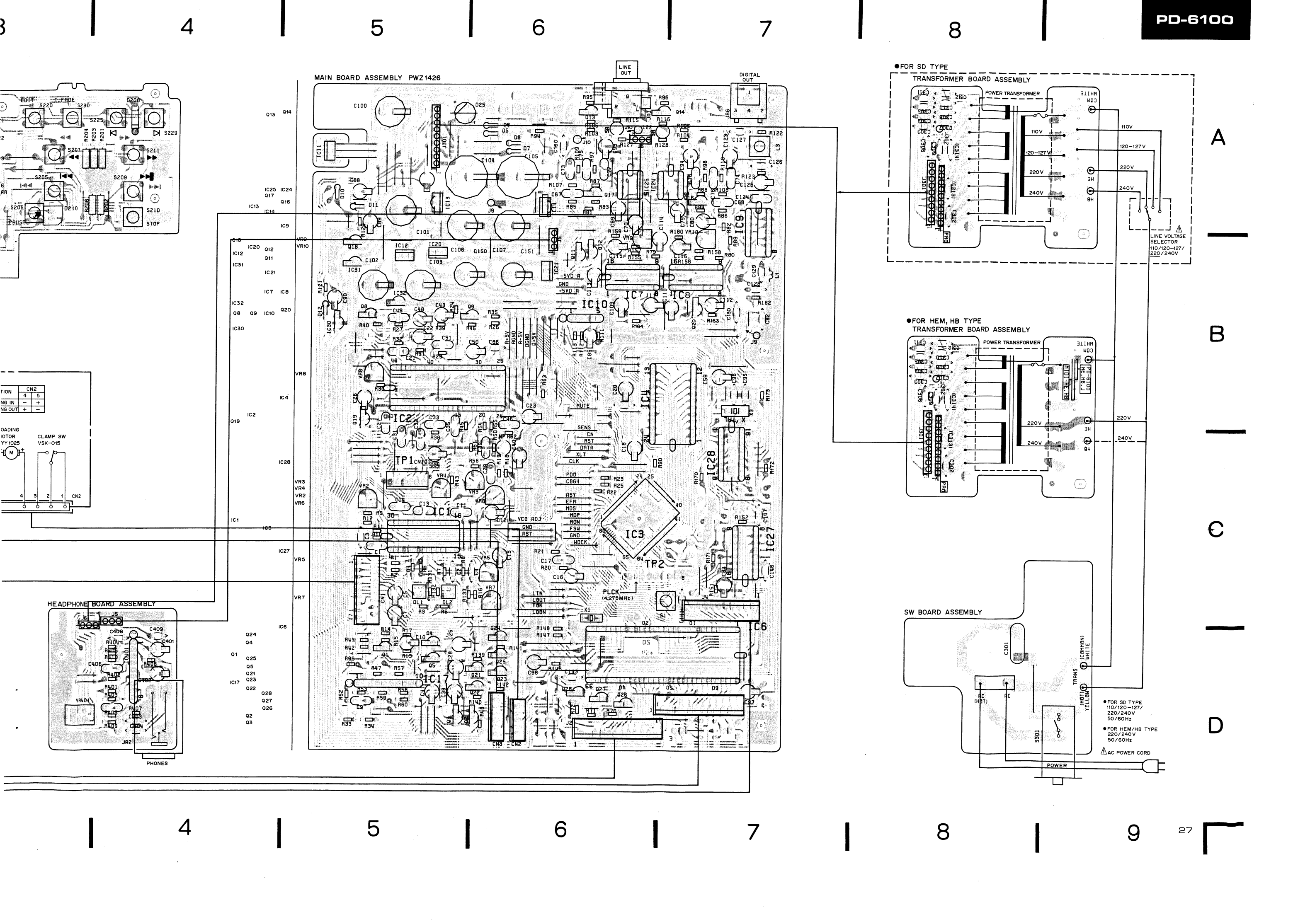
• View from component side

CONTROL BOARD ASSEMBLY PWX1037



| P.C.B. pattern diagram indication | Corresponding part symbol | Part name |
|-----------------------------------|---------------------------|--|
| | | Transistor |
| | | FET |
| | | Diode |
| | | Zener diode |
| | | LED |
| | | Varactor |
| | | Tact switch |
| | | Inductor |
| | | Coil |
| | | Transformer |
| | | Filter |
| | | Ceramic capacitor |
| | | Mylar capacitor |
| | | Styrol capacitor |
| | | Electrolytic capacitor (Non polarized) |
| | | Electrolytic capacitor (Nonleak) |
| | | Electrolytic capacitor (Polarized) |
| | | Electrolytic capacitor (Polarized) |
| | | Power capacitor |
| | | Semi-fixed resistor |
| | | Resistor array |
| | | Resistor |
| | | Resonator |

1. This P.C.B. connection diagram is viewed from the parts mounted side.
2. The parts which have been mounted on the board can be replaced with those shown with the corresponding wiring symbols listed in the above table.
3. The capacitor terminal marked with shows negative terminal.
4. The diode marked with shows cathode side.
5. The transistor terminal marked with shows emitter.



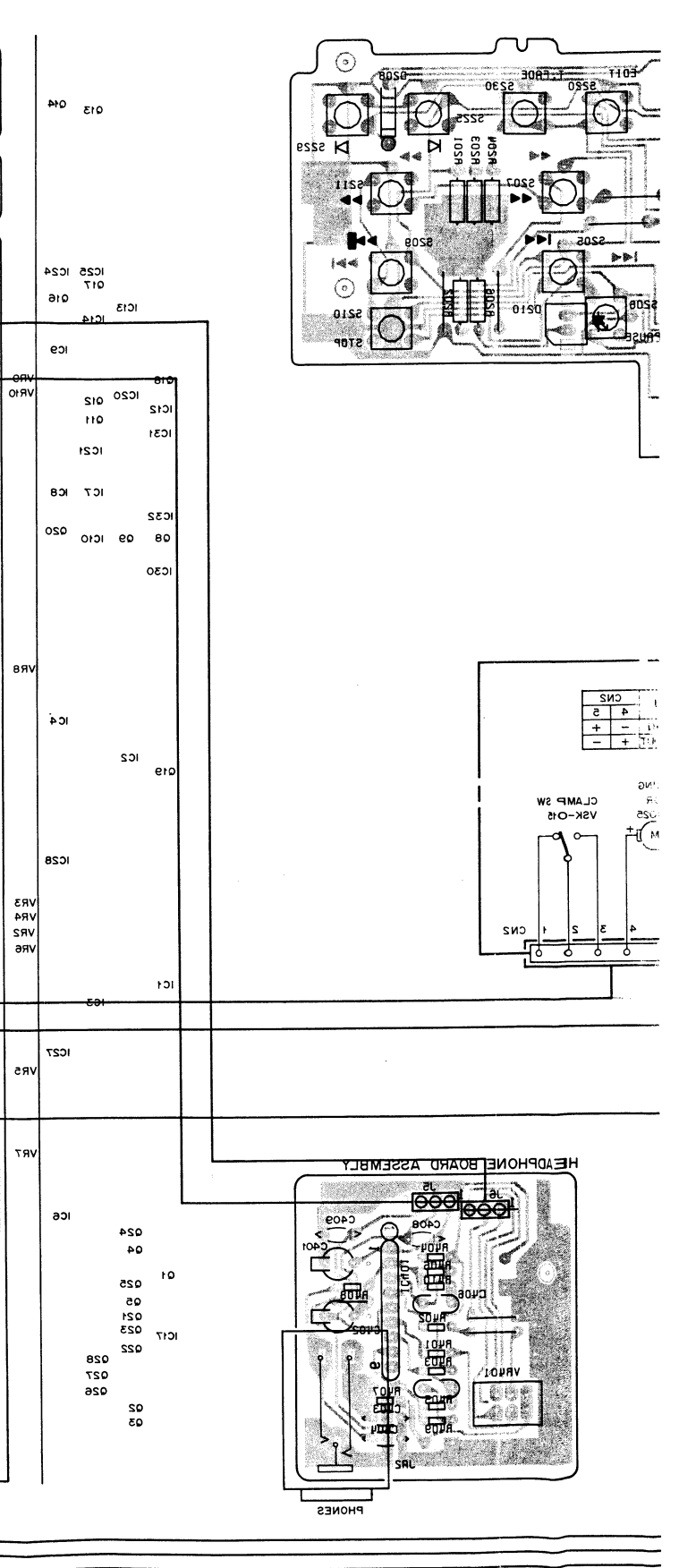
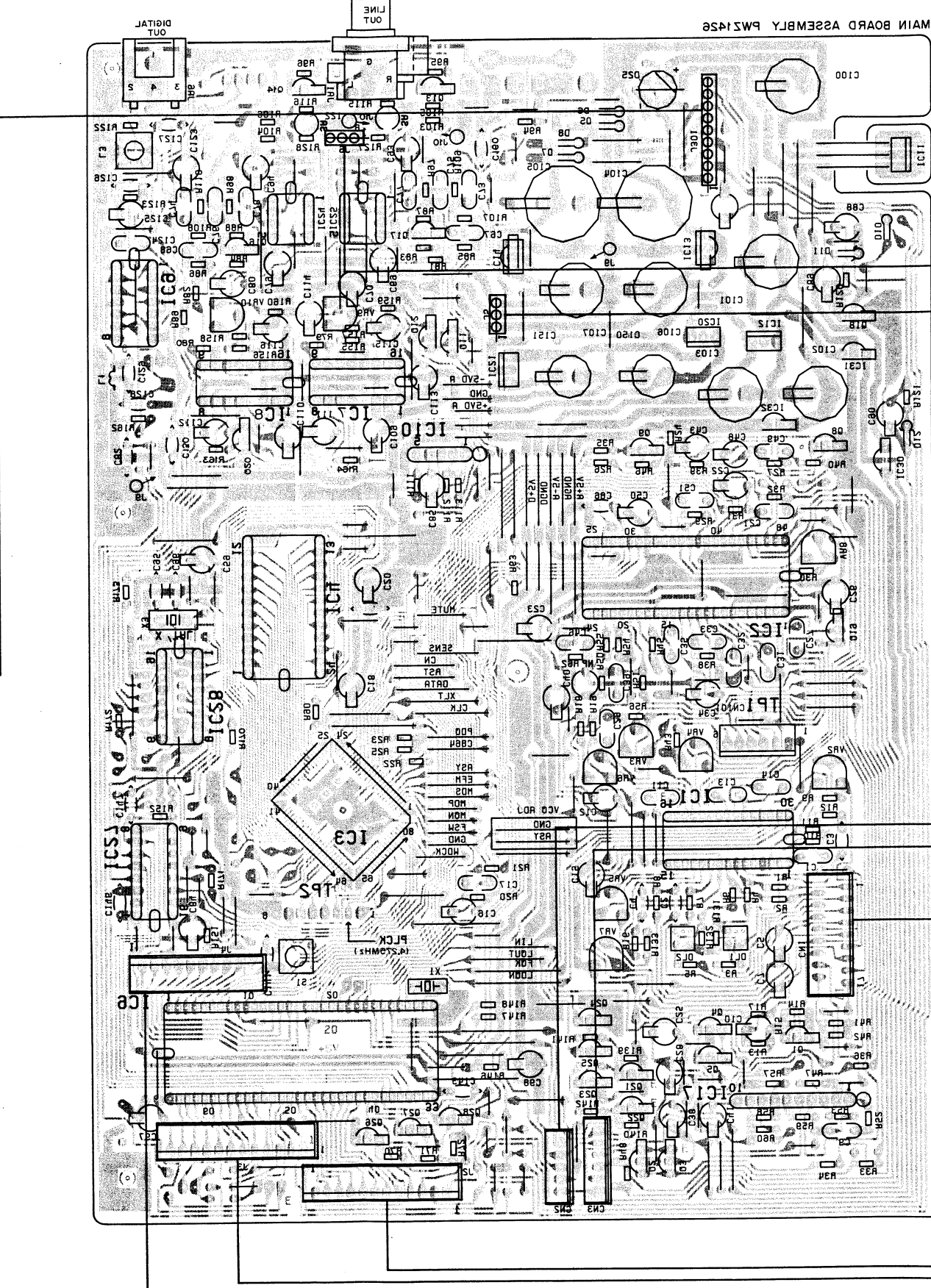
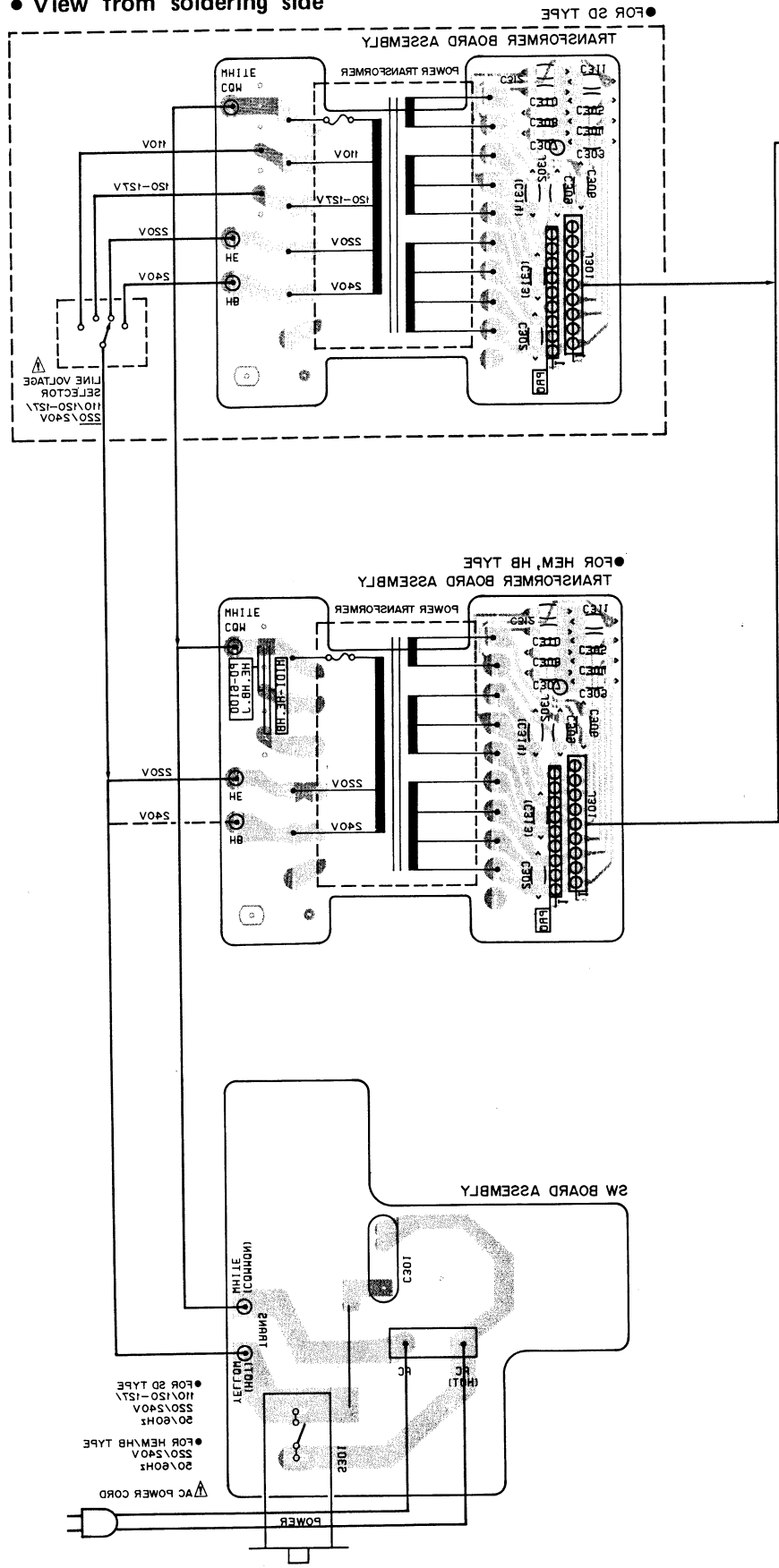
• View from soldering side

A

B

C

D



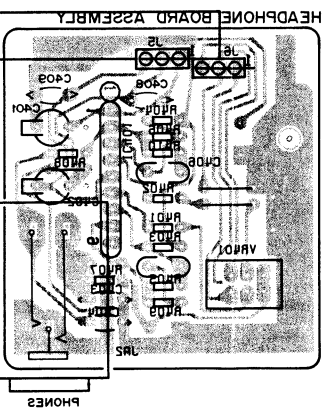
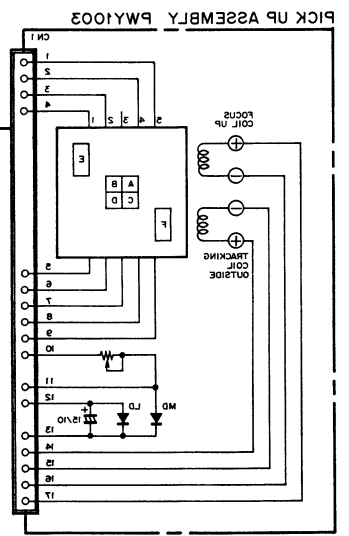
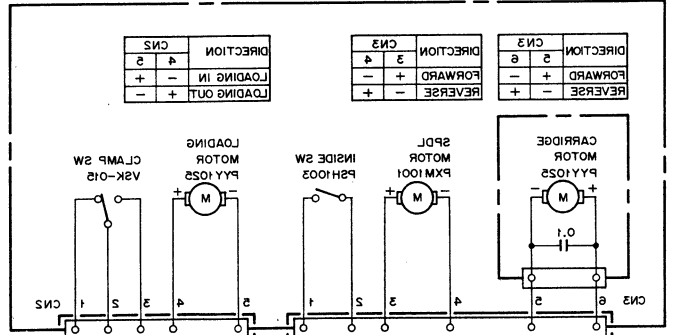
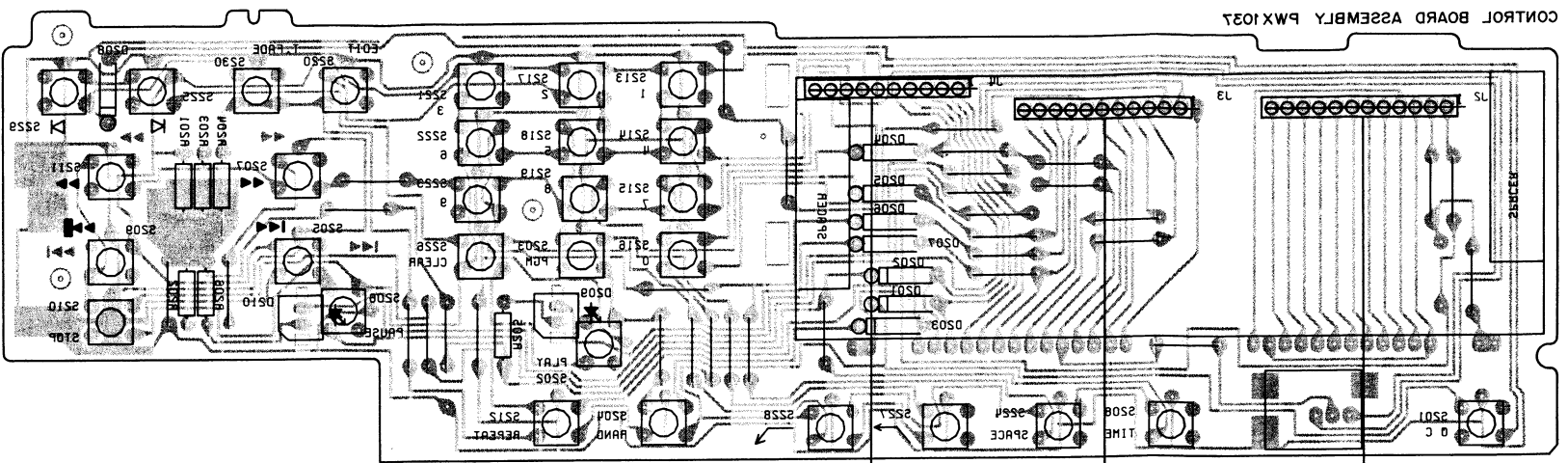
A

B

C

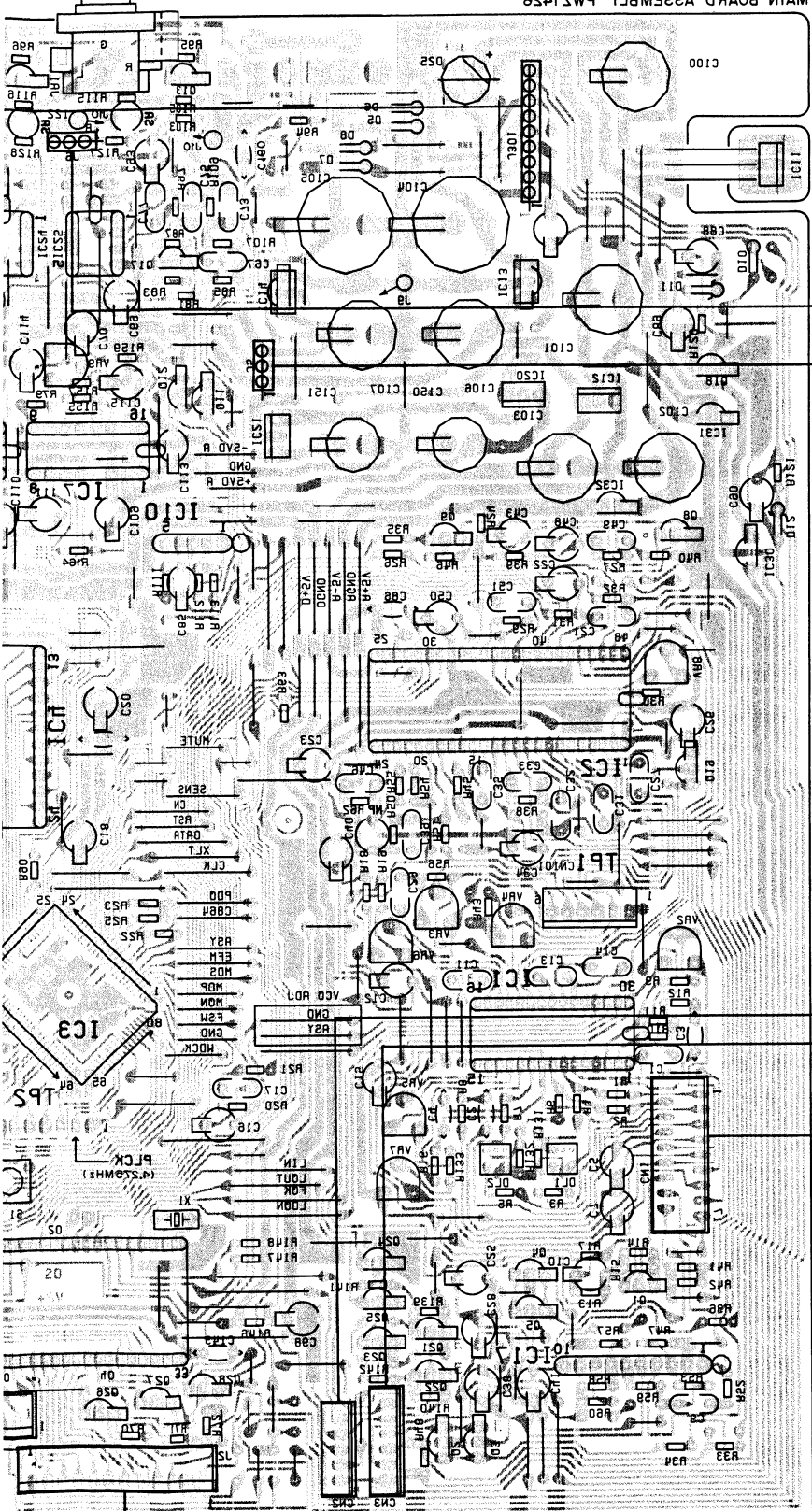
D

CONTROL BOARD ASSEMBLY PMX1031



| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-------|
| IC1 | IC2 | IC3 | IC4 | IC5 | IC6 | IC7 | IC8 | IC9 | IC10 | IC11 | IC12 | IC13 | IC14 | IC15 | IC16 | IC17 | IC18 | IC19 | IC20 | IC21 | IC22 | IC23 | IC24 | IC25 | IC26 | IC27 | IC28 | IC29 | IC30 | IC31 | IC32 | IC33 | IC34 | IC35 | IC36 | IC37 | IC38 | IC39 | IC40 | IC41 | IC42 | IC43 | IC44 | IC45 | IC46 | IC47 | IC48 | IC49 | IC50 | IC51 | IC52 | IC53 | IC54 | IC55 | IC56 | IC57 | IC58 | IC59 | IC60 | IC61 | IC62 | IC63 | IC64 | IC65 | IC66 | IC67 | IC68 | IC69 | IC70 | IC71 | IC72 | IC73 | IC74 | IC75 | IC76 | IC77 | IC78 | IC79 | IC80 | IC81 | IC82 | IC83 | IC84 | IC85 | IC86 | IC87 | IC88 | IC89 | IC90 | IC91 | IC92 | IC93 | IC94 | IC95 | IC96 | IC97 | IC98 | IC99 | IC100 |
|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-------|

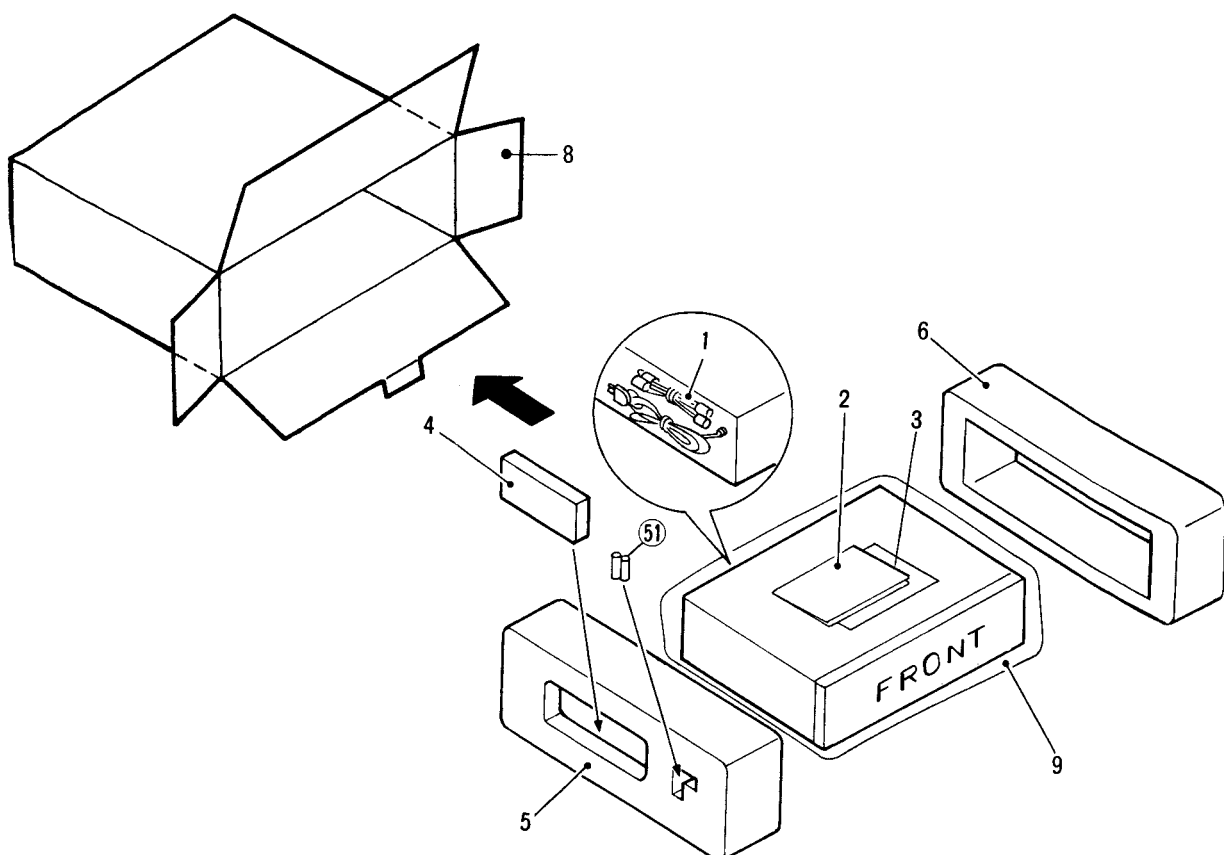
MAIN BOARD ASSEMBLY PM1456



8. PACKING

Parts list

| Mark | No. | Part No. | Description |
|------|-----|----------|--|
| | 1 | PDE1002 | Connection cord |
| | 2 | PRE1052 | Operating instructions (English, German, French, Italian) |
| | 3 | PRF1007 | Operating instructions (Dutch, Spanish, Swedish, Portuguese) |
| | 4 | PWW1023 | Remote control unit |
| | 5 | PHA1059 | Protector (L) |
| | 6 | PHA1060 | Protector (R) |
| | 7 | PHC1030 | Spacer (in the tray) |
| | 8 | PHG1198 | Packing case |
| | 9 | Z23-007 | Sheet |
| | 51 | | Battery |



9. ELECTRICAL PARTS LIST

NOTES :

- Parts without part number cannot be supplied.
- Parts marked by "⊙" are not always kept in stock. Their delivery time may be longer than usual or they may be unavailable.
- The Δ mark found on some component parts indicates the importance of the safety factor of the part. Therefore, when replacing, be sure to use parts of identical designation.
- For your parts Stock Control, the fast moving items are indicated with the marks $\star\star$ and \star .

$\star\star$ GENERALLY MOVES FASTER THAN \star .

This classification shall be adjusted by each distributor because it depends on model number, temperature, humidity, etc.

- When ordering resistors, first convert resistance values into code form as shown in the following examples.

Ex.1 When there are 2 effective digits (any digit apart from 0), such as 560 ohm and 47k ohm (tolerance is shown by J=5%, and K=10%).

| | | | | | |
|--------------|------------------|-----|---------|---|---|
| 560 Ω | 56 $\times 10^1$ | 561 | RD1/4PS | $\begin{smallmatrix} 5 & 6 & 1 \\ \hline \end{smallmatrix}$ | J |
| 47k Ω | 47 $\times 10^3$ | 473 | RD1/4PS | $\begin{smallmatrix} 4 & 7 & 3 \\ \hline \end{smallmatrix}$ | J |
| 0.5 Ω | 0R5 | | RN2H | $\begin{smallmatrix} 0 & R & 5 \\ \hline \end{smallmatrix}$ | K |
| 1 Ω | 010 | | RS1P | $\begin{smallmatrix} 0 & 1 & 0 \\ \hline \end{smallmatrix}$ | K |

Ex.2 When there are 3 effective digits (such as in high precision metal film resistors).

| | | | | | |
|----------------|-------------------|------|---------|---|---|
| 5.62k Ω | 562 $\times 10^1$ | 5621 | RN1/4SR | $\begin{smallmatrix} 5 & 6 & 2 & 1 \\ \hline \end{smallmatrix}$ | F |
|----------------|-------------------|------|---------|---|---|

Miscellaneous Parts

P. C. BOARD ASSEMBLIES

| Mark | Symbol & Description | Part No. |
|------------|----------------------------|----------|
| Δ ⊙ | Main board assembly | PWZ1426 |
| ⊙ | Control board assembly | PWX1037 |
| | Headphone board assembly | |
| Δ | Transformer board assembly | |
| Δ | SW board assembly | |

| Mark | Symbol & Description | Part No. |
|-----------------------|----------------------|------------|
| Δ $\star\star$ | IC11 | NJM7805FA |
| $\star\star$ | IC21 | NJM79M05FA |
| $\star\star$ | IC14 | NJM79M12FA |
| Δ $\star\star$ | IC12 | NJM7905FA |
| $\star\star$ | IC7, IC8 | PCM56P |
| $\star\star$ | IC27 | PD0026A |
| $\star\star$ | IC28 | PD0029 |
| $\star\star$ | IC6 | PD4152 |
| Δ $\star\star$ | IC17 | TA7256P |
| $\star\star$ | IC9 | TC74HCU04P |

OTHERS

| Mark | Symbol & Description | Part No. |
|------------------|------------------------------------|----------|
| Δ | Straine relief | CM-22B |
| Δ | AC power cord | PDG1003 |
| Δ \star | Power transformer | PTT1063 |
| $\star\star$ | S101 Slide switch (INSIDE) | PSH1003 |
| $\star\star$ | S102 Leaf switch (OPEN/CLAMP) | VSK-015 |
| $\star\star$ | Spindle motor | PXM1001 |
| $\star\star$ | Motor assembly (CARRIAGE, LOADING) | PYY1025 |
| | Pick up assembly | PWY1003 |

| | | |
|-----------------------|--------------------------------|-------------------|
| $\star\star$ | Q11, Q23 | DTA124ES |
| $\star\star$ | Q12, Q19, Q24, Q25 | DTC124ES |
| Δ $\star\star$ | Q18 | 2SA1015 |
| $\star\star$ | Q1, Q3, Q5 | 2SA1399 |
| $\star\star$ | Q21 | 2SA854S |
| $\star\star$ | Q8, Q9, Q16, Q17, Q20, Q26-Q28 | 2SC1740S |
| $\star\star$ | Q22 | 2SC1741S |
| $\star\star$ | Q2, Q4 | 2SC3581 |
| $\star\star$ | Q13, Q14 | 2SD1302 |
| \star | D11 | MTZ27B (MTZ27C) |
| \star | D12 | MTZ6.2B (MTZ6.2C) |
| Δ \star | D25 | WL02-5004-L |
| Δ \star | D5-D8, D10 | 1SR139-100 |

SWITCH

| Mark | Symbol & Description | Part No. |
|--------------|-----------------------|----------|
| $\star\star$ | S1 Tact switch (TEST) | PSG-065 |

Δ ⊙ Main Board Assembly (BWZ1426)

SEMICONDUCTORS

| Mark | Symbol & Description | Part No. |
|-----------------------|----------------------|---|
| $\star\star$ | IC1 | CXA1081S |
| $\star\star$ | IC2 | CXA1082AS |
| $\star\star$ | IC3 | CXD1135QZ |
| $\star\star$ | IC4 | CXK5816PN-12L (CXK5816PN-15L) (LH5116-15) |
| Δ $\star\star$ | IC30-IC32 | ICP-N10 |
| $\star\star$ | IC10 | M51957AL |
| $\star\star$ | IC24, IC25 | NJM5532DD |
| $\star\star$ | IC20 | NJM78M05FA |
| $\star\star$ | IC13 | NJM78M12FA |

CAPACITORS

| Mark | Symbol & Description | Part No. |
|------|-------------------------------|-------------|
| | C95, C96 | CCCCH120J50 |
| | C82, | CCCCH100D50 |
| | C2-C4 | CCCCH300J50 |
| | C126 | CCCCL101J50 |
| | C40 | CEANP4R7M25 |
| | C85 | CEASR33M50 |
| | C147 | CCCCL221J50 |
| | C16, C22 | CEASR47M50 |
| | C34 | CEAS4R7M50 |
| | C10, C43 | CEAS101M10 |
| | C88 | CEAS101M50 |
| | C102, C103 | CEAS102M10 |
| | C106, C107 | CEAS102M16 |
| | C89, C93, C94 | CEAS220M50 |
| | C100, C101 | CEAS222M16 |
| | C104, C105 | CEAS222M25 |
| | C48 | CEAS3R3M50 |
| | C5, C7, C12, C15, C20, C23, | CEAS330M16 |
| | C25, C26, C28, C38, C41, C50, | |
| | C59, C69, C70, C79, C80, C84, | |
| | C97, C98, C109-C116, C123, | |
| | C125 | |
| | C90 | CEAS470M50 |
| | C150, C151, C18 | CEAS471M10 |
| | C86, C141, C143, C146 | CKCYF103Z50 |
| | C33, C51, C75, C76 | CQMA102J50 |
| | C14, C17, C46, C124 | CQMA103K50 |
| | C127-C130, C142 | CKCYF473Z50 |
| | C31, C32, C35, C39 | CQMA104K50 |
| | C29 | CQMA272J50 |
| | C13 | CQMA332J50 |
| | C9, C11, C21 | CQMA333K50 |
| | C1, C27, C49 | CQMA472J50 |
| | C77, C78 | CQMA183J50 |
| | C67, C68 | CQMA683J50 |
| | C121, C122 | CQSA102J50 |
| | C73, C74 | CQMA682J50 |

RESISTORS

| Mark | Symbol & Description | Part No. |
|------|-----------------------------|-------------------|
| ★ | VR2 Semi-fixed (10k) | VRTB6VS103 |
| ★ | VR3-VR7 Semi-fixed (22k) | VRTB6VS223 |
| ★ | VR8 Semi-fixed (1k) | VRTS6VS102 |
| | R30 Metal thin film | RN 1/8 PQ3601F |
| | VR9, VR10 Semi-fixed (100k) | VRTB6VS104 |
| | Other resistors | RD 1/8 PM □ □ □ J |

OTHERS

| Mark | Symbol & Description | Part No. |
|------|------------------------------|----------|
| | JA6 1P Pinjack (DIGITAL OUT) | PKB1004 |
| | JA1 2P Pinjack (LINE OUT) | PKB1009 |
| ★ | X3 Crystal resonator | PSS1001 |
| | DL1, DL2 Delay line | PTF1012 |
| | L3 Pulse transformer | PTL1003 |
| | L1 Inductor | LRA010k |
| ★ | X1 Ceramic resonator | VSS1014 |

⊙ Control Board Assembly (PWX1037)

SEMICONDUCTORS

| Mark | Symbol & Description | Part No. |
|------|----------------------|--------------|
| ★ | D209 | SLH-56MC3H |
| ★ | D210 | SLH-56YC3HYL |
| ★ | D201-D208 | 1SS254 |

SWITCHES

| Mark | Symbol & Description | Part No. |
|------|--|----------|
| ★★ | S201-S230 Tact switch (OPEN/CLOSE, TIME, AUTO SPACE, AUTO FADER IN, AUTO FADER OUT, RANDOM PLAY REPEAT, PROGRAM, CLEAR, TRUCK NUMBER, AUTO PROGRAM EDIT, TIME FADE EDIT, INDEX SEARCH, MANUAL SEARCH, TRACK SEARCH, PLAY, PAUSE, STOP) | PSG-065 |

RESISTORS

| Mark | Symbol & Description | Part No. |
|------|----------------------|-------------------|
| | All resistors | RD 1/4 PM □ □ □ J |

OTHERS

| Mark | Symbol & Description | Part No. |
|------|--|-------------------|
| ★ | V201 Fluorescent tube Remote control sensor unit | PEL1020 GPIU52 |

Headphone Board Assembly

SEMICONDUCTOR

| Mark | Symbol & Description | Part No. |
|------|----------------------|----------|
| ★★ | IC401 | NJM4556S |

CAPACITORS

| Mark | Symbol & Description | Part No. |
|------|------------------------|-------------|
| | C401, C402 | CEAS330M16 |
| | C403, C404, C408, C409 | CKCYF103Z50 |
| | C406, C407 | CQMA104K50 |
| | C405 | CKCYF473Z50 |

RESISTORS

| Mark | Symbol & Description | Part No. |
|------|---|-------------------|
| ★ | VR401 Variable resistor (PHONES LEVEL) | PC11001 |
| | Other resistors | RD 1/8 PM □ □ □ J |

OTHERS

| Mark | Symbol & Description | Part No. |
|------|-------------------------|----------|
| | JA2 Phone jack (PHONES) | RK11001 |

⚠ Transformer Board Assembly

CAPACITORS

| Mark | Symbol & Description | Part No. |
|------|----------------------|-------------|
| | C302-C311 | CKCYF103Z50 |

⚠ SW board Assembly

SWITCH

| Mark | Symbol & Description | Part No. |
|------|----------------------|----------|
| ⚠★★ | S301 Power switch | PSA-009 |

CAPACITOR

| Mark | Symbol & Description | Part No. |
|------|----------------------------|----------|
| ⚠ | C301 (0.01 μ F/AC250V) | RCG-009 |

10. ADJUSTMENT

The adjustments for this unit are shown below. Adjustments must be made in the order in which they are listed.

● ADJUSTMENTS

1. Tracking error offset, focus offset and RF offset adjustment
2. RF level adjustment
3. LD (laser diode) power check
4. Focus lock and spindle lock check
5. Grating adjustment (1), (2)
6. Tracking balance adjustment
7. Tangential adjustment
8. Focus gain adjustment
9. Tracking gain adjustment
10. VCO free run frequency adjustment
11. Focus error check
12. MSB adjustment

● REQUIRED EQUIPMENT

1. Dual trace oscilloscope
2. Optical power meter
3. Test disc (YEDS-7)
4. Loop gain adjustment filter
5. Signal generator
6. Frequency counter
7. Other commonly used measuring equipment

● ABOUT THE TEST MODE

All adjustments must be carried out with the unit in the test mode.

Activating and releasing the test mode

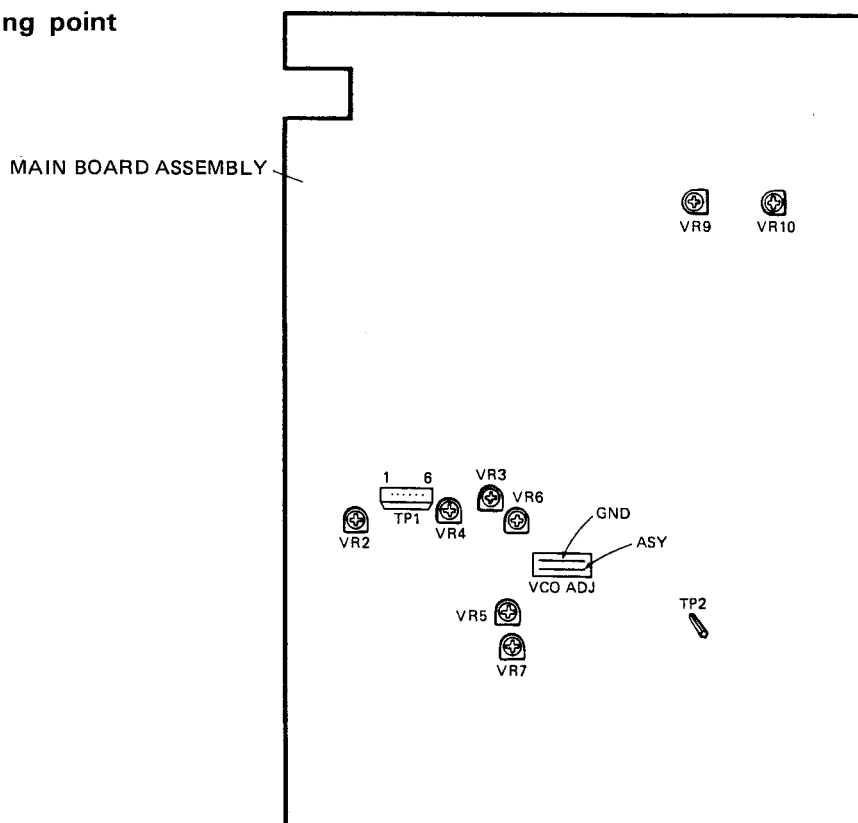
- (1) To activate the test mode, turn ON the power switch (S301) with the test mode switch (S1) in the ON position.
- (2) The test mode is released by turning the power switch OFF.

The functions for the keys in the test mode are outlined in Table 10-1.

● ADJUSTMENT VRs AND THEIR NAMES

- VR1: Laser power
 VR2: RF offset (RF.OFS)
 VR3: Focus gain (FCS.GAN)
 VR4: Tracking gain (TRK.GAN)
 VR5: Tracking balance (TRK.BAL)
 VR6: Focus offset (FCS.OFS)
 VR7: Tracking offset (TRK.OFS)
 VR8: VCO adjust (VCO.ADJ)
 VR9: MSB adjust R-CH (MSB.ADJ-R)
 VR10: MSB adjust L-CH (MSB.ADJ-L)

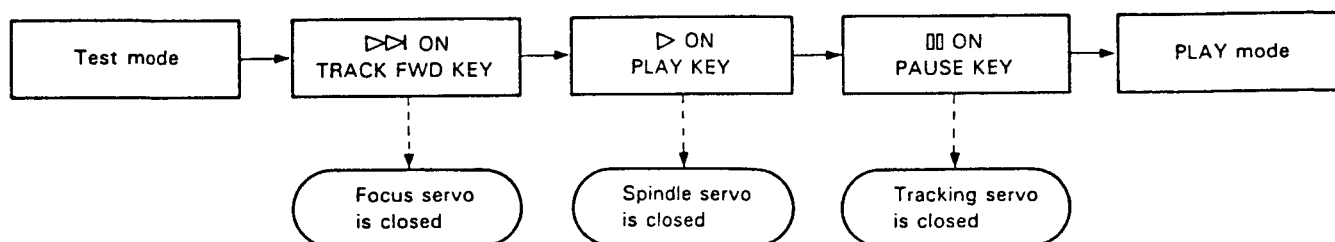
Adjusting point



In the test mode, the servos must be closed and opened individually. Consequently, the servos must each be closed in the proper sequence (serial sequence) in order to put the machine into the play mode. Note also that during test mode the unit will not enter the play mode when the PAUSE (⏸) key is pressed alone.

For example, in order to change from the stop to the play mode, the function keys must be pressed in the following order:

- * In the test mode, the servos must be operated in serial sequence.

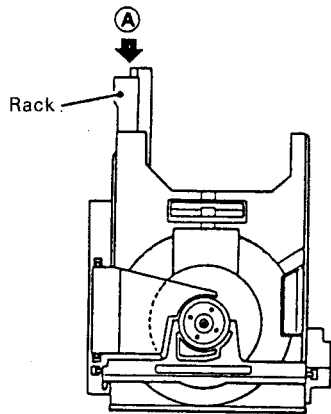
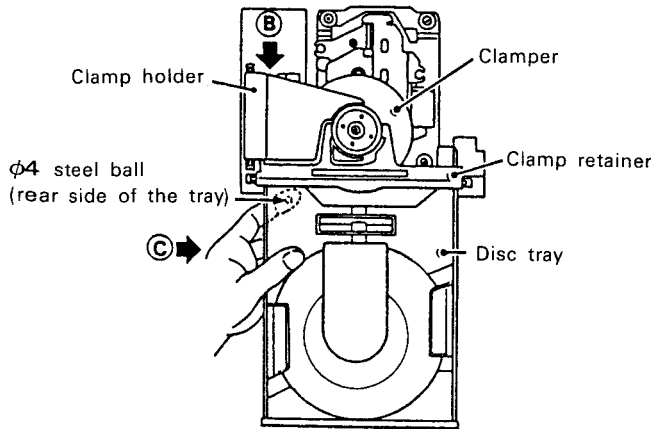


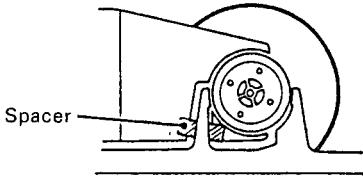
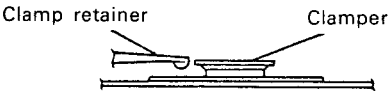
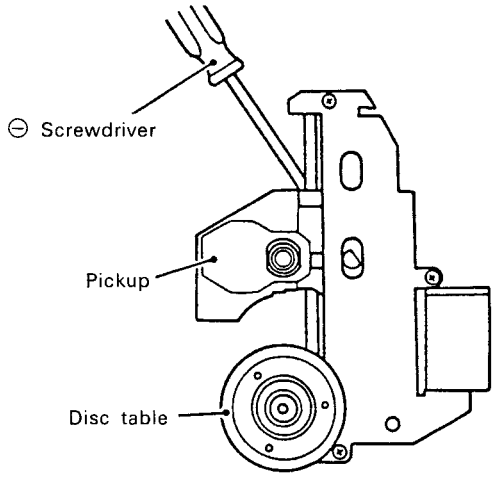
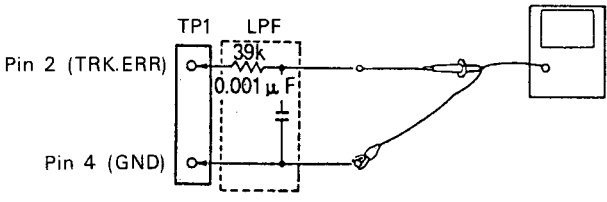
● KEY FUNCTIONS IN THE TEST MODE

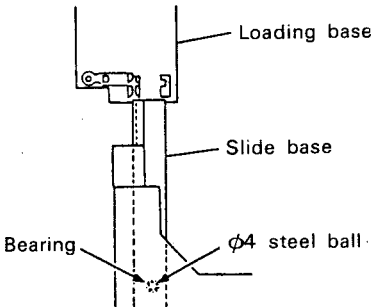
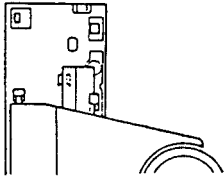
| Symbol | Key name | Function in test mode | Description |
|--------|-------------------|----------------------------------|--|
| ▷▷ | TRACK FWD | Focus servo close | Turns ON the laser diode, and raises and lowers the focusing actuator to close the focus servo. |
| ▷ | PLAY | Spindle servo close | Closes the servo in the CLV-A mode after kicking the spindle motor. |
| ⏸ | PAUSE | Tracking servo close/open | Acts as toggle: closes the tracking servo and activates play mode when pressed (provided the focus and spindle servos are closed), at which time the PAUSE indicator illuminates; opens the tracking servo when pressed again. |
| ◁ | MANUAL SEARCH REV | Carriage reverse (moves inward) | Moves carriage quickly (3 cm/s) toward inner-most track. Be careful not to move too far as there is no safety device to stop the carriage. |
| ▷ | MANUAL SEARCH FWD | Carriage forward (moves outward) | Moves carriage quickly (3 cm/s) toward outer-most track. Be careful not to move too far as there is no safety device to stop the carriage. |
| □ | STOP | Stop | Stops all servos and returns system to its initial state. |
| ⏏ | OPEN/CLOSE | Disc tray open/close | Opens and closes the disc tray. However, pickup does not return to rest on OPEN, and it remains stationary on CLOSE. |

Table 10-1

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustment specifications | Adjustment procedure |
|----------|--|---|---|---|---|---|
| | V | H | | | | |
| 1 | Tracking error offset, focus offset and RF offset adjustment | | | | | |
| | | | TP1 Pin 2 (TRK.ERR) TP1 Pin 6 (FCS.ERR) TP1 Pin 1 (RF. OUTPUT) | VR5 (TRK.BAL) VR7 (TRK.OFS) VR6 (FCS.OFS) VR2 (RF.OFS) | Tracking error offset 45° 0V±50 mV Focus offset 0V±50 mV RF offset 100 mV±50 mV | <ul style="list-style-type: none">Set the unit to test mode (see page 35).Set VR5 TRK.BAL (tracking balance) to the position about 45° to the left of center.Adjust VR7 TRK.OFS (tracking offset) so that the TRK.ERR (tracking error) voltage at TP1 Pin 2 becomes 0V±50 mV.Adjust VR6 FCS.OFS (focus offset) so that the FCS.ERR (focus error) voltage at TP1 Pin 6 becomes 0V±50 mV.Adjust VR2 RF.OFS (RF offset) so that the RF output voltage at TP1 Pin 1 becomes 100 mV±50 mV. <p>Note: When adjusting the tracking error offset, always perform "6. Tracking Balance Adjustment."</p> |
| 2 | RF level adjustment | | | | | |
| | | | TP1 Pin 1 (RF OUTPUT) | VR1 (Laser power) | 1.8V±0.1V | <ul style="list-style-type: none">Set the unit to test mode (see page 35).Play the test disc, connect the oscilloscope to TP1 Pin 1 (RF output), and measure the P-P voltage of the RF waveform.Check that the voltage is 1.8V±0.1V |
| 3 | LD (laser diode) power check | | | | | |
| | | | | | Less than 0.13 mW | <ul style="list-style-type: none">Set the unit to test mode (see page 35).Press the TRACK FWD (▶◀) key to turn ON the LD (laser diode).Place the sensor of the optical power meter directly above the objective lens and confirm that LD power is less than 0.13 mW. |

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/ Adjustment specifications | Adjustment procedure |
|----------|--|----------------------|-----------------------------|------------------|--|--|
| | V | H | | | | |
| 4 | Focus lock and spindle lock check | | | | | |
| | V 0.5V/div | H 100 msec/div | TP1 Pin 1 (RF output) | | RF signal is output Forward (clockwise) rotation | <ul style="list-style-type: none">• Set the test disc.• Set the unit to test mode (see page 35).• Press the MANUAL SEARCH FWD (▶▶) key to move the pickup to the center of the disc.• Observe the output (RF output) of TP1 Pin 1 on the oscilloscope. Confirm that the RF signal is output after the TRACK FWD (▶▶) key is pressed.• Press the PLAY (▶) key and confirm that the disc rotates at constant speed (approx. 300 rpm near center of disc) in the forward (clockwise) direction; make sure that the disc does not rotate too fast or counterclockwise. |
| 5 | Grating adjustment (1) | | | | | |
| |  <p>Fig. 10-1</p> | | | | <p>Remove the disc tray before beginning this adjustment.</p> <ul style="list-style-type: none">• Removal of the disc tray <ol style="list-style-type: none">1. Press the rear edge of the rack, marked (A) in Fig. 10-1., while pulling the disc tray out to the position where it catches, illustrated in Fig. 10-2. <p>(*1) When the rear section of the rack (arrow (A)) is pressed, first the disc clamp is released. To slide out the disc tray fully, continue to press after the clamp has been released.</p> | |
| |  <p>Fig. 10-2</p> | | | | <ol style="list-style-type: none">2. While pulling the clamp holder (B) (see Fig. 10-2.) upward with the right hand, hold the tray as indicated by (C) in the left hand and pull it outward. Take care not to allow the $\phi 4$ steel ball to fall out (it is recommended to hold the ball in place with the left index finger while extracting the tray). | |

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustment specifications | Adjustment procedure |
|----------|----------------------|---|-------------|------------------|--|---|
| | V | H | | | | |
| | | | | | |  <p>Fig. 10-3</p> |
| | | | | | |  <p>Fig. 10-4</p> |
| | | | | |  <p>Fig. 10-5</p> | <ul style="list-style-type: none"> Set the unit to test mode (see page 35). Press the MANUAL SEARCH FWD (⏮) key to move the pickup to the vicinity of what would be the center of the disc. Position the pickup so its grating adjustment screw is visible through the elongated hole on the spindle motor side of the servo mechanism base plate. As shown in Fig. 10-5., insert a ⊖ screwdriver (2 mm precision screwdriver) from the rear of the mechanism and check that the grating adjustment screw can be rotated. Mount the test disc; be sure to insert a 3 – 5 mm spacer (if no spacer is available, use a hex wrench) between the clamp holder and the clamp retainer, as shown in Fig. 10-3. Confirm that the clasper and the clamp retainer are not contacting one another (Fig. 10-4). Press the TRACK FWD (⏭) and the PLAY (▶) keys sequentially to close the focus and spindle servos (do not close the tracking servo). Insert a 4 kHz-cutoff low pass filter between the oscilloscope and TP1 Pins 2 (TRK.ERR) and 4 (GND) as shown in Fig. 10-6. and observe the waveform output by TP1 Pin 2 TRK.ERR (tracking error) on the oscilloscope. |
| | | | | |  <p>Fig. 10-6</p> | |

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustement specifications | Adjustment procedure |
|--|----------------------|------------|---------------------------|--|--|---|
| | V | H | | | | |
| | 0.5V/div | 5 msec/div | TP1 Pin 2 (TRK.ERR) | Grating adjustment screw Grating adjustment screw | Null point Max. amplitude | <ul style="list-style-type: none"> Turn the grating adjustment screw with the \ominus screwdriver to find the null point (see Photo 10-1.). Next, slowly rotate the screw counterclockwise and adjust to the point where the waveform (tracking error signal) first achieves its maximum amplitude (see Photo 10-3.). <p>Note: Avoid applying pressure to the screwdriver while adjusting the screw. Doing so causes the pickup to move inward, making adjustment more difficult.</p> <ul style="list-style-type: none"> Lastly, remove the low pass filter and confirm that the tracking error signal p-p voltage does not greatly vary when the pickup is moved to the inner-most and outer-most tracks of the disc. <p>If the levels diverge by $\pm 10\%$ or more re-adjust the maximum error amplitude point by rotating the grating adjustment screw.</p> |
|  <p>Fig. 10-7</p>  <p>Fig. 10-8</p> | | | | | | <p>Remount the disc tray according to the following procedure when the grating adjustment is complete.</p> <ol style="list-style-type: none"> Remove the disc and the spacer. While lifting the clamp holder [marked \textcircled{B} in Fig. 10-2.] with the right hand, hold the tray in the left hand as indicated by \textcircled{C} and slide the slide base into the hard resin fittings on the loading base as shown in Fig. 10-7. to reinsert the disc tray. (At this time, be sure to hold the $\phi 4$ steel ball in place with the index finger of the left hand.) (Also, be careful that the front panel is not damaged by the bearing of the slide base at the $\phi 4$ steel ball section coming into contact with the panel.) Insert the slide base so that it fits into the two hard resin fittings at the rear of the loading base (see Fig. 10-8.). Insert the tray all the way. |

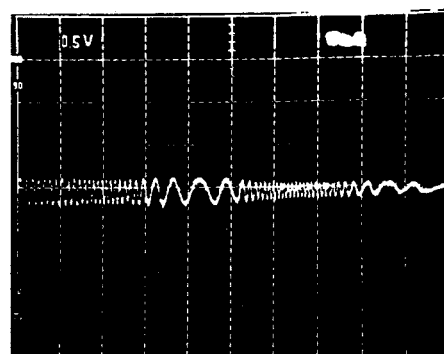


Photo 10-1 Null point

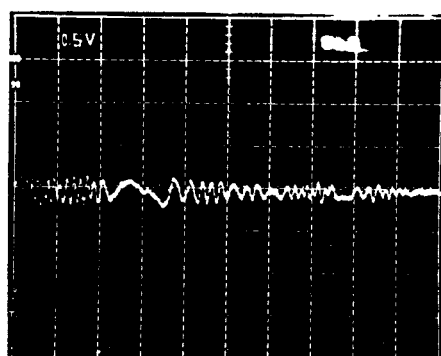


Photo 10-2 This is not the null-point waveform

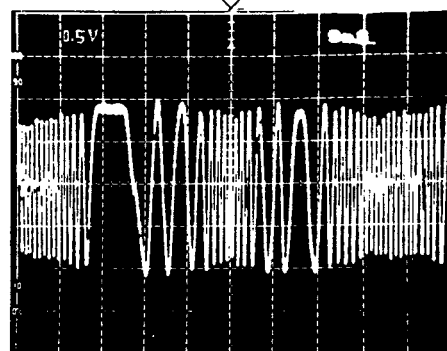
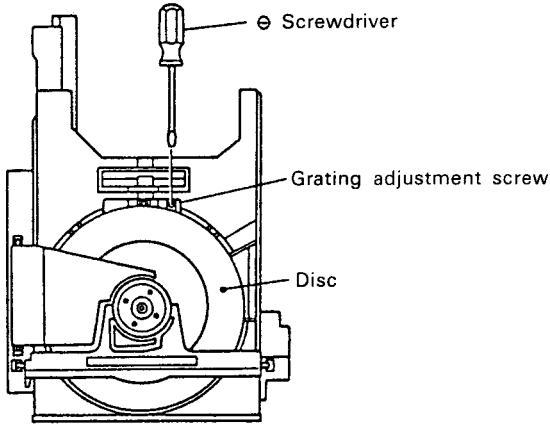
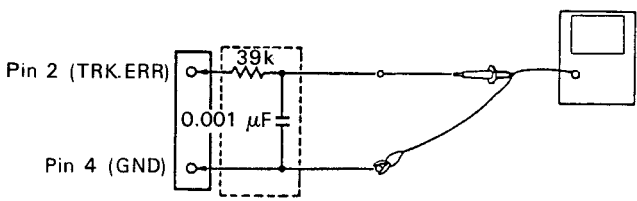
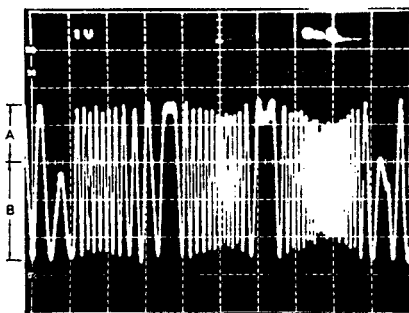
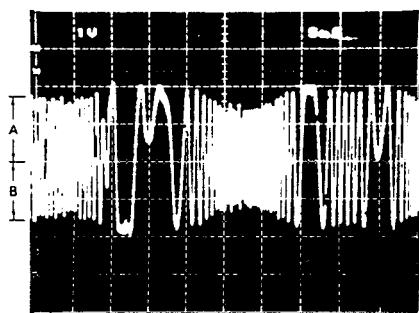
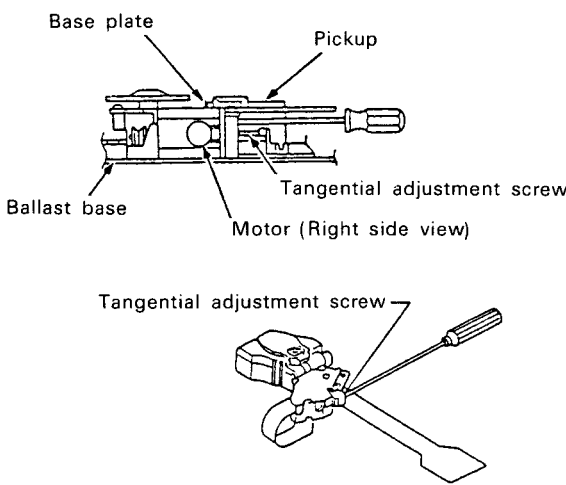
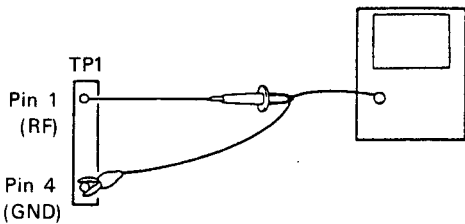
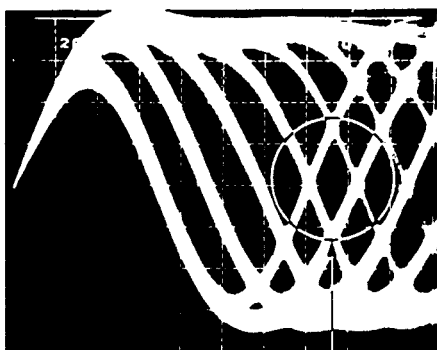


Photo 10-3 Maximum amplitude

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustement specifications | Adjustment procedure |
|----------|---|------------|---------------------------|------------------------|--|--|
| | V | H | | | | |
| 5 | Grating adjustment (2) (using discs with a recording time of 60 min. or more) | | | | | |
| | <div><p>Fig. 10-9</p></div> <div><p>Fig. 10-10</p></div> | | | | | <p>Note: This adjustment can only be performed with a disc having pits up to R115mm, not with the Test Disc (YEDS-7).</p> <ul style="list-style-type: none">• Set the unit to test mode (see page 35).• Load the test disc, shift the pickup to the outer periphery so that the pickup grating adjustment hole is visible from the pit surface of the disc or from the hole in the servo mechanism (see Fig. 10-10.).• Press the TRACK FWD (⏮) and the PLAY (▶) keys in sequence to close the focus servo and spindle servo (do not close the tracking servo).• Observe the waveform output by TP1 Pin 2 TRK.ERR (tracking error) on an oscilloscope, inserting a 4 kHz low-pass filter (see Fig 10-10.). |
| | 0.5V/div | 5 msec/div | TP1 Pin 2 (TRK.ERR) | Grating Grating | Null Point Maximum amplitude | <ul style="list-style-type: none">• Insert a ⊖ screwdriver into the grating hole, turn and find the null point (see Photo 10-1.).• Next, slowly turn the ⊖ screwdriver counter-clockwise from the null point and adjust until the waveform (tracking error signal) reaches maximum amplitude (see Photo 10-3.). <p>Note: Use caution since inserting the ⊖ screwdriver forcefully will cause the pickup unit to float upward.</p> <ul style="list-style-type: none">• Finally, confirm that there is no major fluctuation in the p-p voltage of the tracking error signal (do not insert the cutoff 4 kHz low-pass filter) when the pickup is shifted to the inner periphery and when the pickup is shifted to the outer periphery. If there is a difference of more than ±10% again rotate the grating adjustment screw and adjust the tracking error signal to maximum amplitude point. |

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustment specifications | Adjustment procedure |
|----------|---|------------|---------------------------|------------------|---------------------------------------|---|
| | V | H | | | | |
| 6 | Tracking balance adjustment | | | | | |
| | 0.5V/div | 5 msec/div | TP1 Pin 2 (TRK.ERR) | VR5 (TRK.BAL) | | <ul style="list-style-type: none">• Load the test disc.• Set the unit to test mode (see page 35).• Press the MANUAL SEARCH FWD (⏮) key to position the pickup near the center of the disc.• Press the TRACK FWD (⏭) and PLAY (▶) keys sequentially to cause the disc to rotate.• Observe the waveform output by TP1 Pin 2 TRK.ERR (tracking error) on the oscilloscope and adjust VR5 TRK.BAL (tracking balance) so that the DC components are eliminated from the tracking error signal. |
| |  | | | | |  |
| | Photo 10-4 DC elements mixed in signal | | | | | Photo 10-5 DC elements eliminated |
| 7 | Tangential adjustment | | | | | |
| |  | | | | | <ul style="list-style-type: none">• Set the unit to test mode (see page 35).• Open the tray and load the test disc.• Press the MANUAL SEARCH FWD (⏮) key to position the pickup near the center of the disc.• Insert a hex wrench into the tangential adjustment screw section from the rear of the mechanism.• Close the tray. <p>Note: An L-shaped hex wrench should not be used. Use one such as shown on the left. If an L-shaped hex wrench is to be used, the tray must be removed before performing adjustment (see page 39, 5. Grating Adjustment (1)).</p> <ul style="list-style-type: none">• Press the TRACK FWD (⏭), PLAY (▶), and PAUSE (⏸) keys sequentially to close all the servos (the pause indicator will illuminate). |

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustement specifications | Adjustment procedure |
|----------|----------------------|--------------|-----------------------------|-----------------------------|--|---|
| | V | H | | | | |
| | | 200 nsec/div | TP1 Pin 1 (RF output) | Tangential adjustment screw | Sharpest possible eye pattern | <ul style="list-style-type: none"> Observe the waveform output by TP1 Pin 1 (RF output) on the oscilloscope and adjust the tangential adjustment screw to achieve the sharpest possible eye pattern. The point to which the adjusting screw should be set lies about halfway between the points where the eye pattern becomes most blurred when the screw is rotated clockwise and counterclockwise. When the whole waveform becomes clear, concentrate on sharpening the fine lines forming the diamond at the center of the eye pattern (see Photo 10-8.). Adjust until the fine lines on all four sides of the diamond are both sharply defined and dense.  <p style="text-align: center;">Fig. 10-12</p> <p>Note: Use a hex wrench to raise the pickup somewhat while making this adjustment.</p> |



Part to be observed

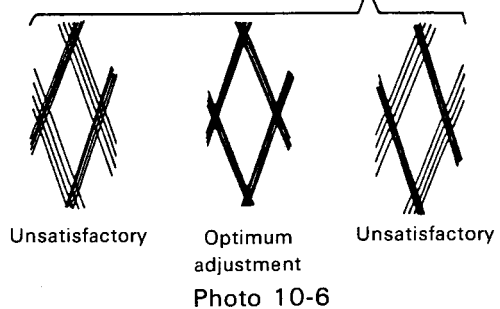


Photo 10-7



Photo 10-8



Photo 10-9

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/Adjustement specifications | Adjustment procedure |
|----------|---|---|-------------------|---------------------------|--|----------------------|
| | V | H | | | | |
| 8 | Focus gain adjustment | | | | | |
| | CH1(X), CH2(Y) 20 mV/div 5 mV/div (probe: 10:1) | X-axis TP1 Pin 5 (FCS. IN) Y-axis TP1 Pin 6 (FCS. ERR) | VR3 (FCS. GAN) | Phase difference of 90 | <ul style="list-style-type: none">With the oscillator power turned OFF, connect the oscilloscope and oscillator as shown in Fig. 10-13.Set the unit to test mode (see page 35).Press the TRACK FWD (▶), PLAY (▷) and PAUSE (⏸) keys sequentially to close the focus, spindle and tracking servos.Turn ON the power to the oscillator and set it to output a 1.2 kHz 1 Vp-p signal. <p>Note: Some oscillators discharge a DC voltage when turned on. It is therefore recommended that the oscillator be connected after it has been turned on.</p> <ul style="list-style-type: none">Adjust VR3 FCS.GAN (focus gain) so that the Lissajous's figure becomes a horizontal circle on the oscilloscope (phase difference of 90°). | |

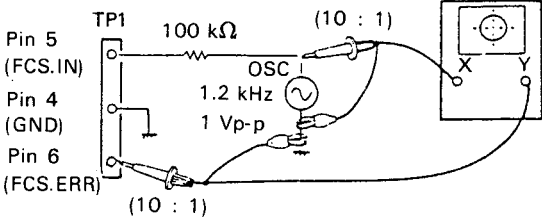
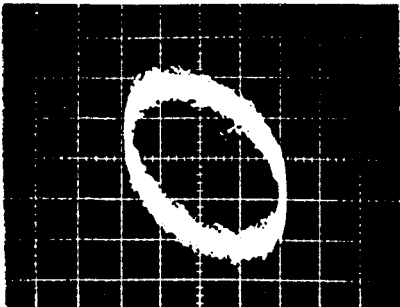
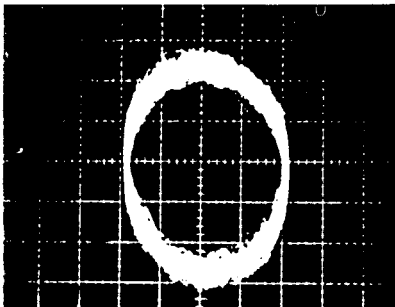


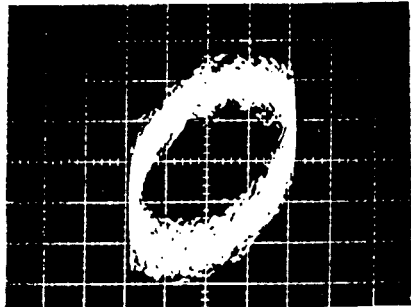
Fig. 10-13



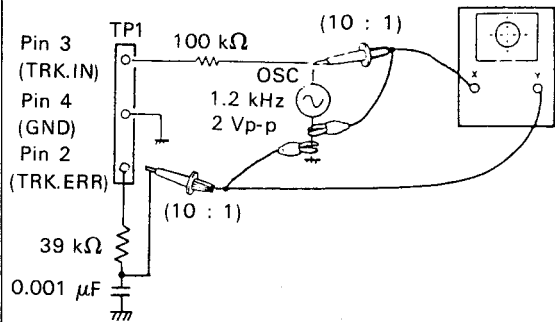
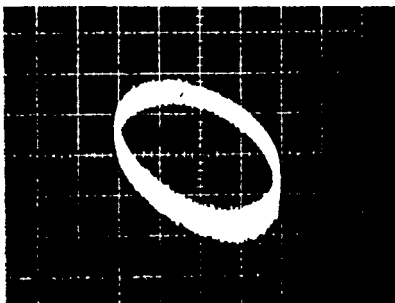
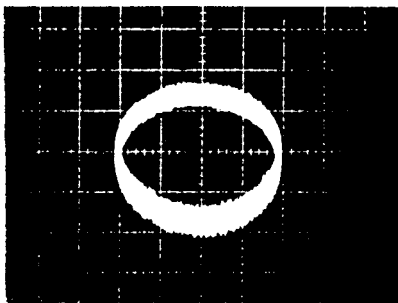
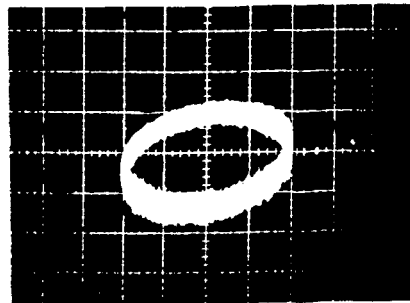
Gain overcompensated
Photo 10-10





Gain optimal
Photo 10-11



Gain undercompensated
Photo 10-12

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/ Adjustment specifications | Adjustment procedure |
|---|--|---|------------------|----------------------------|---|----------------------|
| | V | H | | | | |
| 9 | Tracking gain adjustment | | | | | |
| | CH1(X), CH2(Y) 50 mV/div, 5 mV/div (probe: 10:1) | X-axis TP1 Pin 3 (TRK.IN) Y-axis TP1 Pin 2 (TRK.OUT) | VR4 (TRK.GAN) | Phase difference of 90° | <ul style="list-style-type: none">With the oscillator power turned OFF, connect the oscilloscope and oscillator as shown in Fig. 10-14.Set the unit to test mode (see page 35).Press the TRACK FWD (▶▶), PLAY (▶) and PAUSE (⏸) keys sequentially to close the focus, spindle and tracking servos.Turn ON the power to the oscillator and set it to output a 1.2 kHz 2 Vp-p signal. <p>Note: Some oscillators discharge a DC voltage when turned on. It is therefore recommended that the oscillator be connected after it has been turned on.</p> <ul style="list-style-type: none">Adjust VR4 TRK.GAN (tracking gain) so that the Lissajous's figure becomes a horizontal circle on the oscilloscope (phase difference of 90°). <div></div> | |
| <div><p>Gain overcompensated Photo 10-13</p></div> <div><p>Gain optimal Photo 10-14</p></div> <div><p>Gain undercompensated Photo 10-15</p></div> | | | | | | |

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/ Adjustment specifications | Adjustment procedure |
|----------|-----------------------------------|---|------------------------|------------------|--|--|
| | V | H | | | | |
| 10 | VCO free run frequency adjustment | | | | | |
| | | | TP2 Pin 2 | VR8 (VCO.ADJ) | 4.275 ±0.025 MHz | <ul style="list-style-type: none">Set the unit to test mode (see page 35).Short the ASY and GND jumper with a  screwdriver or similar tool (see Fig. 10-15.).Connect a frequency counter capable of measuring frequencies of 10 MHz and above to TP2 Pin 2.Adjust VR8 VCO.ADJ (VCO free run adjustment) so that the frequency counter reading becomes 4.275±0.025 MHz. |
| 11 | Focus error check | | | | | |
| | | | TP1 Pin 6 (FCS.ERR) | | | <ul style="list-style-type: none">Set the unit to test mode (see page 35).Ground TP1 Pin 5 FCS.IN (focus in) to GND.Observe the waveform output by TP1 Pin 6 FCS.ERR (focus error) when the TRACK FWD () key is pressed. |

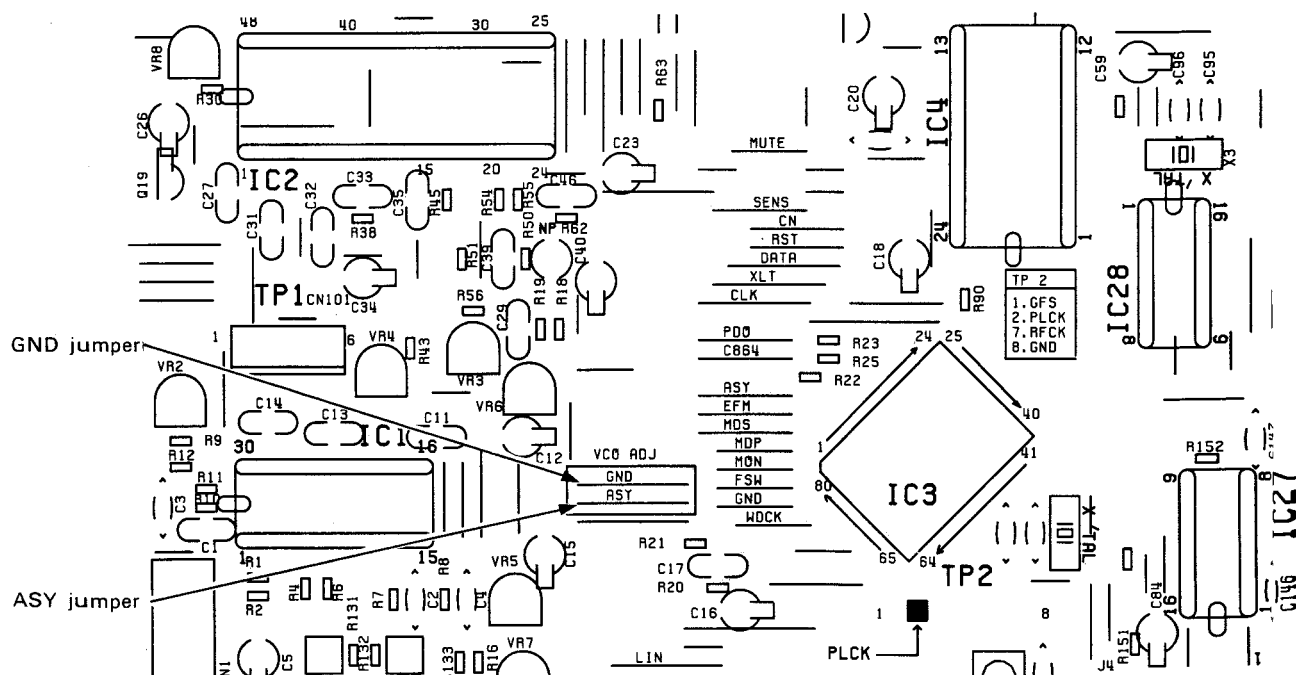
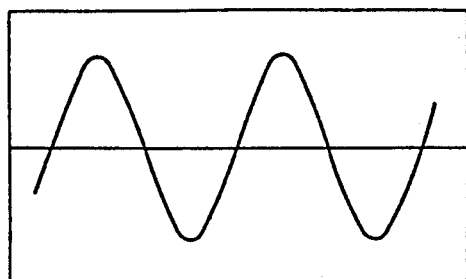


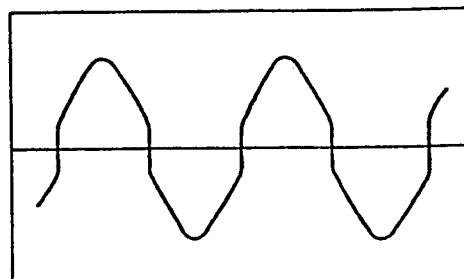
Fig. 10-15 Positions of ASY and GND jumpers

| Step No. | Oscilloscope Setting | | Test Points | Adjusting Points | Check items/ Adjustment specifications | Adjustment procedure |
|----------|----------------------|--------------|--------------------------------------|------------------|--|---|
| | V | H | | | | |
| 12 | MSB adjustment | | | | | |
| | 5mV/div | 0.2 msec/div | JA1 LINE OUT terminal (Lch) | VR10 | Sine wave | <ul style="list-style-type: none">Set the unit to normal play mode.Play back the 20th track (−60 dB, 1 kHz, L/Rch) of the test disc (YEDS-7). Connect an oscilloscope to L ch of the LINE OUT terminals and observe the audio output waveform.Adjust VR10 MSB.ADJ Rch (MSB adjust, right channel) so that the waveform on the oscilloscope becomes a sine wave.Perform the same adjustment for L-CH (VR9). |
| | | | JA1 LINE OUT terminal (Rch) | VR9 | Sine wave | |

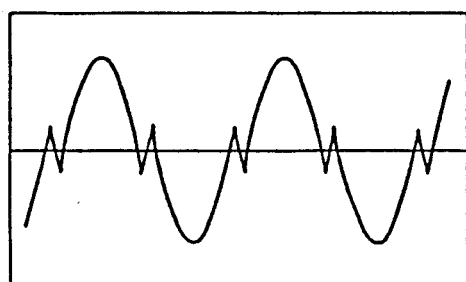
● Zero cross distortion waveform



OK



NG



NG

10. RÉGLAGE

On trouvera ci-après les réglages requis pour cet appareil. Ils doivent être exécutés dans l'ordre donné.

● AJUSTEMENTS

1. Ajustement de décalage d'erreur d'alignement, de décalage de mise au point et de décalage RF
2. Vérification de niveau RF
3. Vérification d'alimentation LD (diode laser)
4. Vérification de verrouillage de mise au point et de verrouillage d'axe
5. Ajustement de grille (1), (2)
6. Ajustement d'équilibre d'alignement
7. Ajustement tangentiel
8. Ajustement de gain de mise au point
9. Ajustement de gain d'alignement
10. Ajustement de fréquence libre VCO
11. Vérification d'erreur de mise au point
12. Ajustement MBS

● EQUIPEMENTS NECESSAIRES

1. Oscilloscope à double tracé
2. Wattmètre optique
3. Disque d'essai (YEDS-7)
4. Filtre d'ajustement de gain de boucle
5. Générateur de signal
6. Fréquencemètre
7. Autres équipements de mesure généralement utilisés

● A PROPOS DU MODE D'ESSAI

Tous les réglages doivent être effectués, l'appareil se trouvant en mode d'essai.

Activation et annulation du mode d'essai

- (1) Pour activer le mode d'essai, allumer (ON) l'interrupteur d'alimentation (S301) après avoir placé l'interrupteur de mode d'essai (S1) à la position ON.
- (2) Le mode d'essai est annulé en ramenant l'interrupteur d'alimentation sur OFF.

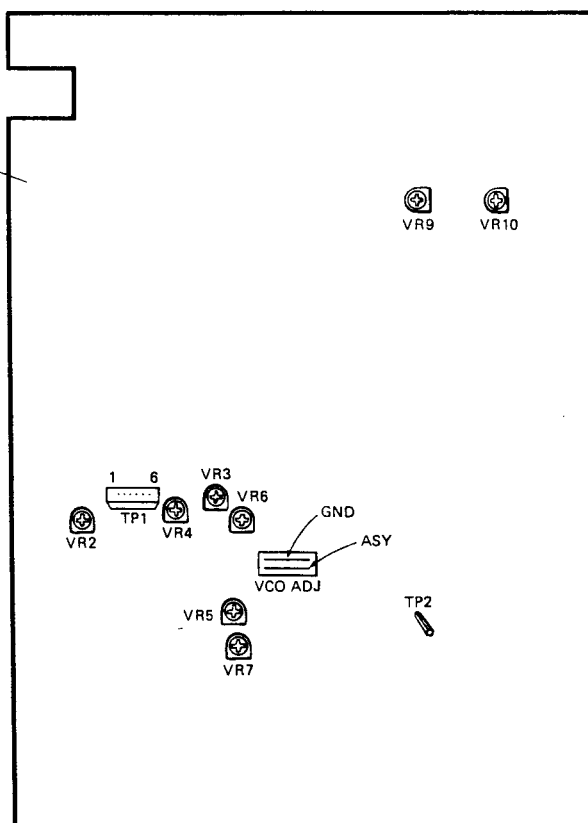
Les fonctions des touches du mode d'essai sont décrites au Tableau 10-1.

● DISPOSITIFS D'AJUSTEMENT ET NOMENCLATURE

- VR1: Alimentation laser
 VR2: Décalage RF (RF.OFS)
 VR3: Gain de mise au point (FCS.GAN)
 VR4: Gain d'alignement (TRK.GAN)
 VR5: Equilibrage d'alignement (TRK.BAL)
 VR6: Décalage de mise au point (FCS.OFS)
 VR7: Décalage d'alignement (TRK.OFS)
 VR8: Ajustement VCO (VCO.ADJ)
 VR9: Ajustement MSB Canal droit (MSB.ADJ-R)
 VR10: Ajustement MSB Canal gauche (MSB.ADJ-L)

Point de réglage

MONTAJE DEL TABLERO PRINCIPAL

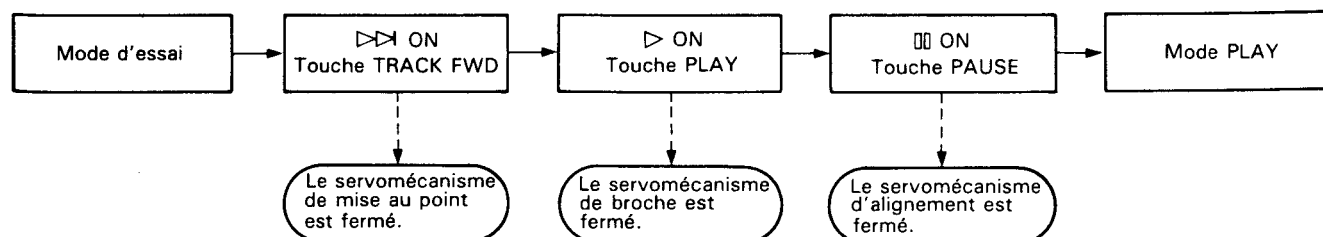


En mode d'essai, les servos doivent être individuellement fermés et ouverts. En conséquence, les servos doivent chacun être fermés dans la séquence correcte (séquence sérielle) afin de placer l'appareil en mode de lecture. Remarquer également que pendant le mode d'essai, l'appareil ne se placera pas en mode de lecture par une

pression sur la seule touche PAUSE (⏸).

Par exemple, pour passer du mode d'arrêt au mode de lecture, les touches de fonction doivent être actionnées dans l'ordre suivant:

* En mode d'essai, les servos doivent être opérés en séquence sérielle.

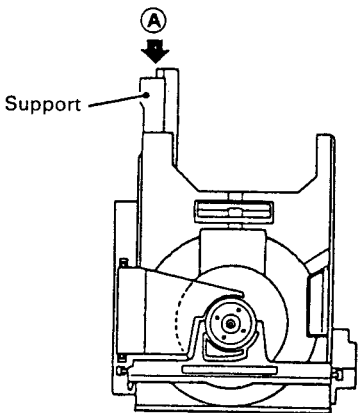
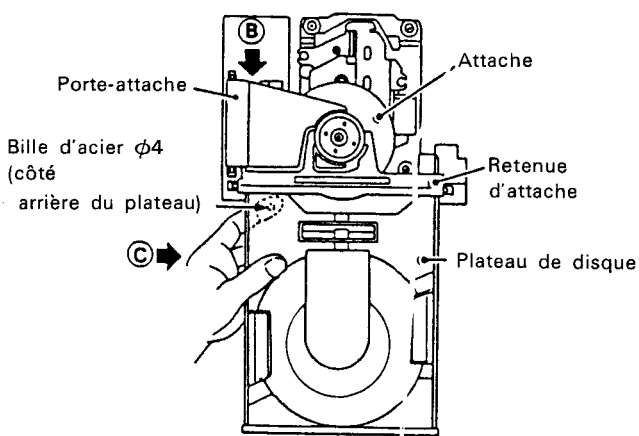


● FONCTIONS DES TOUCHES EN MODE D'ESSAI


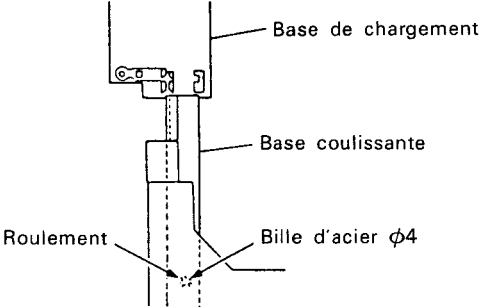
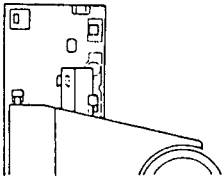
| Symbole | Nom de touche | Fonction en mode d'essai | Description |
|---------|-------------------|---|---|
| ▷ | TRACK FWD | Servo de mise au point fermé | Allume la diode laser et élève ou abaisse le dispositif de commande de mise au point pour fermer le servo de mise au point. |
| ▷ | PLAY | Servo d'axe fermé | Ferme le servo en mode CLV-A après cognement du moteur d'axe. |
| ⏸ | PAUSE | Fermeture/ouverture de servo d'alignement | Agit comme interrupteur articulé: ferme le servo d'alignement et active le mode de lecture quand poussé (à condition que les servos de mise au point et d'axe soient fermés), auquel moment le témoin PAUSE s'allume; ouvre le servo d'alignement à la pression suivante. |
| ◁ | MANUAL SEARCH REV | Inversion du chariot (déplacement vers l'intérieur) | Déplace rapidement (3 cm/sec) le chariot vers la plage la plus au centre. Prendre garde à ne pas déplacer trop loin, car il n'existe pas de dispositif de sécurité pour arrêter le chariot. |
| ▷ | MANUAL SEARCH FWD | Avance du chariot (déplacement vers l'extérieur) | Déplace rapidement (3 cm/sec) le chariot vers la plage la plus à l'extérieur. Prendre garde à ne pas déplacer trop loin, car il n'existe pas de dispositif de sécurité pour arrêter le chariot. |
| □ | STOP | Arrêt | Arrête tous les servos et ramène le système à son état initial. |
| ⏏ | OPEN/CLOSE | Ouverture/fermeture de plateau de disque | Ouvre et ferme le plateau du disque. Cependant, le capteur ne revient pas à la position de repos à OPEN et il reste stationnaire à CLOSE. |

Tableau 10-1.

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/ Spécifications de réglage | Procédure de réglage |
|------------|--|---|---|---|--|--|
| | V | H | | | | |
| 1 | Ajustement de décalage d'erreur d'alignement, de décalage de mise au point et de décalage RF | | | | | |
| | | | TP1 Broche 2 (TRK.ERR) TP1 Broche 6 (FCS.ERR) TP1 Broche 1 (RF OUTPUT) | VR5 (TRK. BAL) VR7 (TRK. OFS) VR6 (FCS.OFS) VR2 (RF.OFS) | Décalage d'erreur d'alignement 45° 0V±50 mV Décalage de mise au point 0V±50 mV Décalage RF 100 mV±50 mV | <ul style="list-style-type: none">Placer l'appareil en mode d'essai (voir page 50).Régler VR5 TRK.BAL (équilibrage d'alignement) à la position environ à 45° à la gauche du centre.Ajuster VR7 TRK.OFS (décalage d'alignement) de sorte que la tension TRK.ERR (erreur d'alignement) à TP1 broche 2 devienne 0V±50 mV.Ajuster VR6 FCS.OFS (décalage de mise au point) de sorte que la tension FCS.ERR (erreur de mise au point) à TP1 broche 6 devienne 0V±50 mV.Ajuster VR2 RF.OFS (décalage RF) de sorte que la tension de sortie RF à TP1 broche 1 devienne 100 mV±50 mV. <p>Remarque: Lors de l'ajustement du décalage d'erreur d'alignement, effectuer toujours "6. Ajustement d'équilibrage d'alignement".</p> |
| 2 | RF level adjustment | | | | | |
| | | | TP1 Broche 1 (RF OUTPUT) | VR1 (Alimentation laser) | 1.8V±0.1V | <ul style="list-style-type: none">Placer l'appareil en mode d'essai (voir page 50).Reproduire le disque d'essai, raccorder l'oscilloscope à TP1 broche 1 (sortie RF), et mesurer la tension c-c de la forme d'onde RF.Vérifier que le voltage est de 1.8V±0.1V. |
| 3 | Vérification d'alimentation LD (diode laser) | | | | | |
| | | | | | Inférieure à 0,13 mW | <ul style="list-style-type: none">Placer l'appareil en mode d'essai (voir page 50).Appuyer sur la touche TRACK FWD (→) pour allumer la diode laser.Placer le senseur du wattmètre optique directement au-dessus de l'objectif et confirmer que l'alimentation LD est inférieure à 0,13 mW. |

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/Spécifications de réglage | Procédure de réglage |
|------------|--|--------------------|--------------------------------|-------------------|---|--|
| | V | H | | | | |
| 4 | Vérification de verrouillage de mise au point et de verrouillage d'axe | | | | | |
| | V 0,5V/div | H 100 ms/div | TP1 Broche 1 (Sortie RF) | | Le signal RF est fourni Rotation avant (sens des aiguilles) | <ul style="list-style-type: none">• Installer le disque d'essai.• Placer l'appareil en mode d'essai (voir page 50).• Appuyer sur la touche MANUAL SEARCH FWD (▷▷) pour amener le cap-teur au centre du disque.• Observer la sortie (sortie RF) de TP1 broche sur l'oscilloscope. Confirmer que le signal haute fréquence est fourni après une pression sur la touche TRACK FWD (▷▷).• Appuyer sur la touche PLAY (▷) et confirmer que le disque tourne à vitesse constante (env. 300 tr/mn près du centre du disque) dans le sens avant (sens des aiguilles); s'assurer que le disque ne tourne pas trop vite ou tourne dans le sens contraire des aiguilles. |
| 5 | Ajustement de grille (1) | | | | | |
| |  <p>Fig. 10-1</p>  <p>Fig. 10-2</p> | | | | | <p>Retirer le disque du plateau avant de commencer cet ajustement.</p> <ul style="list-style-type: none">• Retrait du plateau de disque <ol style="list-style-type: none">1. Appuyer sur le bord arrière du support, à l'endroit marqué A sur la Fig. 10-1, tout en retirant le plateau de disque vers la position où il tient, comme illustré sur la Fig. 10-2. <p>(*1) Lorsque la section arrière du support (flèche A) est enfoncée, l'attache de disque est relâchée en premier. Pour faire glisser le plateau de disque entièrement vers l'extérieur, continuer à appuyer après le relâchement de l'attache.</p> <ol style="list-style-type: none">2. Tout en tirant le porte-attache B (voir Fig. 10-2) vers le haut de la main droite, tenir le plateau comme indiqué par C de la main gauche et le tirer vers l'extérieur. Prendre garde à ne pas laisser tomber la bille d'acier $\phi 4$ (il est conseillé de maintenir la bille en place avec l'index a uche tout en extrayant le plateau). |

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| N d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/ Spécifications de réglage | Procédure de réglage |
|--|---------------------------|----------|------------------------------|--|---|--|
| | V | H | | | | |
| | 0,5V/div | 5 ms/div | TP1 Broche 2 (TRK.ERR) | Vis d'ajustement de grille Vis d'ajustement de grille | Point nul Amplitude maximale | <ul style="list-style-type: none"> • Tourner la vis d'ajustement de grille à l'aide du tournevis  pour trouver le point nul (voir Photo 10-1). • Tourner ensuite lentement la vis dans le sens inverse des aiguilles d'une montre et ajuster au point où la forme d'onde (signal d'erreur d'alignement) arrive en premier à son amplitude maximale (voir Photo 10-3). <p>Remarque: Eviter d'appliquer une pression au tournevis tout en ajustant la vis pour ne pas déplacer le capteur vers l'intérieur, rendant l'ajustement plus difficile.</p> <ul style="list-style-type: none"> • En dernier lieu, retirer le filtre passe-bas et confirmer que la tension c-c du signal d'erreur d'alignement ne varie pas trop quand le capteur est déplacé aux première et dernière plages du disque. Si les niveaux divergent de $\pm 10\%$ ou davantage, réajuster le point d'amplitude d'erreur maximale en agissant sur la vis d'ajustement de grille. |
|  <p>Base de chargement</p> <p>Base coulissante</p> <p>Roulement</p> <p>Bille d'acier $\phi 4$</p> <p>Fig. 10-7</p>  <p>Fig. 10-8</p> | | | | | | <p>Remonter le plateau du disque selon la procédure ci-après après avoir terminé l'ajustement de grille.</p> <ol style="list-style-type: none"> 1. Retirer le disque et l'entretoise. 2. Tout en levant le porte-attache (marqué par B) sur la Fig. 10-2) de la main droite, tenir le plateau de la main gauche, comme illustré par C et déplacer la base coulissante dans les armatures en résine dure sur la base de charge comme indiqué sur la Fig. 10-7 pour réinsérer le plateau du disque. (A ce moment, prendre soin de tenir la bille d'acier $\phi 4$ en place avec l'index de la main droite.) (Veiller également à ce que le panneau avant ne soit pas endommagé par le roulement de la base coulissante au niveau de la section la bille d'acier $\phi 4$ entrant en contact avec le panneau.) 3. Insérer la base coulissante de sorte qu'elle s'engage dans les deux armatures en résine dure à l'arrière de la base de chargement (voir Fig. 10-8). 4. Insérer à fond le plateau. |

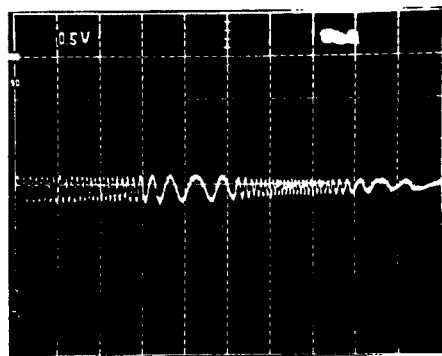


Photo 10-1 Point nul

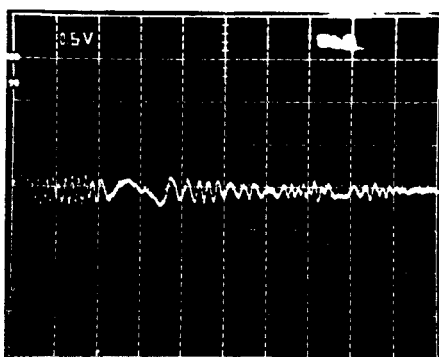


Photo 10-2 Ceci n'est pas la forme d'onde du point nul

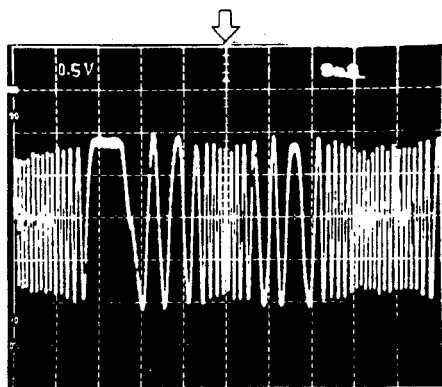
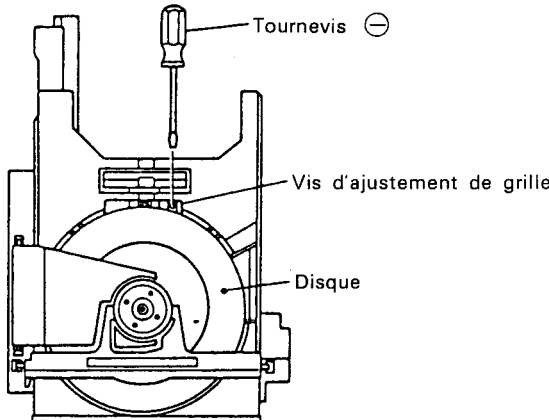
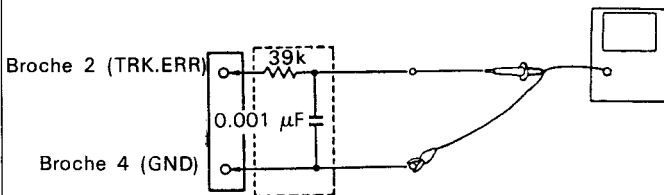



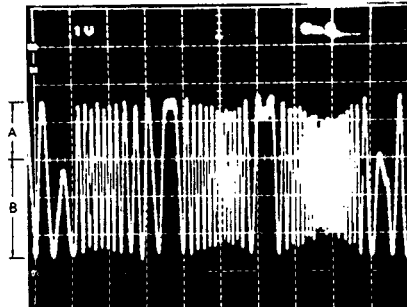
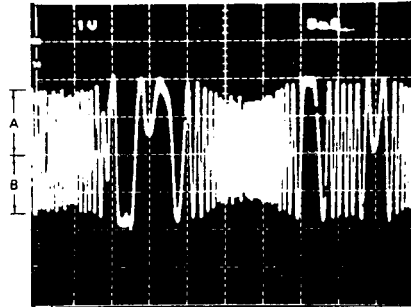
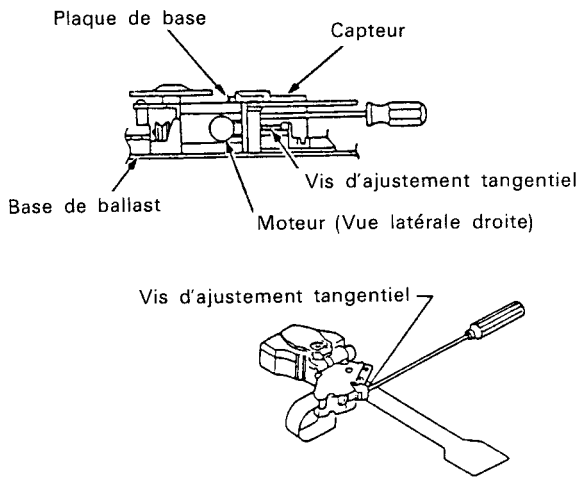
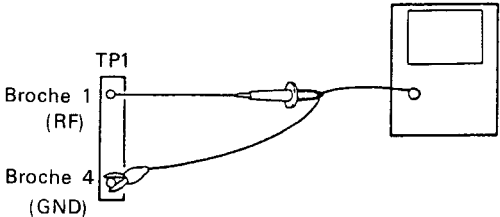
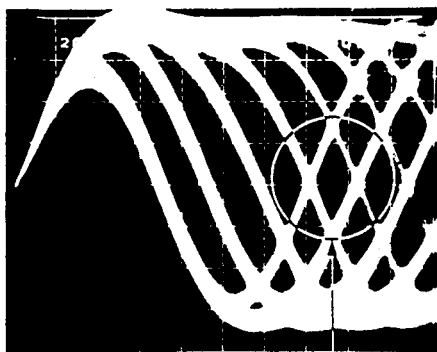


Photo 10-3 Amplitude maximale

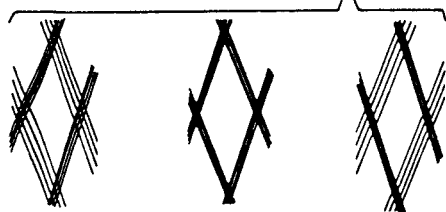
| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/Spécifications de réglage | Procédure de réglage | | | | | | | | | | |
|------------|---|------------------------------|----------------|--------------------|--|----------------------|----------|------------------------------|--------|-----------|--|--|--|--------|--------------------|---|
| | V | H | | | | | | | | | | | | | | |
| 5 | Ajustement de grille (2) (utiliser un disque d'une durée d'enregistrement de 60 min. ou davantage) | | | | | | | | | | | | | | | |
| | <div><p>Fig. 10-9</p></div> <div><p>Fig. 10-10</p></div> <div><table><tr><td>0,5V/div</td><td>5 ms/div</td><td>TP1 Broche 2 (TRK.ERR)</td><td>Grille</td><td>Point nul</td></tr><tr><td></td><td></td><td></td><td>Grille</td><td>Amplitude maximale</td></tr></table></div> | | | | | 0,5V/div | 5 ms/div | TP1 Broche 2 (TRK.ERR) | Grille | Point nul | | | | Grille | Amplitude maximale | <p>Remarque: Cet ajustement ne peut être effectué qu'avec un disque ayant des cavités jusqu'à R115 mm et non pas avec le disque d'essai (YEDS-7).</p> <ul style="list-style-type: none">● Régler l'appareil en mode d'essai (voir page 50).● Installer le disque d'essai, amener le capteur à la périphérie extérieure de sorte que l'orifice d'ajustement de grille de capteur soit visible de la surface de la cavité du disque ou par l'orifice du servomécanisme (voir Fig. 10-10).● Appuyer sur les touches TRACK FWD (➤) et PLAY (▶) en séquence pour fermer les servos de mise au point et d'axe (ne pas fermer le servo d'alignement).● Observer la forme d'onde de TP1 broche 2 TRK.ERR (erreur d'alignement) sur un oscilloscope, en insérant un filtre passe-bas de 4 kHz (voir Fig. 10-10). <p>Remarque: Agir avec précaution car une insertion forcée du tournevis  provoquera un flottement du capteur vers le haut.</p> <ul style="list-style-type: none">● Insérer un tournevis  dans l'orifice de grille, le tourner et rechercher le point nul (voir Photo 10-1).● Tourner ensuite lentement le tournevis  dans le sens inverse des aiguilles d'une montre à partir du point nul et ajuster jusqu'à ce que la forme d'onde (signal d'erreur d'alignement) atteigne l'amplitude maximale (voir Photo 10-3). <p>Remarque: Finalement, confirmer qu'il n'y a pas de fluctuation importante dans la tension c-c du signal d'erreur d'alignement (ne insérer le filtre passe-bas de coupure à 4 kHz) quand le capteur est déplacé vers la périphérie intérieure et vers la périphérie extérieure.</p> <p>Si l'on constate une différence supérieure à $\pm 10\%$ tourner à nouveau la vis d'ajustement de grille et ajuster le signal d'erreur d'alignement au point d'amplitude maximale.</p> |
| 0,5V/div | 5 ms/div | TP1 Broche 2 (TRK.ERR) | Grille | Point nul | | | | | | | | | | | | |
| | | | Grille | Amplitude maximale | | | | | | | | | | | | |

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/Spécifications de réglage | Procédure de réglage |
|------------|---|----------|------------------------------|-------------------|--|---|
| | V | H | | | | |
| 6 | Ajustement d'équilibre d'alignement | | | | | |
| | 0,5V/div | 5 ms/div | TP1 Broche 2 (TRK.ERR) | VR5 (TRK.BAL) | | <ul style="list-style-type: none">• Installer le disque d'essai.• Régler l'appareil en mode d'essai (voir page 50).• Appuyer sur la touche MANUAL SEARCH FWD (↗) pour amener le cap-teur près du centre du disque.• Appuyer sur les touches TRACK FWD (↗) et PLAY (▶) en séquence pour faire tourner le disque.• Observer la forme d'onde de TP1 broche 2 TRK.ERR (erreur d'alignement) sur l'oscilloscope et ajuster VR5 TRK.BAL (équilibrage d'alignement) pour éliminer les éléments CC du signal d'erreur d'alignement. |
| |  | | | | |  |
| | Photo 10-4 Eléments CC mêlés au signal | | | | | Photo 10-5 Eléments CC éliminés |
| 7 | Ajustement tangentiel | | | | | |
| |  | | | | | <ul style="list-style-type: none">• Régler l'appareil au mode d'essai (voir page 50).• Ouvrir le plateau et installer le disque d'essai.• Appuyer sur la touche MANUAL SEARCH FWD (↗) pour amener le cap-teur près du centre du disque.• Insérer une clé hexagonale dans la section de la vis d'ajustement tangentiel par l'arrière du mécanisme.• Refermer le plateau. <p>Remarque: Ne pas se servir d'une clé hexagonale en L, mais d'une clé, comme illustré sur la gauche. Si une clé hexagonale en L est à utiliser, le plateau doit être déposé avant d'effectuer l'ajustement (voir page 39 "5. Ajustement de grille (1)").</p> <ul style="list-style-type: none">• Appuyer sur les touches TRACK FWD (↗), PLAY (▶) et PAUSE en séquence pour fermer tous les servos (le témoin PAUSE s'allume). |
| | Fig. 10-11 | | | | | |

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/ Spécifications de réglage | Procédure de réglage |
|---------------|---------------------------|---------------|--------------------------------|-----------------------------------|---|--|
| | V | H | | | | |
| | | 200 ms/div | TP1 Broche 1 (Sortie RF) | Vis d'ajustement tangential | Mire la plus nette possible | <ul style="list-style-type: none"> Observer la forme d'onde de TP1 broche 1 (Sortie RF) sur l'oscilloscope et agir sur la vis d'ajustement tangential pour obtenir la mire la plus nette possible. Le point où la vis d'ajustement doit être amenée se trouve à environ mi-course entre les points où la mire est la plus floue quand la vis est tournée dans le sens des aiguilles d'une montre et dans le sens contraire. Quand toute la forme d'onde devient claire, se concentrer sur la netteté des lignes fines, formant le losange au centre de la mire (voir Photo 10-8). Ajuster jusqu'à ce que les lignes fines sur tous les quatre côtés du losange soient bien définies et denses.  <p>Fig. 10-12</p> <p>Remarque: Se servir d'une clé hexagonale pour lever légèrement le capteur pendant cet ajustement.</p> |



Partie à observer



Insatisfaisant

Ajustement
optimal

Insatisfaisant

Photo 10-6



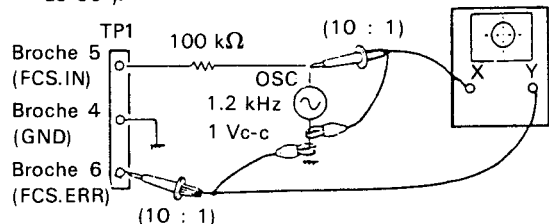
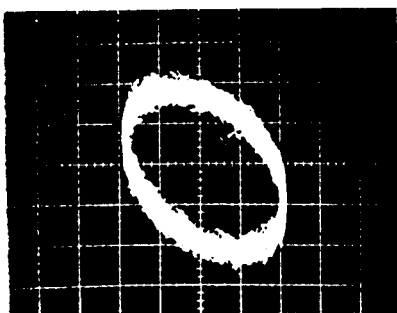
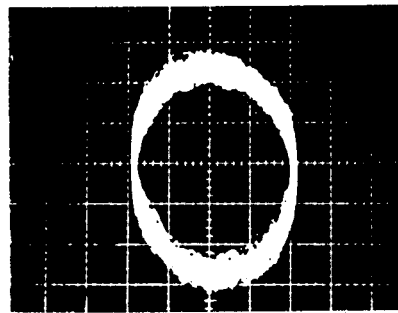
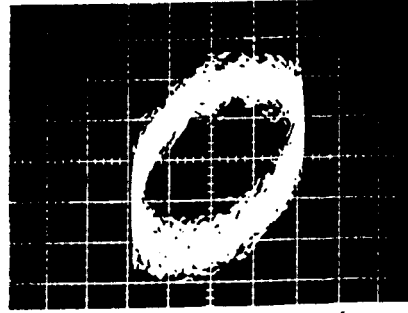
Photo 10-7

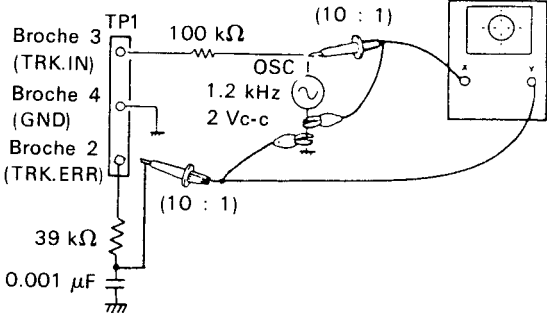
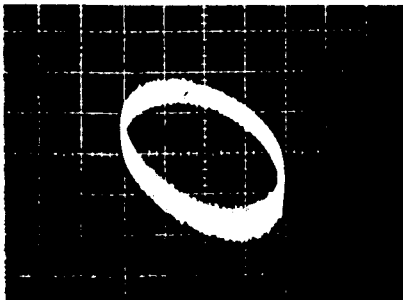
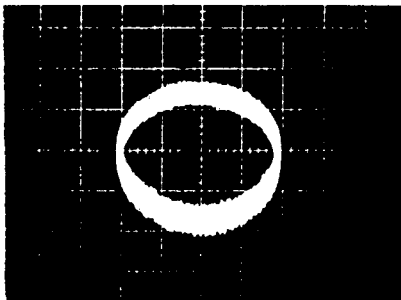
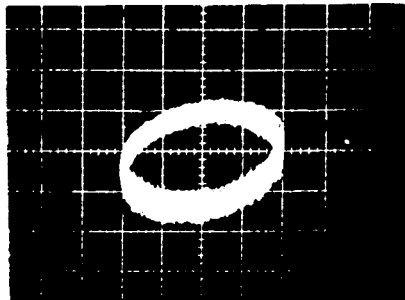


Photo 10-8



Photo 10-9

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/Spécifications de réglage | Procédure de réglage |
|---|--|---|------------------|----------------------------|---|----------------------|
| | V | H | | | | |
| 8 Ajustement de gain de mise au point | | | | | | |
| | CH1(X), CH2(Y) 20 mV/div 5 mV/div (sonde: 10:1) | Axe des X TP1 Broche 5 (FCS.IN) AXE des Y TP1 Broche 6 (FCS.ERR) | VR3 (FCS.GAN) | Différence de phase de 90° | <ul style="list-style-type: none">• L'alimentation de l'oscillateur étant coupée (OFF), raccorder l'oscilloscope et l'oscillateur, comme illustré sur la Fig. 10-13.• Régler l'appareil en mode d'essai (voir page 50).• Appuyer sur les touches TRACK FWD (→), PLAY (▶) et PAUSE (⏏) en séquence pour fermer les servos de mise au point, d'axe et d'alignement.• Mettre l'oscillateur sous tension (ON) et le régler pour fournir un signal de 1,2 kHz 1 Vc-c. <p>Remarque: Certains oscillateurs déchargent une tension CC lors de leur mise sous tension. Par conséquent, il est conseillé de connecter l'oscillateur après l'avoir mis sous tension.</p> <ul style="list-style-type: none">• Ajuster VR3 FCS.BAN (gain de mise au point) de sorte que la figure de Lissajou devienne un cercle horizontal sur l'oscilloscope (différence de phase de 90°). <div></div> <p style="text-align: center;">Fig. 10-13</p> | |
| <div><p style="text-align: center;">Gain sur-compensé Photo 10-10</p></div> <div><p style="text-align: center;">Gain optimal Photo 10-11</p></div> <div><p style="text-align: center;">Gain sous-compensé Photo 10-12</p></div> | | | | | | |

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/Spécifications de réglage | Procédure de réglage |
|--|--|---|----------------|----------------------------|---|----------------------|
| | V | H | | | | |
| 9 | Ajustement de gain d'alignement | | | | | |
| | CH1(X), CH2(Y) 50 mV/div, 5 mV/div (sonde: 10:1) | Axe des X TP1 Broche 3 (TRK.IN) AXE des Y TP1 Broche 2 (TRK.OUT) | VR4 (TRK.GAN) | Différence de phase de 90° | <ul style="list-style-type: none">• L'alimentation de l'oscillateur étant coupée (OFF), raccorder l'oscilloscope et l'oscillateur, comme illustré sur la Fig. 10-14.• Régler l'appareil en mode d'essai (voir page 50).• Appuyer sur les touches TRACK FWD (▶), PLAY (▷) et PAUSE (⏏) en séquence pour fermer les servos de mise au point, d'axe et d'alignement.• Mettre l'oscillateur sous tension (ON) et le régler pour fournir un signal de 1,2 kHz 2 Vc-c. Remarque: Certains oscillateurs déchargent une tension CC lors de leur mise sous tension. Par conséquent, il est conseillé de connecter l'oscillateur après l'avoir mis sous tension. <ul style="list-style-type: none">• Ajuster VR4 TRK.BAN (gain d'alignement) de sorte que la figure de Lissajou devienne un cercle horizontal sur l'oscilloscope (différence de phase de 90°).  | |
| <div><p>Gain sur-compensé Photo 10-13</p></div> <div><p>Gain optimal Photo 10-14</p></div> <div><p>Gain sous-compensé Photo 10-15</p></div> | | | | | | |

| N d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/ Spécifications de réglage | Procédure de réglage |
|--------------|--|---|------------------------------|----------------------|---|--|
| | V | H | | | | |
| 10 | Ajustement de fréquence libre VCO | | | | | |
| | | | TP2 Broche 2 | VR8 (VCO.ADJ) | 4.275 ±0,025 MHz | <ul style="list-style-type: none">• Régler l'appareil en mode d'essai (voir page 50).• Court-circuiter les cavaliers de l'ensemble (ASY) et de masse (GND) à l'aide d'un tournevis \ominus ou d'un outil analogue (voir Fig. 10-15).• Raccorder un fréquencemètre capable de mesurer des fréquences de 10 MHz et au-delà, sur TP2 broche 2.• Ajuster VR8 VCO.ADJ (ajustement libre VCO) de sorte que la lecture du fréquencemètre devienne 4.275 ±0,025 MHz. |
| 11 | Vérification d'erreur de mise au point | | | | | |
| | | | TP1 Broche 6 (FCS.ERR) | | | <ul style="list-style-type: none">• Régler l'appareil en mode d'essai (voir page 50)• Mettre TP1 broche 5 FCS.IN (gain de mise au point) à la masse (GND).• Observer la forme d'onde de TP1 broche 6 FCS.ERR (erreur de mise au point) quand la touche TRACK FWD (\rightarrow) est actionnée. |

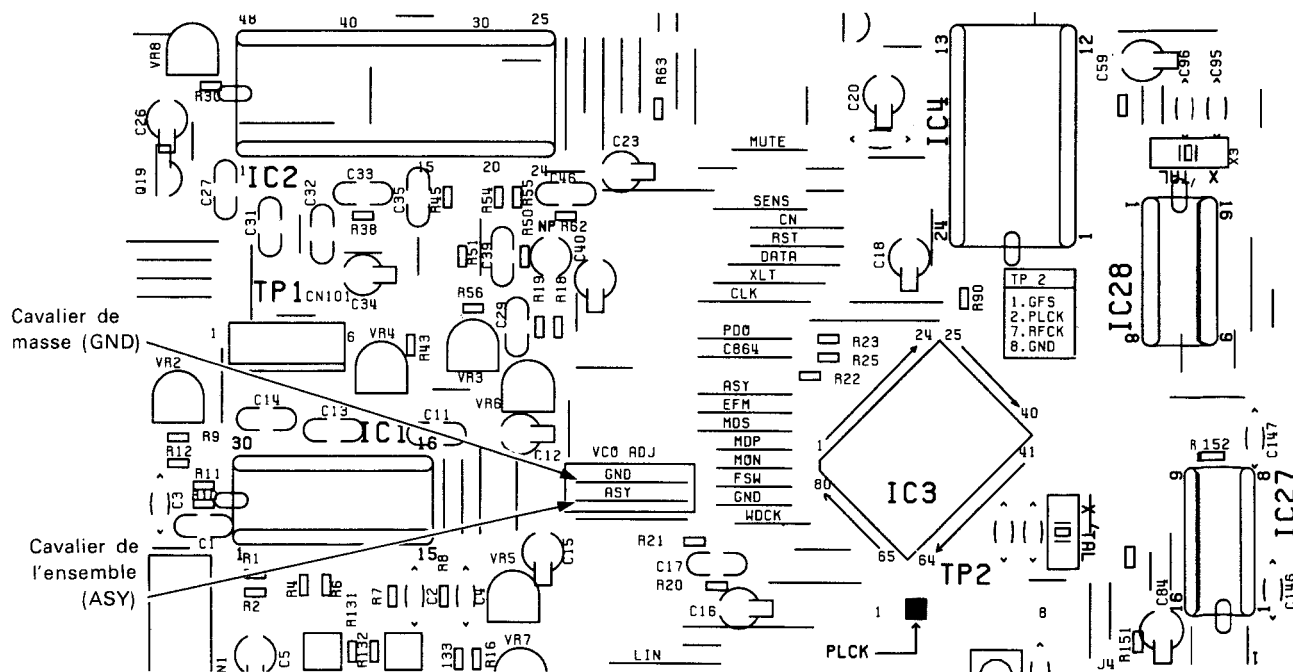
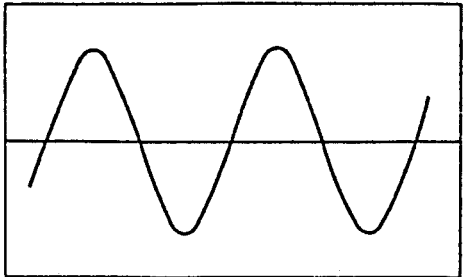


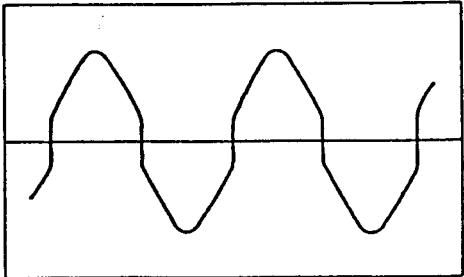
Fig. 10-15 Position des cavaliers ASY et GND

| N° d'étape | Réglage d'oscilloscope | | Points d'essai | Points de réglage | Postes de contrôle/Spécifications de réglage | Procédure de réglage |
|------------|------------------------|------------|--|-------------------|--|--|
| | V | H | | | | |
| 12 | Ajustement MBS | | | | | |
| | 5 mV/div | 0.2 ms/div | Borne de sortie de ligne (LINE OUT) JA1 (canal gauche) | VR10 | Onde sinusoïdale | <ul style="list-style-type: none">● Régler l'appareil en mode d'essai (voir page 36).● Reproduire la 20ème plage (−60 dB, 1 kHz, canal G/D) du disque d'essai (YEDS-7). Raccorder un oscilloscope au canal gauche des bornes de sortie de ligne (LINE OUT) et observer la forme d'onde de sortie audio.● Ajuster VR10 MSB.ADJ Rch (ajustement MBS, canal droit) pour que la forme d'onde sur l'oscilloscope devienne sinusoïdale.● Effectuer le même ajustement pour le canal gauche (VR9). |
| | | | Borne de sortie de ligne (LINE OUT) JA1 (canal droit) | VR9 | Onde sinusoïdale | |

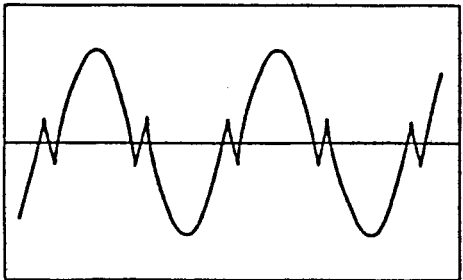
● Forme d'onde de ligne horizontale nulle



OK



NG



NG

10. AJUSTE

A continuación se ofrecen los ajustes para esta unidad.
Los ajustes deberán realizarse en el orden indicado

● AJUSTES

1. Ajuste de la desviación del error de seguimiento, desviación de enfoque y desviación de RF.
2. Ajuste del nivel de RF
3. Comprobación de la energía del diodo láser (LD)
4. Comprobación de la sincronización del foco y del eje
5. Ajuste de retícula
6. Ajuste del equilibrio de seguimiento
7. Ajuste tangencial
8. Ajuste de la ganancia de enfoque
9. Ajuste de la ganancia de seguimiento
10. Ajuste de la frecuencia de oscilación libre del oscilador controlado por tensión (VCO)
11. Comprobación del error de enfoque
12. Ajuste de MSB

● EQUIPOS REQUERIDOS

1. Osciloscopio de doble traza
2. Medidor de energía óptica
3. Disco de prueba (YEDS-7)
4. Filtro de ajuste de ganancia de bucle
5. Generador de señales
6. Frecuencímetro
7. Otros equipos de medición de uso normal

● ACERCA DEL MODO DE PRUEBA

Todos los ajustes deberán efectuarse con la unidad en el modo de prueba.

Activación y desactivación del modo de prueba

- (1) Para activar el modo de prueba, ponga en ON el interruptor de la alimentación (S301) con el interruptor de modo de prueba (S1) en la posición ON.
- (2) El modo de prueba se desactiva poniendo el interruptor de la alimentación en OFF.

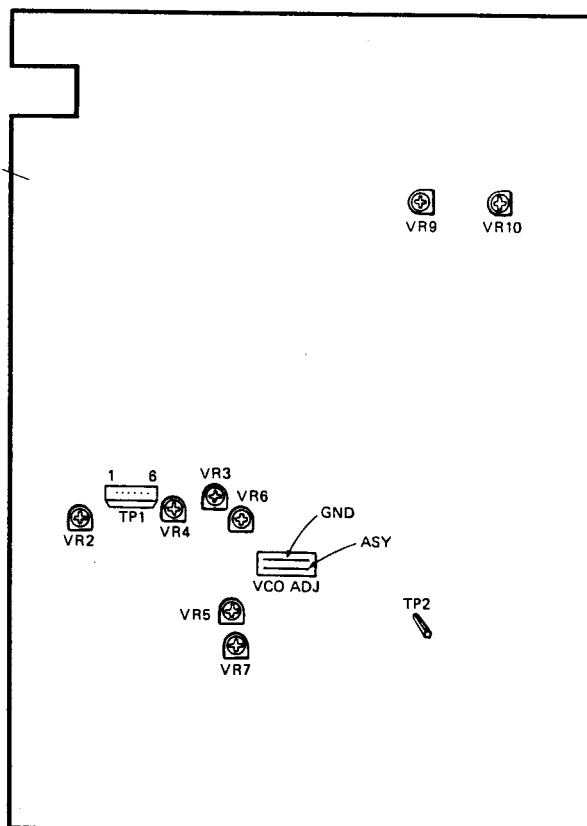
Las funciones de las teclas en el modo de prueba se describen en la tabla 10-1.

● RESISTORES VARIABLES (VR) DE AJUSTE Y SUS NOMBRES

- VR1: Energía láserica
 VR2: Desviación de RF (RF.OFS)
 VR3: Ganancia de enfoque (FCS.GAN)
 VR4: Ganancia de seguimiento (TRK.GAN)
 VR5: Equilibrio de seguimiento (TRK.BAL)
 VR6: Desviación de enfoque (FCS.OFS)
 VR7: Desviación de seguimiento (TRK.OFS)
 VR8: Ajuste del VCO (VCO.ADJ)
 VR9: Ajuste de MSB del canal derecho (MSB.ADJ-R)
 VR10: Ajuste de MSB del canal izquierdo (MSB.ADJ-L)

Punto de ajuste

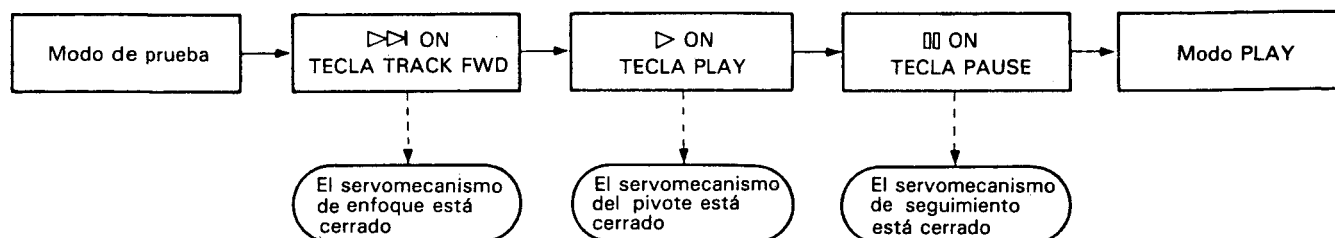
ENSEMBLE DE PLAQUETTE PRINCIPALE



En el modo de prueba, los servos deberán cerrarse y abrirse individualmente. Por consiguiente, los servos deberán cerrarse en la secuencia apropiada (secuencia en serie) a fin de poner el aparato en el modo de reproducción. Tenga en cuenta además que durante el modo de prueba el aparato no entrará en el modo de reproducción cuando haya presionado la tecla PAUSE (■).

Por ejemplo, para cambiar del modo de parada al de reproducción tendrá que presionar las teclas de función en el orden siguiente:

* En el modo de prueba, los servos deberán operarse en la secuencia en serie

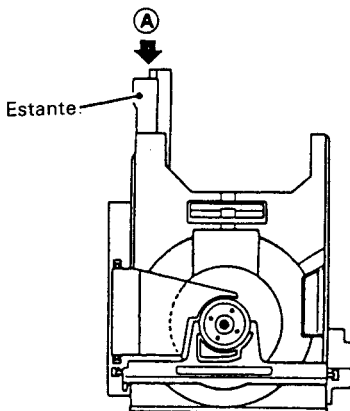
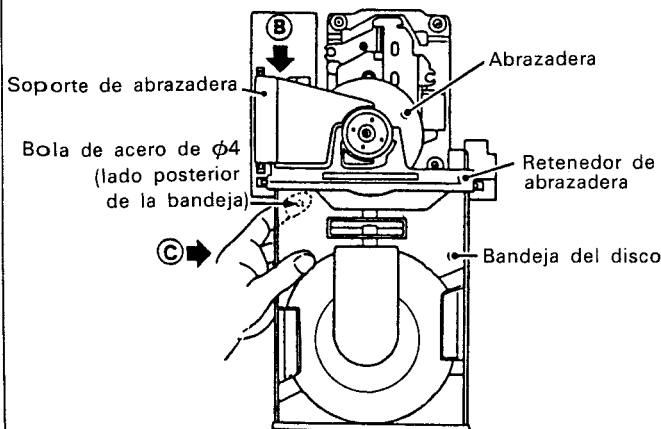


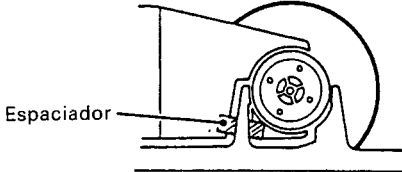

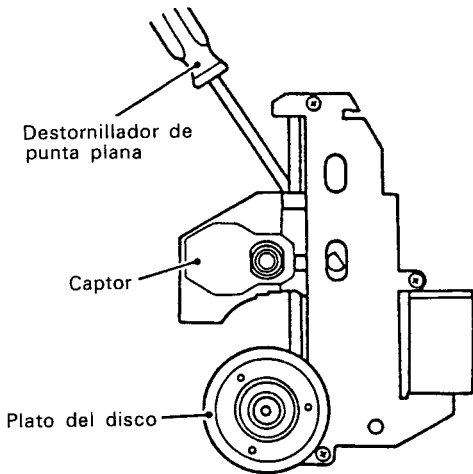
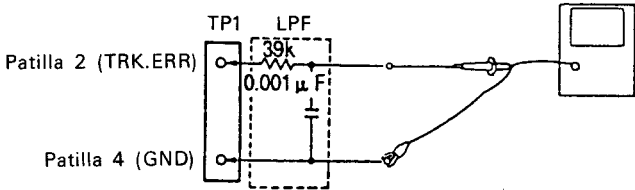
● FUNCIONES DE LAS TECLAS EN EL MODO DE PRUEBA

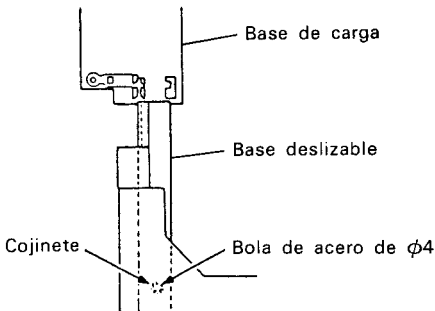
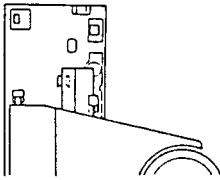
| Símbolo | Nombre de la tecla | Función en el modo de prueba | Descripción |
|---------|--------------------|--|---|
| ▷ | TRACK FWD | Cierre del servo de enfoque | Activa el diodo láser y eleva y hace descender el actuador de enfoque para cerrar el servo de enfoque. |
| ▷ | PLAY | Cierre del servo del eje | Cierra el servo en el modo CLV-A después de impulsar el motor del eje. |
| ■ | PAUSE | Cierre/apertura del servo de seguimiento | Actúa como conmutador: cierra el servo de seguimiento y activa el modo de reproducción cuando se presiona (suponiendo que los servos de enfoque y del eje estén cerrados), momento en el que se encenderá el indicador PAUSE; y abre el servo de seguimiento cuando vuelve a presionarse. |
| ◁ | MANUAL SEARCH REV | Retroceso del carro (se mueve hacia adentro) | Mueve el carro rápidamente (3 cm/s) hacia la pista más interior. Tenga cuidado para no moverlo demasiado ya que no hay dispositivo de seguridad para parar el carro. |
| ▷ | MANUAL SEARCH FWD | Avance del carro (mueve el carro hacia afuera) | Mueve el carro rápidamente (3 cm/s) hacia la pista más exterior. tenga cuidado para no moverlo demasiado ya que no hay dispositivo de seguridad para parar el carro. |
| □ | STOP | Parada | Para todos los servos y devuelve el sistema a su estado inicial. |
| ▲ | OPEN/CLOSE | Apertura/cierre de la bandeja del disco | Abre y cierra la bandeja del disco. Sin embargo, el captor no regresa a su soporte en OPEN y permanece estacionario en CLOSE. |

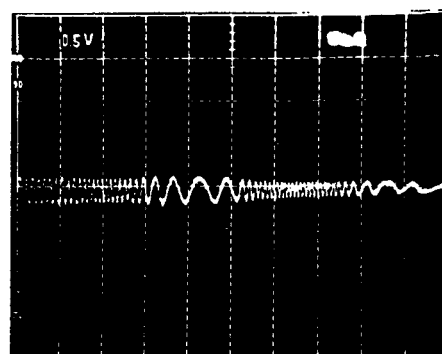
Tabla 10-1

| N.º de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|-------------|--|---|---|---|---|--|
| | V | H | | | | |
| 1 | Ajuste de la desviación del error de seguimiento, desviación de enfoque y desviación de RF | | | | | |
| | | | TP1 Patilla 2 (TRK.ERR) TP1 Patilla 6 (FCS.ERR) TP1 Patilla 1 (RF. OUTPUT) | VR5 (TRK.BAL) VR7 (TRK.OFS) VR6 (FCS.OFS) VR2 (RF.OFS) | Desviación del error de seguimiento 45° 0V±50 mV Desviación de enfoque 0V±50hHmV Desviación de RF 100 mV±50 mV | <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Ponga VR5 TRK.BAL (equilibrio de seguimiento) en una posición aproximadamente 45° a la izquierda del centro.• Ajuste VR7 TRK.OFS (desviación de seguimiento) de forma que la tensión TRK.ERR (error de seguimiento) en la patilla 2 de TP1 sea de 0V±50 mV.• Ajuste VR6 FCS.OFS (desviación de enfoque) de forma que la tensión de FCS.ERR (error de enfoque) en la patilla 6 de TP1 sea de 0V±50 mV.• Ajuste VR2 RF.OFS (desviación de RF) de forma que la tensión de salida de RF en la patilla 1 de TP1 sea de 100 mV±50 mV. <p>Nota: Cuando ajuste la desviación del error de seguimiento, realice siempre "6. Ajuste del equilibrio de seguimiento."</p> |
| 2 | Ajuste del nivel de RF | | | | | |
| | | | TP1 Patilla 1 (RF OUTPUT) | VR1 (Energía láserica) | 1.8V±0.1V | <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Reproduzca el disco de prueba, conecte el osciloscopio en la patilla 1 de TP1 (salida de RF) y mida la tensión P-P de la forma de onda de RF.• Compruebe si la tensión es de 1.8V±0.1V. |
| 3 | Comprobación de la energía del diodo láser (LD) | | | | | |
| | | | | | Menos de 0,13 mW | <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Presione la tecla TRACK FWD (→) para activar el diodo láser (LD).• Coloque el sensor del medidor de energía óptica directamente sobre el objetivo y confirme si la energía del LD es inferior a 0,13 mW. |

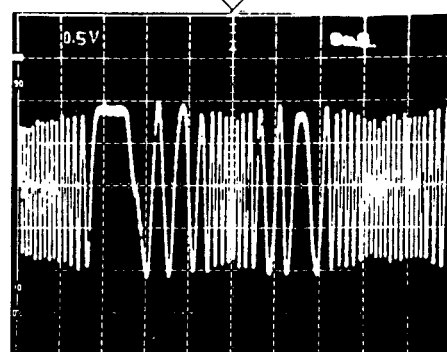
| N.º de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|-------------|---|----------------------|------------------------------------|--|--|---|
| | V | H | | | | |
| 4 | Comprobación de la sincronización del foco y del eje | | | | | |
| | V 0,5V/div | H 100 mseg/div | TP1 Patilla 1 (salida de RF) | La señal de RF sale Giro en sentido de avance (hacia la derecha) | | <ul style="list-style-type: none">• Instale el disco de prueba.• Ponga la unidad en el modo de prueba (consulte la página 65).• Presione la tecla MANUAL SEARCH FWD (▷) para mover el captor hacia el centro del disco.• Observe la salida de la patilla 1 de TP1 (salida de RF) en el osciloscopio. Compruebe si la señal de RF sale después de presionar la tecla TRACK FWD (▷).• Presione la tecla (PLAY) y compruebe si el disco gira a una velocidad constante (aproximadamente 300 r.p.m. cerca del centro del disco) en sentido de avance (hacia la derecha); cerciórese de que el disco no gire demasiado rápido ni hacia la izquierda. |
| 5 | Ajuste de retícula (1) | | | | | |
| |  <p>Figura 10-1.</p> | | | | <p>Antes de hacer este ajuste, extraiga la bandeja del disco.</p> <ul style="list-style-type: none">• Extracción de la bandeja del disco. | |
| |  <p>Figura 10-2.</p> | | | | <ol style="list-style-type: none">1. Presione el borde posterior del bastidor, marcado con (A) en la figura 10-1., mientras tira de la bandeja del disco hacia afuera hasta la posición en la que agarre, mostrada en la figura 10-2.(*1) Cuando presione la sección trasera del bastidor (flecha (A)) empieza a liberarse la abrazadera del disco. Para deslizar completamente hacia afuera la bandeja del disco, continúe presionando hasta que se libere la abrazadera.2. Tirando del soporte de abrazadera (B) (consulte la figura 10-2.) hacia arriba con la mano derecha, sujete la bandeja como se indica en (C) con la mano izquierda y tire de ella hacia afuera. Tenga cuidado de que no caiga la bola de acero de $\phi 4$ (recomendamos sujetar la bola en su lugar con el dedo índice de la mano izquierda al sacar la bandeja). | |

| N. de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|------------------|---------------------------|---|---------------------|--|--|-------------------------|
| | V | H | | | | |
| | | | |  <p>Espaciador</p> <p>Figura 10-3.</p> | | |
| | | | |  <p>Retenedor de abrazadera</p> <p>Abrazadera</p> <p>Figura 10-4.</p> | | |
| | | | |  <p>Destornillador de punta plana</p> <p>Captor</p> <p>Plato del disco</p> <p>Figura 10-5.</p> | <ul style="list-style-type: none"> • Ponga la unidad en el modo de prueba (consulte la página 65). • Presione la tecla MANUAL SEARCH FWD (▷) para mover el captor hasta cerca de lo que sería el centro del disco. Coloque el captor de forma que su tornillo de ajuste de retícula se vea a través del orificio alargado situado al lado del motor del eje de la placa base del mecanismo de servos. • Como se muestra en la figura 10-5., inserte un destornillador (ranurado de 2 mm) desde la parte posterior del mecanismo y compruebe si puede girar el tornillo de ajuste de retícula. • Instale el disco de prueba; asegúrese de insertar un separador de 3 — 5 mm (si no dispone de separador, emplee una llave hexagonal) entre el sujetador de abrazadera y el retenedor de abrazadera, como se muestra en la figura 10-3. • Confirme que la abrazadera y el retenedor de la misma no estén en contacto entre sí (figura 10-4.). • Presione secuencialmente las teclas TRACK FWD (▷) y PLAY (▷) para cerrar los servos de enfoque y del eje (no cierre el servo de seguimiento). • Inserte un filtro de paso bajo de 4 kHz de corte entre las patillas 2 de TP1 (TRK.ERR) y la patilla 4 (GND) como se muestra en la figura 10-6., y observe la salida de la forma de onda de la patilla 2 de TP1 TRK.ERR (error de seguimiento) en el osciloscopio. | |
| | | | |  <p>TP1</p> <p>LPF</p> <p>39k</p> <p>0.001 µF</p> <p>Patilla 2 (TRK.ERR)</p> <p>Patilla 4 (GND)</p> <p>Figura 10-6.</p> | | |

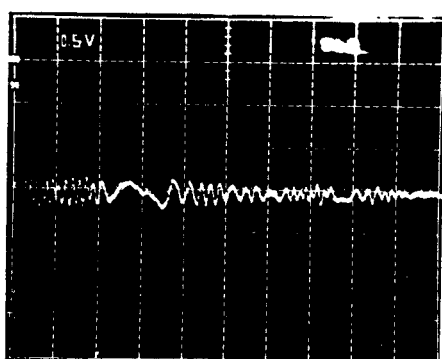
| N. de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/especificaciones de ajuste | Procedimiento de ajuste |
|--|------------------------|------------|--------------------------------|--|---|---|
| | V | H | | | | |
| | 0,5V/div | 5 mseg/div | TP1 Patilla 2 (TRK. ERR) | Tornillo de ajuste de retícula Tornillo de ajuste de retícula | Punto nulo Amplitud máxima | <ul style="list-style-type: none"> Gire el tornillo de ajuste de retícula con el destornillador de punta plana para encontrar el punto nulo (consulte la fotografía 10-1.). A continuación, gire lentamente el tornillo hacia la izquierda y ajuste hasta llegar al punto en que la forma de onda (señal de error de seguimiento) alcance por primera vez su amplitud máxima (consulte la fotografía 10-3.). <p>Nota: Evite presionar sobre el destornillador mientras ajusta el tornillo. De lo contrario, el captor se moverá hacia adentro haciendo más difícil el ajuste.</p> <ul style="list-style-type: none"> Para finalizar, quite el filtro de paso bajo y confirme que la tensión p-p de la señal de error de seguimiento no cambie considerablemente cuando mueva el fonocaptor hacia las pilas más interiores y exteriores del disco. <p>Si el nivel cambia en $\pm 10\%$ o más, vuelva a ajustar el punto de amplitud máxima de error girando el tornillo de ajuste de retícula.</p> |
|  <p>Figura 10-7.</p>  <p>Figura 10-8.</p> | | | | | | <p>Una vez finalizado el ajuste de retícula, vuelva a montar la bandeja del disco de acuerdo con el procedimiento siguiente:</p> <ol style="list-style-type: none"> Extraiga el disco y el separador. Levantando el sujetador de abrazadera (marcada con Ⓑ en la figura 10-2.) con la mano derecha, sujete la bandeja con la mano izquierda como se indica en Ⓒ y deslice la base deslizable en los acopladores de resina rígida de la base de carga como se muestra en la figura 10-7. para reinsertar la bandeja del disco. <p>En este momento, asegúrese de sujetar la bola de acero de $\phi 4$ en su lugar con el dedo índice de la mano izquierda.</p> <p>Además, tenga cuidado para no dañar el panel frontal con el cojinete de la base deslizable, en la sección de la bola de acero de $\phi 4$ que entra en contacto con el panel.</p> <ol style="list-style-type: none"> Inserte la base deslizable de forma que encaje en los dos acopladores de resina rígida de la parte posterior de la base de carga (consulte la figura 10-8.). Inserte completamente la bandeja del disco. |



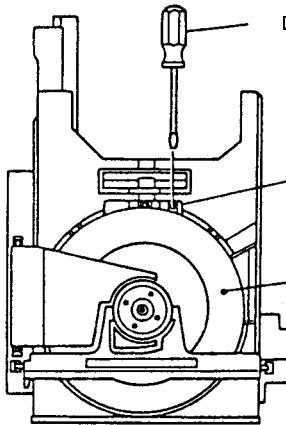
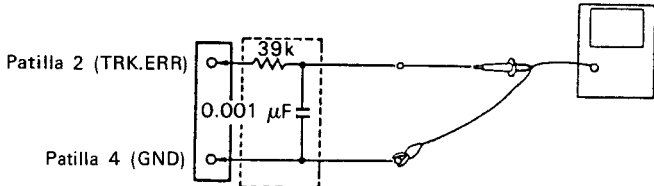
Fotografía 10-1. Punto nulo

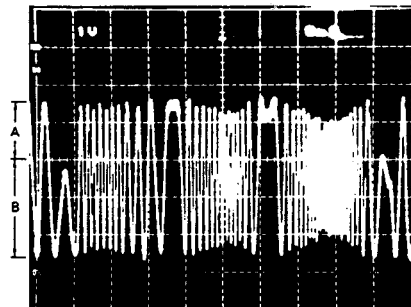
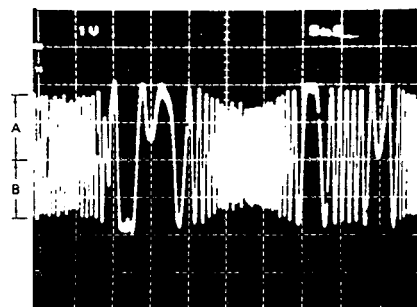
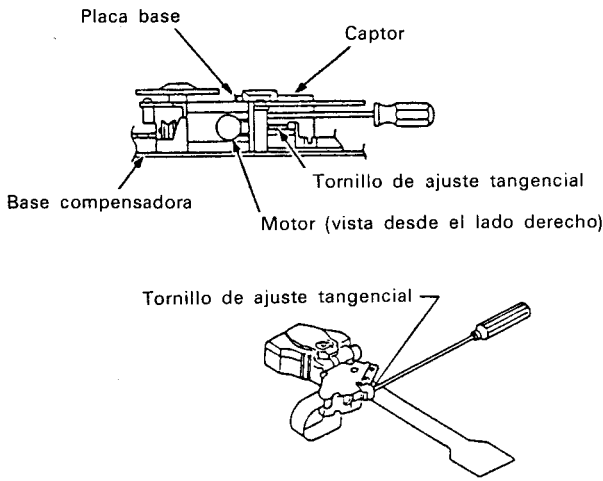


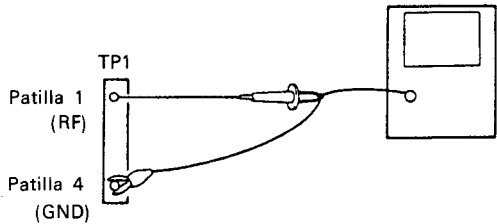
Fotografía 10-3. Amplitud máxima

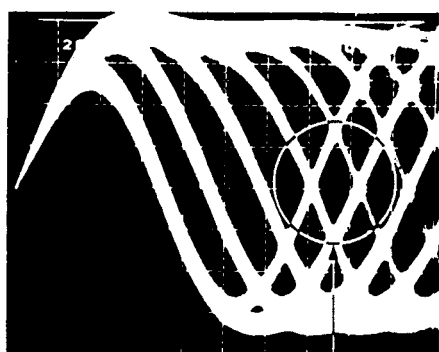


Fotografía 10-2. Esta no es la forma de onda de punto nulo

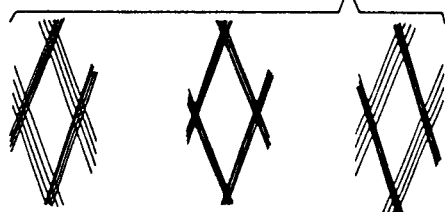
| N.º de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|-------------|---|------------|--------------------------------|--------------------------|--|--|
| | V | H | | | | |
| 5 | Ajuste de retícula (2) (empleando discos con una duración de reproducción de 60 minutos o más) | | | | | |
| | <div><p>Destornillador de punta plana</p><p>Tornillo de ajuste de retícula</p><p>Disco</p></div> <p>Figura 10-9.</p> <div><p>Patilla 2 (TRK.ERR)</p><p>39k</p><p>0.001 µF</p><p>Patilla 4 (GND)</p></div> <p>Figura 10-10.</p> | | | | | <p>Nota: Este ajuste podrá realizarse solamente con un disco que tenga hoyos de hasta R115 mm, no con el disco de prueba (YEDS-7).</p> <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Instale el disco de prueba, desplace el captor hacia la pista exterior de forma que el orificio de ajuste de retícula del captor quede visible desde la superficie de hoyos del disco o a través del agujero del mecanismo de servos (consulte la figura 10-10.).• Presione las teclas TRACK FWD (▶▶) y PLAY (▶) en secuencia para cerrar los servos de enfoque y del eje (no cierre el servo de seguimiento).• Observe la salida de la forma de onda de TRK.ERR (error de seguimiento) de la patilla 2 de TP1 en un osciloscopio, insertando un filtro de paso bajo de 4 kHz (consulte la figura 10-10.). |
| | 0,5V/div | 5 mseg/div | TP1 Pastilla 2 (TRK.ERR) | Retícula Retícula | Punto nulo Amplitud máxima | <ul style="list-style-type: none">• Inserte un destornillador de punta plana en el agujero de retícula, gire el destornillador y encuentre el punto nulo (consulte la fotografía 10-1.).• A continuación, gire lentamente el destornillador de punta plana hacia la izquierda desde el punto nulo y ajuste hasta que la forma de onda (señal de error de seguimiento) alcance la máxima amplitud (consulte la fotografía 10-3.).• Ta: Tenga cuidado porque si inserta el destornillador de punta plana a la fuerza el captor se elevará.• Finalmente, confirme que no haya una gran fluctuación de la tensión p-p de la señal de error de seguimiento (no inserte el filtro de paso bajo de 4kHz de corte) cuando el captor se desplace hacia la pista más interior del disco. Si la diferencia es mayor del ±10%, gire de nuevo el tornillo de ajuste de retícula y ajuste la señal de error de seguimiento al punto de amplitud máximo. |

| N. de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|------------|---|------------|-------------------------------|------------------|--|--|
| | V | H | | | | |
| 6 | Ajuste del equilibrio de seguimiento | | | | | |
| | 0,5V/div | 5 mseg/div | TP1 Patilla 2 (TRK.ERR) | VR5 (TRK.BAL) | | <ul style="list-style-type: none">• Instale el disco de prueba• Ponga la unidad en el modo de prueba (consulte la página 65).• Presione la tecla MANUAL SEARCH FWD (⏩) para colocar el captor cerca del centro del disco.• Presione secuencialmente las teclas TRACK FWD (⏩) y PLAY (▶) para que gire el disco.• Observe la salida de la forma de onda de TRK.ERR (error de seguimiento) de la patilla 2 de TP1 en el osciloscopio y ajuste VR5 TRK.BAL (equilibrio de seguimiento) para eliminar los componentes de CC de la señal de error de seguimiento. |
| |  | | | | |  |
| | Fotografía 10-4. Elementos de CC mezclados en la señal | | | | | Fotografía 10-5. Elementos de CC eliminados |
| 7 | Ajuste tangencial | | | | | |
| |  | | | | | <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Abra la bandeja e instale el disco de prueba.• Presione la tecla MANUAL SEARCH FWD (⏩) para poner el captor cerca del centro del disco.• Inserte una llave hexagonal en la sección del tornillo de ajuste tangencial desde la parte posterior del mecanismo.• Cierre la bandeja. <p>Nota: No emplee una llave hexagonal en forma de L. Emplee una como la mostrada a la izquierda. Si emplea una llave hexagonal en forma de L tendrá que retirar la bandeja antes de realizar el ajuste (consulte la página 39, "5. Ajuste de retícula (1))."</p> <ul style="list-style-type: none">• Presione secuencialmente las teclas TRACK FWD (⏩), PLAY (▶) y PAUSE para cerrar todos los servos (el indicador de pausa se encenderá). |

| N. de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítems de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|------------------|---------------------------|-----------------|---------------------------------------|-------------------------------------|--|---|
| | V | H | | | | |
| | | 200 mseg/div | TP1 Patilla 1 (Salida de RF) | Tornillo de ajuste tangencial | Patrón ocular más nítido posible | <ul style="list-style-type: none"> Observe la salida de la forma de onda de la patilla 1 de TP1 (salida de RF) en el osciloscopio y ajuste el tornillo de ajuste tangencial hasta lograr el patrón ocular más nítido posible. El punto en el que el tornillo de ajuste tendrá que quedar está aproximadamente en la mitad de los puntos en los que el patrón ocular se vuelve más borroso al girar dicho tornillo hacia la derecha y hacia la izquierda. Cuando toda la forma de onda sea clara, concentre o aguce las líneas finas que forman el diamante en el centro del patrón ocular (consulte la fotografía 10-8.). Ajuste hasta que las líneas finas de los cuatro lados del diamante queden nítidamente definidas y densa.  <p>Figura 10-12.</p> <p>Nota: Emplee una llave hexagonal para levantar algo el captor cuando realice este ajuste.</p> |



Parte que debe observar



Insatisfactorio

Ajuste óptimo

Insatisfactorio

Fotografía 10-6.



Fotografía 10-7.

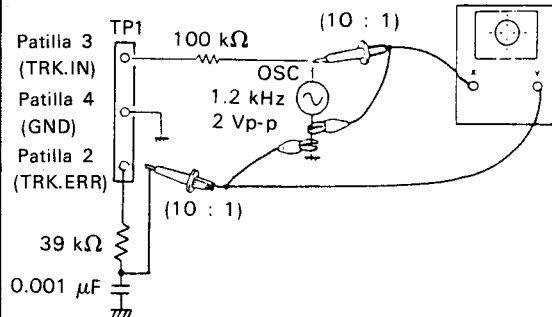


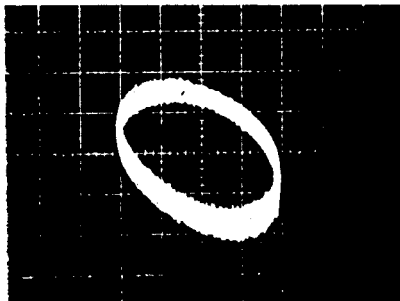
Fotografía 10-8.



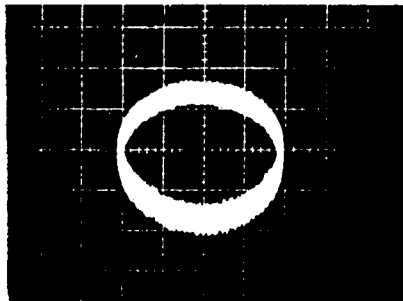
Fotografía 10-9.

| N. de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|--|---|---|-------------------|---------------------------|--|-------------------------|
| | V | H | | | | |
| 8 | Ajuste de ganancia de enfoque | | | | | |
| | CH1(X), CH2(Y) 20 mV/div 5 mV/div (Sonda: 10:1) | Eje x TP1 Patilla 5 (FCS. IN) Eje Y TP1 Patilla 6 (FCS. ERR) | VR3 (FCS. GAN) | Diferencia de fase de 90° | <ul style="list-style-type: none">• Con la alimentación del oscilador desconectada, conecte el osciloscopio y el oscilador como se muestra en la figura 10-13.• Ponga la unidad en el modo de prueba (consulte la página 65).• Presione secuencialmente las teclas TRACK FWD (▶), PLAY (▷) y PAUSE (⏏) para cerrar los servos de enfoque, eje y seguimiento.• Conecte la alimentación del oscilador y ajuste su salida a una señal de 1,2 kHz, 1 Vp-p. <p>Nota: Algunos osciladores descargan una tensión CC cuando se conecta su alimentación. Por lo tanto, se recomienda conectar el oscilador después de haber conectado su alimentación.</p> <ul style="list-style-type: none">• Ajuste VR3 FCS.GAN (ganancia de enfoque) de forma que la figura de Lissajous se convierta en un círculo horizontal en el osciloscopio (diferencia de fase de 90°). <div></div> <p>Figura 10-13.</p> | |
| <div><div></div><div>Ganancia sobrecompensada Fotografía 10-10.</div></div> <div><div></div><div>Ganancia óptima Fotografía 10-11.</div></div> <div><div></div><div>Ganancia subcompensada Fotografía 10-12.</div></div> | | | | | | |

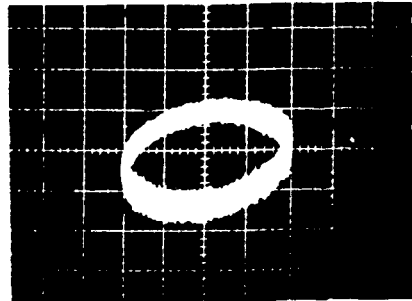
| N. de paso | Ajuste de osciloscopio | | Puntos de ajuste | Puntos de prueba | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|------------|--|---|------------------|---------------------------|---|---|
| | V | H | | | | |
| 9 | Ajuste de ganancia de seguimiento | | | | | |
| | CH1(X), CH2(Y) 50 mV/div, 5 mV/div (Sonda: 10:1) | Eje X TP1 Patilla 3 (TRK.IN) Eje Y TP1 Patilla 2 (TRK.OUT) | VR4 (TRK.GAN) | Diferencia de fase de 90° | <ul style="list-style-type: none">Con la alimentación del oscilador desconectada, conecte el osciloscopio y el oscilador como se muestra en la figura 10-14.Ponga la unidad en el modo de prueba (consulte la página 65).Presione secuencialmente las teclas TRACK FWD (→), PLAY (▷) y PAUSE (⏏) para cerrar los servos de enfoque, eje y seguimiento.Conecte la alimentación del oscilador y ajuste su salida a una señal de 1,2 kHz, 2 Vp-p. <p>Nota: Algunos osciladores descargan una tensión CC cuando se conecta su alimentación. Por lo tanto, se recomienda conectar el oscilador después de haber conectado su alimentación.</p> <ul style="list-style-type: none">Ajuste VR4 TRK.GAN (ganancia de seguimiento) de forma que la figura de Lissajous se convierte en un círculo horizontal en el osciloscopio (diferencia de fase de 90°). |  |



Ganancia sobrecompensada
Fotografía 10-13.



Ganancia óptima
Fotografía 10-14.



Ganancia subcompensada
Fotografía 10-15.

| N. ^o de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|-------------------------------|---|---|-------------------------|---------------------|---|--|
| | V | H | | | | |
| 10 | Ajuste de frecuencia de oscilación libre del oscilador controlado por tensión (VCO) | | | | | |
| | | | TP2 Patilla 2 | VR8 (VCO.ADJ) | 4.275 ±0,025 MHZ | <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Cortocircuite el cable de puente de ASY y GND con un destornillador de punta plana o herramienta similar (consulte la figura 10-15.).• Conecte un frecuencímetro capaz de medir frecuencias de 10 MHz y más a la patilla 2 de TP2.• Ajuste VR8 VCO.ADJ (ajuste de oscilación libre del VCO) para que la indicación del frecuencímetro sea de 4.275 ±0,025. |
| 11 | Comprobación del error de enfoque | | | | | |
| | | | TP1 Patilla 6 (FCS.ERR) | | | <ul style="list-style-type: none">• Ponga la unidad en el modo de prueba (consulte la página 65).• Conecte a masa FCS.IN (entrada de enfoque) de la patilla 5 de TP1.• Observe la salida de forma de onda de FCS.ERR (error de enfoque) de la patilla 6 de TP1 cuando se presione la tecla TRACK FWD (▶▶). |

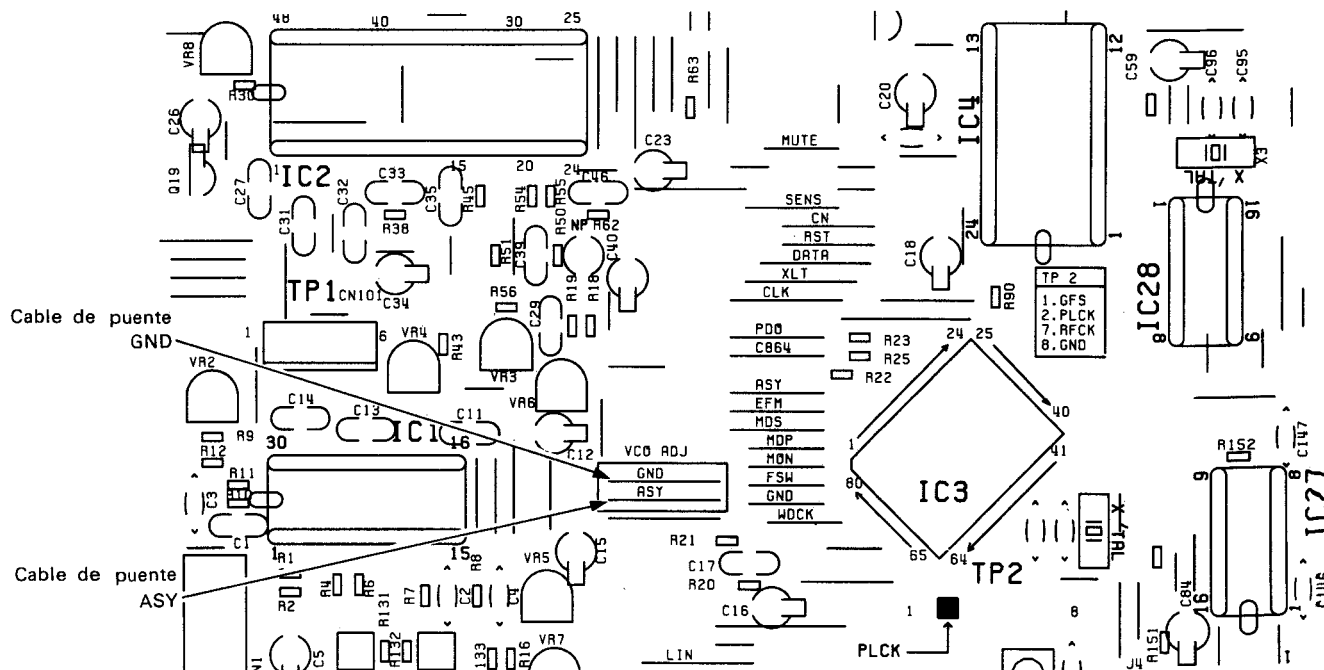
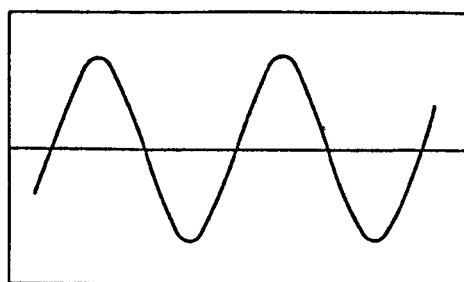


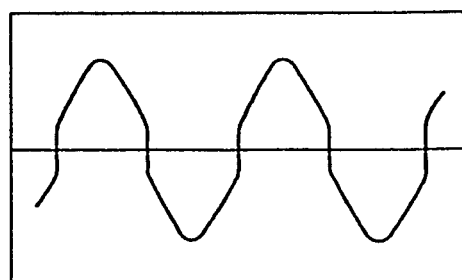
Figura 10-15. Posiciones de los cables de puente ASY y GND

| N. de paso | Ajuste de osciloscopio | | Puntos de prueba | Puntos de ajuste | Ítemes de comprobación/ especificaciones de ajuste | Procedimiento de ajuste |
|------------|------------------------|--------------|--|------------------|--|--|
| | V | H | | | | |
| 12 | Ajuste de MSB | | | | | |
| | 5 mV/div | 0,2 mseg/div | JA1 Terminal LINE OUT (Canal izquierdo) | VR10 | Onda sinusoidal | <ul style="list-style-type: none">• Ponga la unidad en el modo de reproducción normal.• Reproduzca la melodía n.º 20 (−60 dB, 1 kHz, canal izquierdo/derecho (YEDS-7). Conecte un osciloscopio en el canal izquierdo de los terminales LINE OUT y observe la forma de onda de la salida de audio.• Ajuste VR10 MSB.ADJ Rch (ajuste de MSB, canal derecho) de forma que la forma de onda del osciloscopio sea una onda sinusoidal.• Realice el mismo ajuste para el canal izquierdo (VR9). |
| | | | JA1 Terminal LINE OUT (Canal derecho) | VR9 | Onda sinusoidal | |

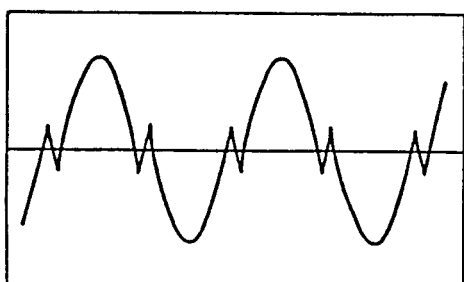
● Forma de onda de distorsión del eje de cruce cero



BIEN



MAL



MAL

11. IC DESCRIPTIONS

PD0029

| Pin No. | Symbol | Name | I/O | Function |
|---------|----------------------------|--------------|-----|---|
| 1 | XIN | XIN | I | Crystal oscillation circuit input or external input |
| 2 | XOUT | XOUT | O | Crystal oscillation circuit output |
| 3 | CKS | CLOCK SELECT | I | 16.9344 MHz when H 8.4672 MHz when L |
| 4 | CKOUT | CLOCK OUT | O | 16.9344 MHz clock output when CKS=H 8.4672 MHz clock output when CKS=L |
| 5 | LRCK | LR CLOCK | I | LR clock input |
| 6 | DATA | DATA | I | Serial data input (compliment of 2, MSB first) |
| 7 | BCLK | BIT CLOCK | I | Bit clock input for input data |
| 8 | VSS | | | Ground pin |
| 9 | LCOUT | LCLOCK OUT | O | L-ch when 2 DAC used Clock output for DAC |
| 10 | SHR | SHR | O | Sample hold pulse output for R-ch |
| 11 | SHL | SHL | O | Sample hold pulse output for L-ch |
| 12 | DOUT | DATA OUT | O | Serial data output (compliment of 2, MSB first) |
| 13 | WOUT | WORD CK OUT | O | Word clock output |
| 14 | LR $\overline{\text{OUT}}$ | LR CK OUT | O | LR select clock output |
| 15 | BOUT | BIT CK OUT | O | Bit clock output for DOUT |
| 16 | VDD | | | +5V, Power supply pin |

PD4152

| No. | Symbol | Name | I/O | Function | At Reset | Initial |
|-----|-------------------------|--------------------------|-----|--|----------|---------|
| 1 | S ₃ | SEG h | O | Segment output for FL drive | -26V | -26V |
| 2 | S ₂ | SEG g | O | Segment output for FL drive | -26V | -26V |
| 3 | S ₁ | SEG f | O | Segment output for FL drive | -26V | -26V |
| 4 | S ₀ | SEG e | O | Segment output for FL drive | -26V | -26V |
| 5 | P ₀₀ | $\overline{\text{TEST}}$ | I | Test mode selection input Test Normal | — | — |
| 6 | $\overline{\text{SCK}}$ | CLK | O | Serial clock | — | H |
| 7 | SO | DATA | O | LSI control data serial output | — | H |
| 8 | SI | SUBQ | I | Sub-code Q data serial input | — | — |
| 9 | INT ₀ | RMDT | I | Remote control data input | — | — |
| 10 | INT ₁ | SCOR | I | Sub-code sync S0 + S1 output Sync | — | — |
| 11 | P ₁₂ | GFS | I | Frame sync lock input NG OK | — | — |
| 12 | P ₁₃ | CENS | I | LSI operation state multi-mode input | — | — |
| 13 | P ₂₀ | KD0 | I | Key scan input | — | — |
| 14 | P ₂₁ | KD1 | I | Key scan input | — | — |
| 15 | P ₂₂ | KD2 | I | Key scan input | — | — |
| 16 | P ₂₃ | KD3 | I | Key scan input | — | — |
| 17 | P ₃₀ | Not used | O | NC (open) | — | L |
| 18 | P ₃₁ | MUTE | O | Muting output OFF ON | — | H |
| 19 | P ₃₂ | $\overline{\text{XLT}}$ | O | LSI control data latch pulse | — | H |
| 20 | P ₃₃ | DIRC | O | Direction reversal output for track jump | — | H |
| 21 | P ₆₀ | SYC1 | I | Input pin for deck syncro (pull-up when not used) | — | — |
| 22 | P ₆₁ | SYC2 | O | Output pin for deck syncro | — | L |
| 23 | P ₆₂ | LIN | O | Disk tray loading IN | — | L |
| 24 | P ₆₃ | LOUT | O | IN/OUT output Brake OUT | — | L |
| 25 | P ₄₀ | $\overline{\text{OPEN}}$ | I | Disk tray open completion SW input OPEN NOT | — | — |
| 26 | P ₄₁ | $\overline{\text{CLMP}}$ | I | Disk tray clamp completion SW input CLAMP NOT | — | — |
| 27 | P ₄₂ | $\overline{\text{INSD}}$ | I | Slider inside SW input INSIDE NOT | — | — |
| 28 | P ₄₃ | FOK | I | Focus OK input NG OK | — | — |
| 29 | PPO | $\overline{\text{LDON}}$ | O | Laser diode ON OFF output ON OFF | — | H |
| 30 | X ₁ | — | — | Connection pin for main system clock oscillation 4.19 MHz | — | — |
| 31 | X ₂ | — | — | | — | — |
| 32 | V _{SS} | — | — | GND | | |
| 33 | XT ₁ | — | — | GND | | |
| 34 | XT ₂ | — | — | NC | | |
| 35 | P ₅₀ | Not used | O | NC (open) | — | L |

| No. | Symbol | Name | I/O | Function | At Reset | Initial |
|-----|-------------------|-------|-----|---|----------|---------|
| 36 | P ₅₁ | ALAT | O | ATT level latch pulse output | — | H |
| 37 | P ₅₂ | ADAT | O | ATT level data | — | H |
| 38 | P ₅₃ | ACLK | O | ATT level clock | — | H |
| 39 | RESET | RESET | I | CPU reset input | — | — |
| 40 | T ₀ | DIG0 | O | Digit output for FL drive | -26V | |
| 41 | T ₁ | DIG1 | O | Digit output for FL drive | -26V | |
| 42 | T ₂ | DIG2 | O | Digit output for FL drive | -26V | |
| 43 | T ₃ | DIG3 | O | Digit output for FL drive | -26V | |
| 44 | T ₄ | DIG4 | O | Digit output for FL drive | -26V | |
| 45 | T ₅ | DIG5 | O | Digit output for FL drive | -26V | |
| 46 | T ₆ | DIG6 | O | Digit output for FL drive | -26V | |
| 47 | T ₇ | DIG7 | O | Digit output for FL drive | -26V | |
| 48 | T ₈ | DIG8 | O | Digit output for FL drive | -26V | |
| 49 | T ₉ | DIG9 | O | Digit output for FL drive | -26V | |
| 50 | PH ₃ | PASL | O | Pause LED output | — | L |
| 51 | PH ₂ | PLYL | O | Play LED output | — | L |
| 52 | PH ₁ | LIOL | O | Loading LED output | — | H |
| 53 | PH ₀ | DEMP | O | De-emphasis ON/OFF output | — | -5V |
| 54 | S ₁₁ | SEG.m | O | Segment output for FL drive | -26V | -26V |
| 55 | S ₁₀ | SEG.l | O | Segment output for FL drive | -26V | -26V |
| 56 | V _{LOAD} | — | — | FIP controller/driver pull-down resistor connection pin | -26V | |
| 57 | V _{PRE} | — | — | Power pin for FIP controller/driver pre-driver | -5V | |
| 58 | S ₉ | SEG.j | O | Segment output for FL drive | -26V | -26V |
| 59 | S ₈ | SEG.i | O | Segment output for FL drive | -26V | -26V |
| 60 | S ₇ | SEG.d | O | Segment output for FL drive | -26V | -26V |
| 61 | S ₆ | SEG.c | O | Segment output for FL drive | -26V | -26V |
| 62 | S ₅ | SEG.b | O | Segment output for FL drive | -26V | -26V |
| 63 | S ₄ | SEG.a | O | Segment output for FL drive | -26V | -26V |
| 64 | V _{DD} | — | — | +5V | | |

NOTE:

— : Hi — Imp

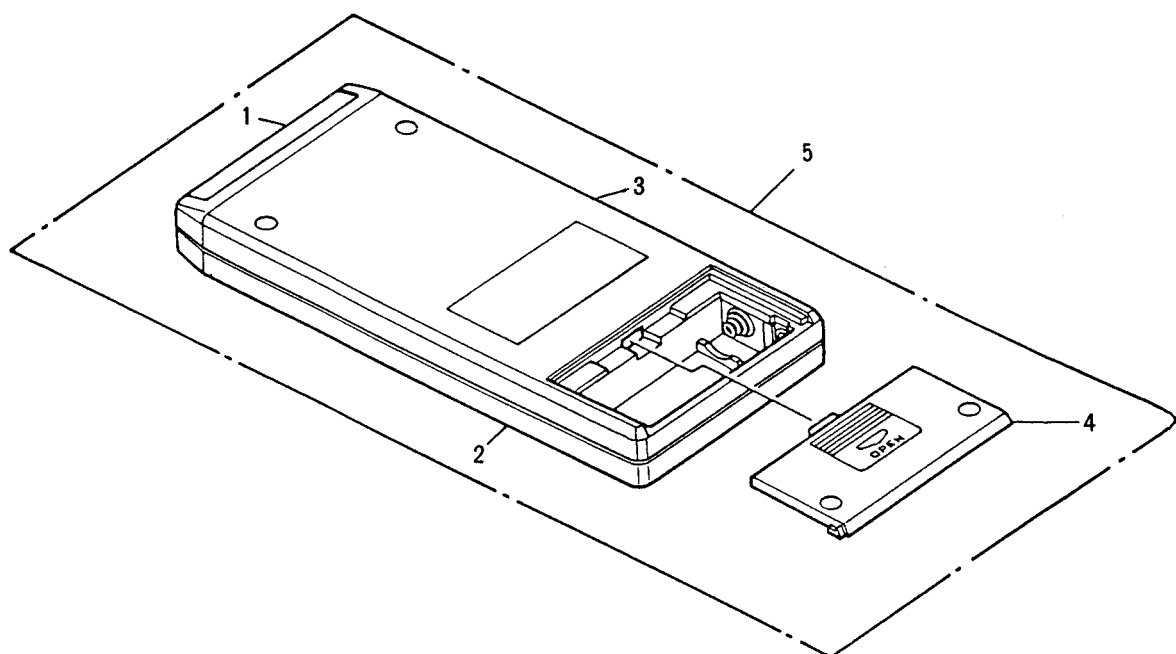
H: Hi-Level

L: Low-Level

12. REMOTE CONTROL UNIT

Parts list

| Mark | No. | Part No. | Description |
|------|-----|----------|---------------------|
| | 1 | PAM1071 | Filter |
| | 2 | PNW1151 | Case (T) |
| | 3 | PNW1152 | Case (B) |
| | 4 | PNW1153 | Cover |
| | 5 | PWW1023 | Remote control unit |



13. FOR HB, SD AND PD-6100-S/HEM TYPES

NOTES :

- Parts without part number cannot be supplied.
- The Δ mark found on some component parts indicates the importance of the safety factor of the part. Therefore, when replacing, be sure to use parts of identical designation.
- For your parts Stock Control, the fast moving items are indicated with the marks $\star\star$ and \star .
 $\star\star$ GENERALLY MOVES FASTER THAN \star .
- This classification shall be adjusted by each distributor because it depends on model number, temperature, humidity, etc.
- Parts marked by "O" are not always kept in stock. Their delivery time may be longer than usual or they may be unavailable.

The PD-6100/HB, SD and PD-6100-S/HEM types are the same as the PD-6100/HEM type with the exception of the following sections.

| Mark | Symbol & Description | Part No. | | | | Remarks |
|--------------------|--|----------------------|---------------------|---------------------|------------------------|---------|
| | | PD-6100/ HEM type | PD-6100/ HB type | PD-6100/ SD type | PD-6100-S/ HEM type | |
| Δ | AC power cord | PDG1003 | PDG1004 | PDG1013 | PDG1003 | |
| $\Delta \star$ | Power transformer | PTT1063 | PTT1063 | PTT1064 | PTT1063 | |
| $\Delta\star\star$ | Line voltage selector | | | PSB1002 | | |
| | Name plate B | PNW1358 | PNW1358 | PNW1358 | PNW1398 | |
| | Knob (PHONES LEVEL) | PAC1208 | PAC1208 | PAC1208 | PAC1271 | |
| | Button (TRACK) | PAC1251 | PAC1251 | PAC1251 | PAC1287 | |
| | Button B (POWER) | PAC1252 | PAC1252 | PAC1252 | PAC1289 | |
| | Button C (SELECT) | PAC1253 | PAC1253 | PAC1253 | PAC1286 | |
| | Button D (SELECT) | PAC1254 | PAC1254 | PAC1254 | PAC1295 | |
| | FL Filter | PAM1232 | PAM1232 | PAM1233 | | |
| | Button C (OPEN/CLOSE) | PAC1256 | PAC1256 | PAC1256 | PAC1288 | |
| | Play button B assembly | PAD1035 | PAD1035 | PAD1035 | PAD1037 | |
| | Function panel C | PNW1357 | PNW1357 | PNW1357 | PNW1380 | |
| | Bonnet | PYY1062 | PYY1062 | PYY1062 | PYY1068 | |
| | GND plate | | | | PBK1044 | |
| | Packing case | RHG1198 | RHG1198 | RHG1198 | RHG1200 | |
| | Operating instruction (English) | | PRB1052 | PRB1052 | | |
| | Operating instruction (Spanish) | | | PRC1009 | | |
| | Operating instruction (English, German, French, Italian) | PRE1052 | | | PRE1052 | |
| | Operating instruction (Spanish, Swedish, Dutch, Portuguese) | PRF1007 | | | PRF1007 | |
| | Lead wire unit | PDF1035 | | PDF1041 | | |